

1 **Title:** Dielectric Elastomer Actuator-Based Valveless Pump as Fontan Failure Assist Device:  
2 Introduction and Preliminary Study

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## 31 **Abstract:**

### 32 Objective

33 Fontan failure refers to a condition in which the Fontan circulation, a surgical procedure used  
34 to treat certain congenital heart defects, becomes insufficient, leading to compromised  
35 cardiac function and potential complications. This *in-vitro* study therefore investigates the  
36 feasibility of bladeless impedance-driven cavopulmonary assist device *via* dielectric elastomer  
37 actuator (DEA) as a means to address Fontan failure.

### 38 Methods

39 A cavopulmonary assist device, constructed using DEA technologies and employing the  
40 impedance pump concept, is subjected to *in-vitro* testing within a closed-loop setup. This  
41 study aims to assess the device's functionality and performance under controlled conditions,  
42 providing valuable insights into its potential application as a cavopulmonary assistive  
43 technology.

### 44 Results

45 The DEA-based pump, measuring 50mm in length and 30mm in diameter, is capable of  
46 achieving substantial flow rates within a closed-loop setup, reaching up to 1.20 L/min at an  
47 activation frequency of 4 Hz. It also provides a broad range of working internal pressures (less  
48 than 10 mmHg to more than 20 mmHg). Lastly, the properties of the flow (direction,  
49 magnitude, etc.) can be controlled by adjusting the input signal parameters (frequency,  
50 amplitude, etc.).

### 51 Conclusions

52 In summary, the results suggests that the valveless impedance-driven pump utilizing DEA  
53 technology is promising in the context of cavopulmonary assist devices. Further research and  
54 development in this area may lead to innovative and potentially more effective solutions for  
55 assisting the right heart, ultimately benefiting patients with heart-related health issues  
56 overall, with a particular focus on those experiencing Fontan failure.

57 **Keywords:** Fontan failure, cavopulmonary assist device, congenital heart defect, valveless  
58 pumping

### 59 **Abbreviations:**

CHD	Congenital heart defect
DEA	Dielectric elastomer actuator
EAP	Electroactive polymer
PET	Polyethylene terephthalate
PMMA	poly(methyl methacrylate)

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61

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## 63 Introduction:

64 The Fontan procedure (1,2), introduced over fifty years ago, represents a landmark surgical  
65 intervention designed to address the unique challenges of single ventricle congenital heart  
66 defects (CHDs). These complex congenital anomalies result in the presence of a single  
67 pumping ventricle, necessitating intricate surgical solutions to ensure adequate systemic  
68 circulation. The Fontan procedure, a staged surgical approach, redirects venous blood directly  
69 to the pulmonary arteries, bypassing the missing ventricle. Although this procedure has  
70 undoubtedly improved the prognosis for people with single ventricle anatomy, long-term  
71 results are far from ideal, with failure of the Fontan procedure becoming a substantial cause  
72 for concern.

73 Fontan failure refers to the progressive decline in cardiac function and exercise tolerance that  
74 affects a substantial proportion of people who have undergone the Fontan procedure. This  
75 can lead to various complications, such as arrhythmias (3), thromboembolism (4), liver  
76 dysfunction (5), and plastic bronchitis (6), which substantially impact these patients' quality of  
77 life and overall survival. Understanding the underlying mechanisms of Fontan failure requires  
78 a comprehensive exploration of the complex hemodynamic alterations (7) and physiological  
79 adaptations accompanying single ventricle circulation (8). A promising solution is to  
80 compensate for the absent right ventricular function by utilizing a cavopulmonary assist device  
81 made of soft robotic technology.

