CODE IGS reference products including Galileo

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Contents

- Evolution of CODE's MGEX (COM) solution
- Dedicated model changes
- Galileo orbit and clock performance in the COM solution
- IGS perspective
- First experience with Galileo in (Ultra-)Rapid products
- Summary



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Evolution of the COM solution

- Orbit modelling:
 - Eclipse attitude laws for GPS, GLONASS, Galileo (Summer 2017)
 - Earth albedo and transmit antenna thrust applied for GPS, GLONASS, Galileo, QZSS (since Summer 2017)
 - ⇒ Prange et al. (presentation at 6th Galileo/GNSS Colloquium 2017), Dach et al. (CODE: IGS Technical Report 2017, doi 10.7892/boris.116377)
 - Correct consideration of orbit normal (ON) attitude mode for QZS-1 and BDS2 (since Summer 2018)
 - Use of ECOM-TB SRP model for satellites with ON attitude (since Summer 2018)

⇒ Prange et al. (doi 10.1016/j.asr.2019.07.031)

 Empirical thermal radiation model for Galileo satellites (since Summer 2019)

⇒ Sidorov et al. (poster at 7th Galileo/GNSS Colloquium 2019; paper doi 10.1016/j.asr.2020.05.028)



Evolution of the COM solution

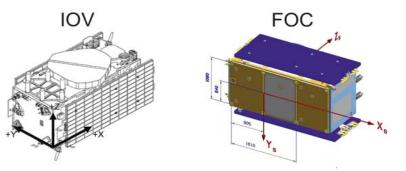
- Observation biases:
 - Observable-specific code biases (OCB) (Summer 2017)
 - ⇒ Villiger et. al. (2019, doi 10.1007/s00190-019-01262-w)
 - Observable-specific phase biases (OPB) (Summer 2018)
 - ⇒ Schaer et. al. (presentation at IGS Workshop 2018; paper in preparation)
 - Phase ambiguity resolution:
 - DD orbit solution: GPS, Galileo, QZSS, BDS2 (Summer 2017)
 - Ambiguity-fixed clocks: GPS, Galileo (WL+NL), QZSS, BDS2 (WL only) (Summer 2018)
 - ⇒ Dach et al. (CODE: IGS Technical Report 2018; doi
 - 10.7892/boris.130408); paper by Schaer et. al. under preparation
- Antenna calibrations:
 - Satellite antenna phase center offsets (PCO) of Galileo and QZSS published by system provider (values are included in IGS-MGEX-ANTEX)
 Ground antenna calibrations considering all GNSS available since 2019
 Switch to new antenna calibrations to be coordinated with IGS REPRO3
 see diverse presentations and poster by Villiger et. al. (2019), paper under review



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Galileo thermal radiation model

 Galileo spacecraft have a large AMR and are equipped with thermal radiators (known from the publicly available Galileo satellite metadata - thanks to GSA)



- Thermal radiators produce non-negligible forces (particularly important during eclipse seasons)
- Neglecting thermal effects may produce modelling artifacts (visible in MGEX products; magnitude depends on the employed orbital arc length)
- The ECOM2 SRP model was modified to account for these effects leading to improvements in satellite orbits and clock corrections during eclipse seasons.
- Sidorov et al. (2020): Adopting the Empirical CODE Orbit Model to Galileo satellites. doi 10.1016/j.asr.2020.05.028

