



Erratum

Erratum to 'In vitro scan accuracy and time efficiency in various implant-supported fixed partial denture situations' [Journal of Dentistry 127C (2022) 104358]

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The publisher regrets that information was missing within Tables 1, 2 and 3 of this article.

The correct tables can be seen below:

This has now been corrected within the article.

The publisher would like to apologise for any inconvenience caused.

DOI of original article: <https://doi.org/10.1016/j.jdent.2022.104358>.

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Table 1

Median and interquartile range (IQR: 25% - 75%) values for 3D point deviations (μm).

Model	Scanner	Trueness (IQR)	Precision (IQR)
Model 1	IDW	172.16 ^A (161.33-178.44)	55.14 ^a (47.59-60.48)
	DDW-P	155.94 ^B (142.4-158.88)	35.21 ^b (29.14-43.87)
	DDW-T	163.48 ^A (159.87-174.32)	57.21 ^a (46.71-86.37)
Model 2	IDW	162.78 ^A (133.79-221.33)	100.89 ^a (80.85-124.34)
	DDW-P	127.03 ^B (108.99-141.07)	47.79 ^c (33.13-59.41)
	DDW-T	111.66 ^B (107.23-144.06)	69.32 ^b (50.38-79.28)
Model 3	IDW	43.36 ^A (31.06-47.66)	26.84 ^a (22.39-30.89)
	DDW-P	13.66 ^B (12.15-18.75)	9.18 ^c (6.85-31.33)
	DDW-T	32.05 ^A (28.35-34.34)	21.79 ^b (13.9-31.36)

IDW: Indirect digital workflow; DDW-P: Direct digital workflow by using Primescan; DDW-T: Direct digital workflow by using Trios 3.

*Different superscript letters indicate significant differences among impression techniques within each model (Uppercase letters for trueness, lowercase letters for precision) ($P<.05$)

Table 2

Median and interquartile range (IQR: 25% - 75%) values for interimplant distance deviations (μm).

Model	Scanner	Trueness (IQR)	Precision (IQR)
Model 1	IDW	14.50 ^A (5.86-36.41)	17.88 ^a (5.6-45.86)
	DDW-P	20.15 ^A (8-39.28)	21.06 ^a (10.45-45.85)
	DDW-T	11.50 ^A (4.14-34.44)	15.08 ^a (6.45-35.98)
Model 2	IDW	33.7 ^A (16.02-36.1)	18.99 ^a (5.2-34)
	DDW-P	20.58 ^A (1.86-36.17)	29.34 ^a (1.6-34.62)
	DDW-T	21.84 ^A (5.34-36.4)	28.30 ^a (2.54-31.68)
Model 3	IDW	6.92 ^A (5.24-11.5)	5.47 ^a (3-9.69)
	DDW-P	2.04 ^B (1.07-3.32)	1.54 ^c (0.8-2.39)
	DDW-T	3.86 ^A (2.98-6.24)	3 ^b (1.11-6.32)

IDW: Indirect digital workflow; DDW-P: Direct digital workflow by using Primescan; DDW-T: Direct digital workflow by using Trios 3.

*Different superscript letters indicate significant differences among impression techniques within each model (Uppercase letters for trueness, lowercase letters for precision) ($P<.05$)

Table 3

Median and interquartile range (IQR: 25% - 75%) values for angular deviations.

Model	Scanner	Mesiodistal Direction		Buccopalatal Direction	
		Trueness (IQR)	Precision (IQR)	Trueness (IQR)	Precision (IQR)
Model 1	IDW	0.57 ^A (0.42-0.63)	0.19 ^a (0.1-0.38)	0.24 ^A (0.18-0.36)	0.14 ^a (0.06-0.24)
	DDW-P	0.23 ^B (0.11-0.34)	0.21 ^a (0.11-0.67)	0.33 ^A (0.28-0.4)	0.12 ^a (0.06-0.23)
	DDW-T	0.21 ^B (0.13-0.34)	0.16 ^a (0.07-0.71)	0.21 ^A (0.12-0.29)	0.16 ^a (0.1-0.33)
Model 2	IDW	1.26 ^A (0.56-1.99)	0.98 ^a (0.47-1.69)	0.68 ^A (0.62-0.91)	0.36 ^a (0.14-0.54)
	DDW-P	0.58 ^A (0.36-0.8)	0.37 ^b (0.18-0.68)	0.11 ^B (0.06-0.52)	0.40 ^a (0.06-0.49)
	DDW-T	0.37 ^A (0.18-0.96)	0.44 ^b (0.16-1.03)	0.21 ^{AB} (0.11-0.58)	0.38 ^a (0.09-0.8)
Model 3	IDW	0.34 ^A (0.25-0.45)	0.14 ^a (0.07-0.26)	0.18 ^A (0.13-0.29)	0.12 ^a (0.06-0.17)
	DDW-P	0.06 ^B (0.04-0.09)	0.04 ^c (0.02-0.06)	0.04 ^B (0.03-0.06)	0.03 ^c (0.01-0.04)
	DDW-T	0.08 ^B (0.07-0.16)	0.06 ^b (0.03-0.11)	0.06 ^B (0.04-0.10)	0.04 ^b (0.01-0.12)

IDW: Indirect digital workflow; DDW-P: Direct digital workflow by using Primescan; DDW-T: Direct digital workflow by using Trios 3.

*Different superscript letters indicate significant differences among impression techniques within each model and direction (Uppercase letters for trueness, lowercase letters for precision) ($P<.05$)