82 Inspired by the innate intelligence of living organisms, soft robotics has made substantial  
83 advances in recent decades. By merging traditional robotics with smart soft materials, this  
84 field has attracted the attention of researchers and engineers alike. The dielectric elastomer  
85 actuator (DEA) (9), often referred to as artificial muscle (10,11), is an example of such a  
86 material. Belonging to the electroactive polymers (EAPs) class, DEAs share similarities with  
87 natural muscles and exhibit qualities such as softness, lightness, large strains (12), high energy  
88 density (13), dynamic responsiveness (14), and even self-sensing capabilities (15). These  
89 attributes make them prime candidates for soft robotics applications, particularly for  
90 specialized uses in biomedicine (16,17).

91 Another promising system within the realm of biomedical applications, boasting unique  
92 capabilities, is the impedance pump (18). It offers a simple method of generating or amplifying  
93 flow without the need for valves or impellers (19,20). The concept can operate on both macro  
94 (21) and micro (22) scales and is achieved using a straightforward concept: a flexible tube  
95 filled with fluid, compressed off-center from its ends. This action generates waves propagating  
96 along the tube, reflecting at its ends, and producing a unidirectional net flow. The  
97 characteristics of this flow, including its direction and magnitude, are highly related to  
98 compression parameters such as frequency, duty cycle, and position.

99 This study investigates the feasibility of an innovative valveless impedance-driven pumping  
100 device based on a fully integrated DEA actuation, emphasizing its application as a  
101 cavopulmonary assist device (Fontan failure patients). However, the main target application  
102 for such a device is Fontan failure, where the pre-existing passive conduit of the Fontan  
103 procedure could be replaced by an active conduit (DEA pump), offering a potential long-term

104 solution to mitigate the complications associated with the Fontan failure (see **Figure 1a**). The  
105 pump is made of an active DEA tube interconnected with a passive tube via a poly(methyl  
106 methacrylate) (PMMA) decoupling link.

107 The literature presents few examples of cavopulmonary assist devices, with examples falling  
108 into two categories. Firstly, short and medium-term devices utilize percutaneous axial-flow  
109 systems to enhance blood flow from the inferior vena cava (23,24) or provide combined  
110 superior and inferior vena cava support (25). Secondly, long-term devices differ based on  
111 outlet configuration, featuring double-outlet designs positioned between the pulmonary  
112 arteries (26,27) or single-outlet concepts implantable anterior to the total cavopulmonary  
113 connection (28). Despite the demonstrated merit in these approaches, it is noteworthy that a  
114 majority of them necessitate more intricate surgical interventions and modifications to the  
115 Fontan procedure. In contrast, our design relies on DEA, eliminating the need for further  
116 surgical alterations in Fontan procedures. This key distinction underscores the potential  
117 advantage of our device, offering a streamlined solution for circulatory support without  
118 imposing additional surgical complexities. Furthermore, traditional pumping configurations  
119 relying on valves, AC/DC motors, and intricate components, this design presents several  
120 advantages: it operates without valves, thereby minimizing the risk of flow disruption or  
121 hemolysis; it displays softness, which reduces the potential for damage due to impacts; its  
122 lightweight construction weighs less than 25g in total; It exhibits high energy efficiency,  
123 requiring minimal power consumption (258 mW for 5kV activation); and it features a  
124 monolithic structure (DEAs capable of enduring over 400 million cycles (14)). Moreover, the  
125 inherent pulsatile nature of this system holds substantial implications within the realm of  
126 biomedical applications (29).

## 127 **Materials and Methods:**

128 Ethical statement: None.

129 Working principle of DEA and DEA pump:

130 DEAs, typically composed of compliant electrodes sandwiching a dielectric film, function as a  
131 capacitive system. When an electric field is introduced, it triggers a mechanical force on the  
132 hyperelastic material due to the charges on the electrodes. This force compresses the film,  
133 reducing its thickness while expanding its surface area. Consequently, the conversion of an  
134 electric field into a mechanical deformation occurs. The extent of voltage application and  
135 resulting displacements hinges on the film's thickness.