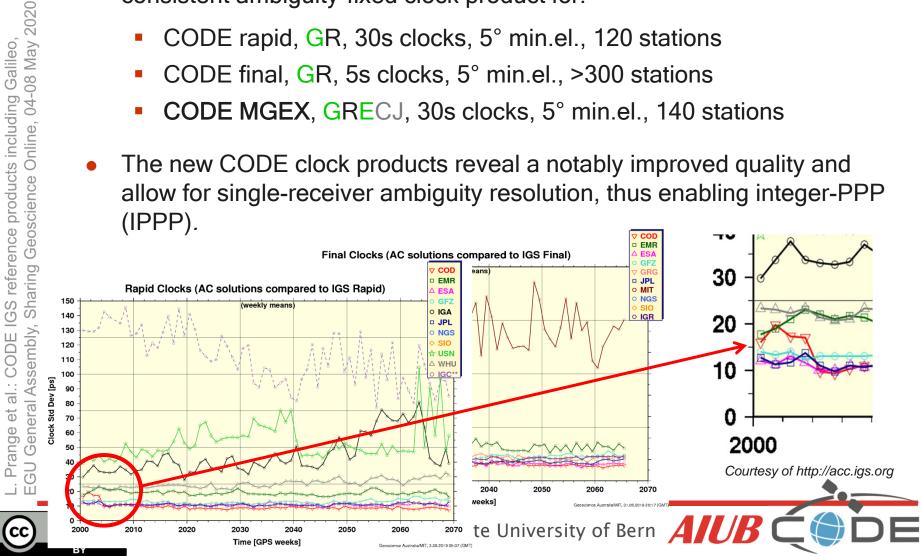
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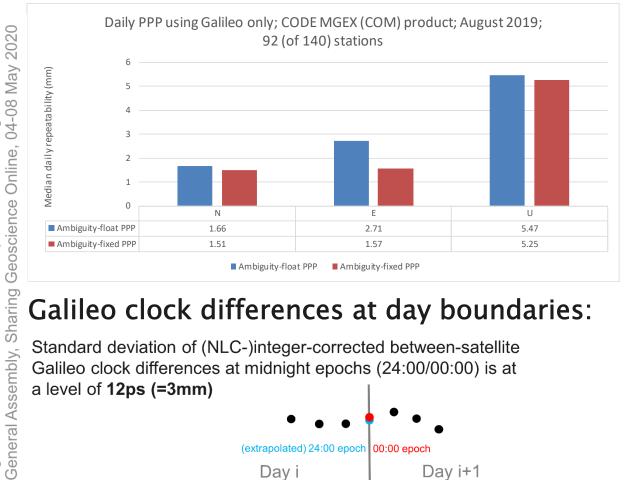
Ambiguity-fixed clock and phase bias products

- June 2018: signal-specific phase bias (OPB) product (internal) and a fully consistent ambiguity-fixed clock product for:
 - CODE rapid, GR, 30s clocks, 5° min.el., 120 stations
 - CODE final, GR, 5s clocks, 5° min.el., >300 stations
 - CODE MGEX, GRECJ, 30s clocks, 5° min.el., 140 stations
- The new CODE clock products reveal a notably improved quality and allow for single-receiver ambiguity resolution, thus enabling integer-PPP (IPPP).



Ambiguity-fixed clock and phase bias products

Daily PPP vs. daily IPPP using Galileo only:



References:

Schaer et al. (2018): Presentation at IGS-WS 2018.

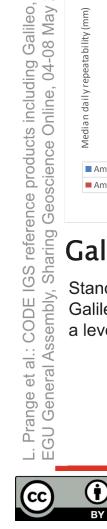
Schaer et al. (2020): The CODE ambiguity-fixed clock and phase bias analysis products and their properties and performance. Manuscript in preparation.

Galileo clock differences at day boundaries:

(extrapolated) 24:00 epoch 00:00 epoch

Standard deviation of (NLC-)integer-corrected between-satellite Galileo clock differences at midnight epochs (24:00/00:00) is at a level of 12ps (=3mm)

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Time

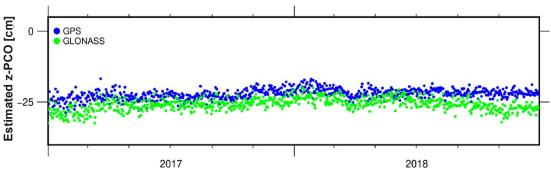
Day i+1

Antenna calibrations

Available receiver and satellite antenna patterns:

System	Rece	eiver	Satellite	
× 2020	IGS 14	REPRO3		
GPS	L1 / L2	L1 / L2	Estimated	→ Calibrated receiver and satellite antenna patterns
GLONASS	L1 / L2	L1 / L2	Estimated	allow to estimate a
Galileo	L1 / L2	L1 / L5	Calibrated	GNSS scale
Beidou	L1 / L2	L1 / L7	Estimated	
QZSS	L1 / L2	L1 / L2	Calibrated	
			Gali	ileo PCO constrained
compatible. ➤ Possible sc	S and Galileo P) are not olution: adaptation d GLONASS		VASS	
z-PCOs to Galileo by intro- ducing a system wise affect				
ducing a system-wise offset \Rightarrow Villiger et al. (2020): GNSS scale determination using calibrated receiver and Galileo satellite antenna				

- Estimated GPS and Galileo PCO (z-component) are not
- General Assembly, Sharing compatible. \geq
 - Possible solution: adaptation of GPS and GLONASS z-PCOs to Galileo by introducing a system-wise offset
 - Study related to IGS REPRO3

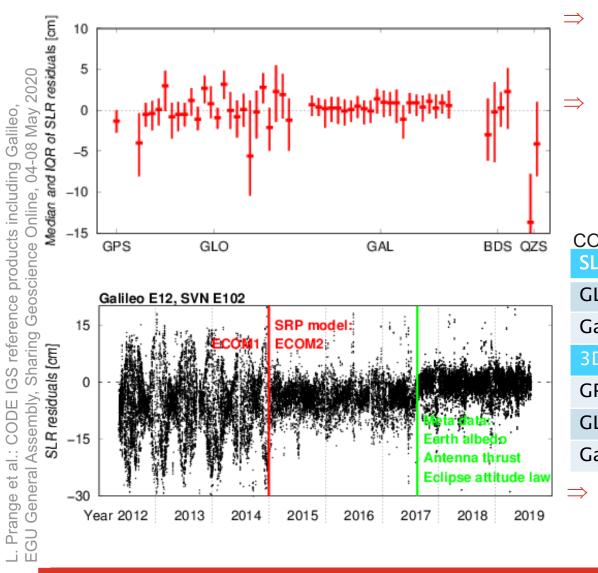


 \Rightarrow Villiger et al. (2020): GNSS scale determination using calibrated receiver and Galileo satellite antenna patterns. Paper under review



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COM orbit validation: SLR residuals



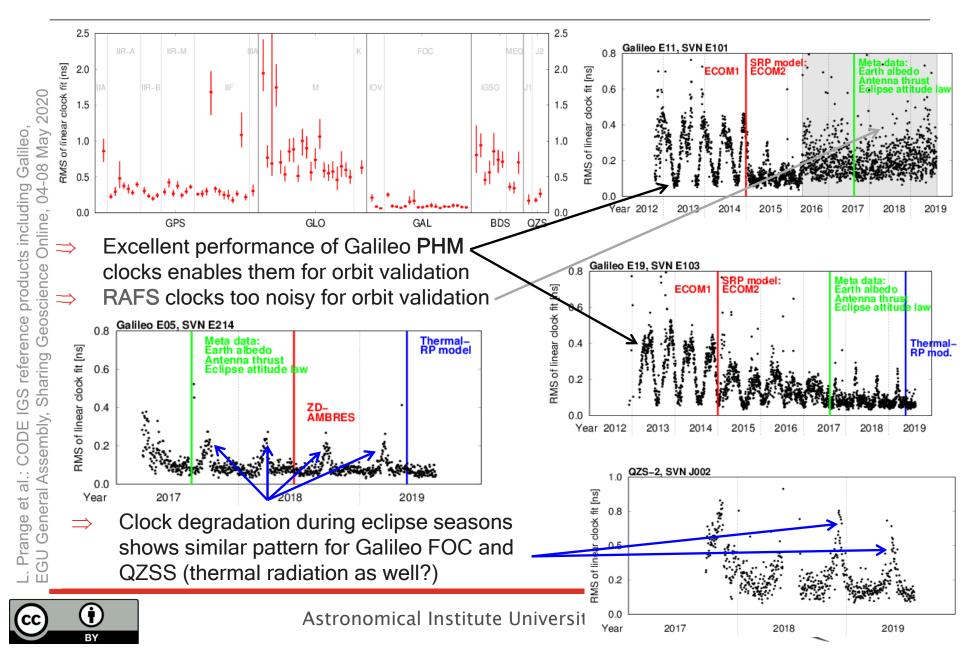
Galileo POD improved within recent years - thanks to model changes and better tracking Disclosure of meta data contributes to orbit improvements (e.g., reduction of SLR offset)