136 The concept of the valveless pumping system based on DEAs is presented in **Figure 1b**. This  
137 design consists of an active DEA combined with a passive tube linked through a rigid  
138 decoupling PMMA link. Here, the tubular DEA ensures the off-center compression (or, in this  
139 case, decompression), thus achieving wave generation. Before activation (applying electrical  
140 voltage), the tubular DEA is subjected to internal pressure. Once activated, the mechanical  
141 properties of the DEA will change (drop), causing it to inflate like a balloon under internal  
142 pressure and leading to the required waves generation. On the other hand, the passive tube  
143 acts as a soft tube, while the rigid link ensures a decoupling between the two (DEA and passive  
144 tube).

145  
146 Fabrication process

147 The tubular DEA comprises multiple modules that are assembled in a stacked arrangement  
148 and subsequently rolled to create the final device. The manufacturing procedure involves a  
149 series of distinct stages, encompassing module creation, stacking, rolling, and establishment  
150 of electrical connections. A module is composed of a silicone film (Elastosil film 2030, Wacker,  
151 Munich, Germany), compliant electrodes containing carbon powder, and silver lines serving  
152 as electrical conduits.

153 The manufacturing process commences by cutting silicone film sheets and polyethylene  
154 terephthalate (PET) masks (ES301130, Goodfellow) to the desired dimensions using a CO<sub>2</sub>  
155 laser cutter (Trotec, Speedy 360 flexx). After accurately sizing the silicone films, narrow strips  
156 of silver ink (CreativeMaterials, 125-19(SP)A/B) are applied through PET masks. This  
157 deposition is accomplished using an automatic film applicator coater and a universal  
158 applicator (Zehntner ZAA 2300 and ZUA 2000, Proceq Group, Switzerland). Following this, a  
159 curing period of 16 hours at 80°C is necessary. Similarly, a layer of carbon ink is subsequently  
160 deposited, and it requires a curing time of 4 hours at 80°C. At this juncture, the modules are  
161 considered prepared.

162 Additionally, laser-engraved markers aid in aligning the modules during the stacking process.  
163 Silicone glue (Silbione, LSR4305) is employed for stacking, containing 0.3% carbon powder by  
164 mass to enhance charge distribution. After stacking, the assembly is cured for 2 hours at 80°C.  
165 Once the layers are fully stacked, the resulting multilayer system undergoes a rolling process.  
166 This rolling action utilizes a 30 mm diameter PMMA tube, along with the same silicone glue  
167 used for stacking, albeit without carbon powder. The multilayer stack is rolled and then  
168 subjected to a 2-hour curing period at 80°C within an oven.

169 For wiring purposes, high-voltage copper wires are affixed to the ends of the silver lines using  
170 conductive silicone (Wacker, ELASTOSIL LR 3162 A/B). To prevent unintended arcing during  
171 activation, the conductive silicone is coated with molded silicone (Dow Corning, Sylgard 186).  
172 Both types of silicone require a 2-hour curing duration at 80°C each. Further details of the  
173 fabrication of the tubular DEA used here is available in (30).

174

### 175 Experimental Setup

176 The experimental arrangement designed to assess the efficiency of the proposed impedance  
177 pump is a closed-loop in vitro system. This setup consists of a Tygon tube interconnected with  
178 the tubular DEA-based soft pump, utilizing aluminum components for connection. These  
179 aluminum parts facilitate the integration of pressure sensors (PBMN-258 1 2R A21 44621  
180 2000, provided by Baumer, Germany) at both ends of the pump. Additionally, the setup  
181 incorporates a laser sensor (LK-G23/LK-G3001P, Keyence, Osaka, Japan) to measure the radial  
182 deformation of the active DEA. Furthermore, a flow sensor (ME16PX, Transonic Systems Inc.,  
183 NY, USA) is installed externally around the Tygon tube to gauge the resulting net flow rate  
184 generated by the tubular pump. Notably, this setup does not incorporate any type of valves.  
185 The fluid used for the experimental testing is water with a density of 1000 kg/m<sup>3</sup> and a  
186 viscosity of 1 mPa·s.