COM orbit validation DOYs 1-320/2019:				
SLR	Median [cm]	IQR [cm]		
GLONASS	-0.1	4.6		
Galileo	0.2	3.6		
3D orbit misclosures				
GPS	0.8	0.6		
GLONASS	1.2	1.0		
Galileo	1.4	1.0		

 Nowadays: Galileo orbit quality is not worse than that of GLONASS



COM clock validation: daily linear fit



Operational IGS processing chains:

Demand for additional systems is higher for (near-)real time applications (# of satellites in view and observation geometry matters) \rightarrow (Ultra-)Rapid

Product line	Applications	Latency Req.	Accuracy Req.	Systems	
Ultra -Rapid (including orbit predictions)	Real time (predictions), near real time	Very short (few hours)	Low	GR	
Rapid	Reference	Short (1 day)	Medium	GR	
Final	High accuracy reference (including scale); contribution to ITRF	Long (2 weeks)	High	GR	
		Color code: requi	rement or factor is	System:	
		Very important		GPS:	G
		Moderately impo	rtant	GLONASS:	R
		Less important		Galileo:	Е
				BeiDou:	С
				QZSS:	J
				SBAS:	S
				IRNSS:	I



IGS processing chains (recent years):

 MGEX: testing of new systems (other than GPS and GLONASS) and RINEX3 raw observation data format; preparation of software, processing chains, modelling

Product line	Applications	Latency Req.	Accuracy Req.	Systems
MGEX	Experimental: new GNSS and RNSS; RINEX3 data	Diverse	Diverse	GRECJ
Ultra -Rapid (including orbit predictions)	Real time (predictions), near real time	Very short (few hours)	Low	GR
Rapid	Reference	Short (1 day)	Medium	GR
Final	High accuracy reference (including scale); contribution to ITRF	Long (2 weeks)	High	GR

 Demand for new GNSS is less urgent in Final products (scale consistency and avoiding contamination of EOP and TRF parameters by orbit modelling artifacts matter more)



• IGS processing chains (around 2020):

 RINEX3 is gradually replacing RINEX2 data in all processing chains according to the IGS RINEX 3 Transition Plan

Product line	Applications	Latency Req.	Accuracy Req.	Systems
MGEX	Experimental: new GNSS and RNSS; RINEX3 data	Diverse	Diverse	GRECJ
Ultra -Rapid (including orbit predictions)	Real time (pred ctions), near real tinge	Very short (few hours)	Low	GRE
Rapid	Reference 🗸	Short (1 day)	Medium	GRE
Final	High accuracy reference (including scale)	Long (2 weeks)	High	GR
REPRO3	Preparation of new ITR including definition of GNSS scale	On demand	Very high	GRE

 As first AC, CODE started to include Galileo in Ultra- and Rapid products in September 2019 (accepting scale inconsistencies between Galileo and GPS/GLONASS/ITRF2014) (see Dach (2019): IGSMAIL-7832)



• IGS processing chains (near future, 2021?):

 REPRO3: possible definition of a GNSS scale based on Galileo satellite and new ground antenna calibrations, re-estimation of GPS and GLONASS PCO and ITRFcontribution; several ACs (incl. CODE) thus include Galileo in their contribution

Product line	Applications	Latency Req.	Accuracy Req.	Systems
MGEX	Experimental: new GNSS and RNSS	Diverse	Diverse	GRECJSI
Ultra -Rapid (including orbit predictions)	Real time (predictions), near real time	Very short (few hours)	Low	GRE
Rapid	Reference	Short (1 day)	Medium	GRE
Final	Hign accuracy reference (including scale); contribution to new ITRF	Long (2 weeks)	High	GR
REPRO3	Preparation of new ITRF including definition of GNSS scale	On demand	Very high	GRE

New ITRF (with new scale) to be introduced in all IGS routines



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- IGS processing chains (future, 2021+):
 - With the new ITRF Galileo can potentially contribute to Final products without causing a scale inconsistency

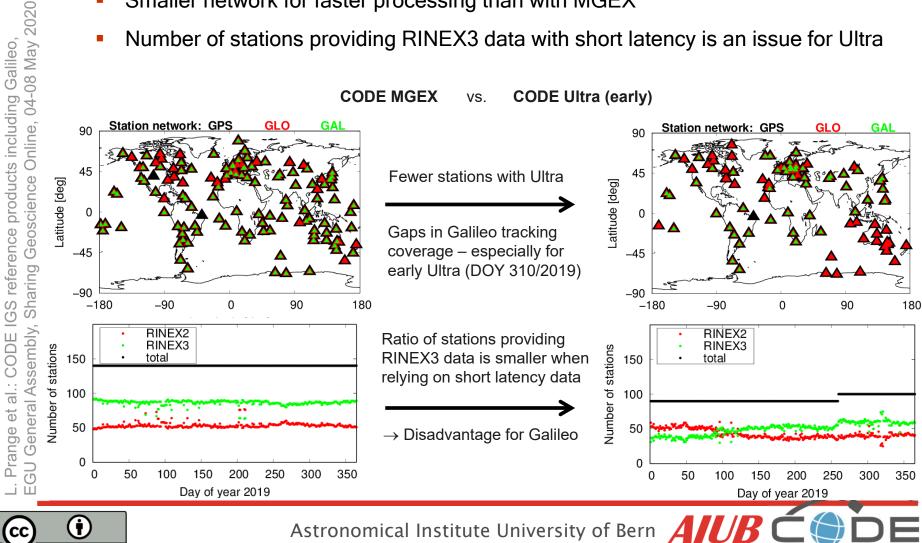
Product line	Applications	Latency Req.	Accuracy Req.	Systems
MGEX	Experimental: new GNSS and RNSS	Diverse	Diverse	GRE CJSI
Ultra -Rapid (including orbit predictions)	Real time (predictions), near real time	Very short (few hours)	Low	GRE
Rapid	Reference	Short (1 day)	Medium	GRE
Final	High accuracy reference (including new scale); contribution to next ITRF	Long (2 weeks)	High	GRE

 MGEX: could address open technical (e.g., GEO POD, improving orbit models) and scientific questions (e.g., how can GEO and IGSO satellites contribute to TRF parameters and other reference products?)



Galileo in CODE (Ultra-)Rapid - first experiences

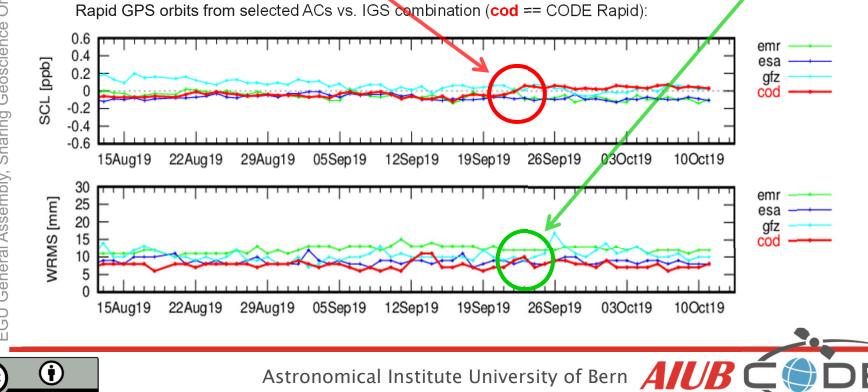
- Galileo included in CODE (Ultra-)Rapid since September 2019:
 - Smaller network for faster processing than with MGEX
 - Number of stations providing RINEX3 data with short latency is an issue for Ultra



CODE MGEX CODE Ultra (early) VS.

Galileo in CODE (Ultra-)Rapid - first experiences

- IGS Rapid combination validates impact of Galileo on GPS orbits:
 - No issues concerning data processing or reliability
 - Jump in GPS scale (as expected from Villiger and Rebischung (2019))
 - No degradation of GPS orbits (Helmert transformation parameters and WRMS of comparison with combined IGS Rapid orbit do not change)



Summary

- Galileo data analysis has significantly improved in recent years (e.g., ambiguity-fixed clocks)
 - Galileo nowadays is a fully established GNSS constellation, which is sufficiently supported by the IGS infrastructure, and is mature enough to contribute to legacy IGS products
 - Availability of metadata lets Galileo appear even appropriate to determine a GNSS scale in the frame of the IGS REPRO3 campaign
 - GNSS community expressed interest in Galileo short latency products
- CODE AC started to include Galileo in Ultra-Rapid, Rapid and in its REPRO3 effort
- Inclusion of Galileo in CODE's (Ultra-)Rapid analysis has so far not indicated negative side-effects - apart from a scale difference w.r.t. GPS and GLONASS, which was expected (and is likely to disappear when a new ITRF will be introduced)



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Thank you for your attention!

Note: For more information on this topic we refer to Prange et al. (2020): Overview of CODE's MGEX solution with the focus on Galileo. ASR. doi: 10.1016/j.asr.2020.04.038



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- Villiger and Rebischung (2019). Possible Contribution of GNSS to the Definition of the ITRF2020 Scale Based on the Galileo Satellite Phase Center Offsets. Presentation at Unified Analysis Workshop, Paris, France.
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Bonus: CODE MGEX (COM) orbit solution

GNSS considered:	GPS + GLONASS + Galileo + BDS2 (MEO+IGSO) + QZSS (>90 SV)
Serocessing mode:	Post-processing (≈2 weeks latency)
Timespan covered:	GPS-weeks 1689 - today
Solumber of stations:	140 (GPS), 130 (GLONASS),
, 04-	100 (Galileo); 80 (BDS2); 40 - 50 (QZSS)
Processing scheme:	Double-difference network processing
Local Contracts	(observable: phase double differences; ambiguity-fixed)
Signal frequencies:	L1+ L2 (GPS + GLO+ QZSS);
Jeos Jeos	E1 (L1) + E5a (L5) Galileo; B1 (L2) + B2 (L7) BDS2
Orbit characteristic:	3-day long arcs; SRP: ECOM2, ECOM-TB (during ON)
້ອ ເອົ້ອ Reference frame:	IGS14
$\frac{1}{2}$ $\stackrel{\circ}{\leq}$ IERS conventions:	IERS2010
្លី ទ្លូ៍Product list:	Daily orbits (SP3; 300s) and ERPs
Distribution:	ftp://cddis.gsfc.nasa.gov/gnss/products/mgex/ and
Senel Senel	ftp://ftp.aiub.unibe.ch/CODE_MGEX/
Designation:	COD0MGXFIN_YYYDDDgz



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Bonus: CODE MGEX (COM) clock solution

GNSS considered:	GPS + GLONASS + Galileo + BDS2 + QZSS (>90 SV)
Processing mode:	Post-processing (≈2 weeks latency)
Timespan covered:	GPS-weeks 1710 - today
Number of stations:	140 (GPS), 130 (GLO), 100 (Galileo); 50 (BDS2); 40 (QZSS)
Processing scheme:	Zero-difference processing
, ine,	(code+phase undifferenced; ambiguity-fixed for G,E,C,J)
Signal frequencies:	L1+ L2 (GPS + GLO+ QZSS);
ence	E1 (L1) + E5a (L5) Galileo; B1 (L2) + B2 (L7) BDS2
A priori information:	Orbits, ERPs, coordinates, and troposphere from
	CODE MGEX orbit solution introduced as known
Reference frame:	IGS14
JERS conventions:	IERS2010
Product list:	Epoch-wise (30s) clock corrections for satellites and stations
Asse	in daily CLK-RINEX files; daily observable-specific (OSB)
lera	code biases for satellites and stations in BIAS-SINEX-format
Ger	ftp://cddis.gsfc.nasa.gov/gnss/products/mgex/ and
Distribution:	ftp://ftp.aiub.unibe.ch/CODE_MGEX/



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