187

188 Controlling and overseeing the experimental arrangement is achieved through MATLAB /  
189 Simulink software, Massachusetts, US. To facilitate this, a versatile data acquisition module  
190 (NI cDAQ-9179) from National Instruments (Texas, US) is employed. This module serves the  
191 dual purpose of providing the input control voltage and measuring the output current. The  
192 module is capable of generating precise voltage levels (with a resolution of 3.5 mV) ranging  
193 from -10 V to +10 V. To administer the input signal (up to 20kV), a high-voltage amplifier (Trek

194 20/20C-HS, manufactured by Advanced Energy, Denver, Colorado, USA) is employed. The  
195 same data acquisition module is responsible for real-time measurements of pressure  
196 waveforms, radial deformations, and flow rates.

197 All testing procedures and parameter adjustments (both input and output) are executed and  
198 controlled in real-time using a unified MATLAB / Simulink program. The experimental study  
199 operates with a time step of 0.004 seconds.

200

201

202

203

## 204 **Results and Discussion:**

205 To illustrate the effectiveness of the proposed concept, an innovative scenario is envisioned  
206 to support the pumping function of a weakened or failing heart, particularly in individuals with  
207 Failing Fontan. This scenario centers on the implementation of a cavopulmonary assist device  
208 targeting the right side of the heart, providing a unique approach to enhancing cardiac  
209 function and improving the quality of life. Specifically, it focuses on replacing the existing  
210 Fontan conduit with the tubular DEA pump (internal pressure of 10 - 20 mmHg), as depicted  
211 in **Figure 1a**. Thus, it is a more targeted approach for individuals who have previously  
212 undergone or in need of a Fontan procedure. The Fontan procedure is typically performed on  
213 patients with CHDs to redirect blood flow directly to the lungs without passing through the  
214 heart. In this envisioned scenario, the existing Fontan conduit is replaced with a specialized  
215 pump designed to optimize circulatory efficiency (See **Figure 1a**).

216

217 The custom-built DEA pump (see **Figure 1b**) is designed, fabricated, and subjected to testing  
218 to emulate the operational parameters of a Fontan conduit (characterized by an internal  
219 pressure range of 10 - 20 mmHg). As previously indicated, this pump consists of three primary  
220 components: a tubular DEA (depicted in black in Figure 2a) measuring 50 mm in length, 30  
221 mm in diameter, and possessing a thickness of 0.12 mm; a passive tube (shown as transparent  
222 in **Figure 2a**) with the same dimensions of 50 mm length, 30 mm diameter, and a thickness of  
223 0.1 mm; these two components are interconnected through a PMMA link measuring 10 mm  
224 in length, 30 mm in diameter, and 1 mm in thickness (see **Table 1**). The link's small size  
225 minimizes additional system length. Each of the three elements plays a vital role in achieving  
226 a unidirectional net flow. The active DEA functions as a pressure wave generator, the passive  
227 tube acts as a pressure wave damper, and the rigid ring ensures each part adheres to its  
228 designated function by decoupling their motions. This guarantees that the passive tube  
229 responds exclusively to fluid movement. For instance, in the absence of or insufficient  
230 decoupling, the sum of all incident and reflected pressure waves produced by the tubular DEA  
231 equals zero, resulting in no flow.

232

233 Furthermore, the selection of the DEA's thickness is contingent upon the operational internal  
234 pressure, chosen strategically to optimize the extent of volume variation during activation,  
235 thereby facilitating the generation of waves, thus flow rates.

236

237 The DEA pump designed and manufactured here underwent testing across a range of 10  
238 frequencies, spanning from 1 to 10 Hz. Each frequency is tested a multiple time. Throughout  
239 these experiments, the internal pressure and maximum activation voltage remained constant

240 at 13 mmHg and 4.5 kV, respectively. The outcomes of these tests are graphically depicted in  
241 **Figure 3**, revealing the characteristic behavior associated with an impedance pump.

242  
243 It's worth noting that even though this DEA pump functions through expansion rather than  
244 compression and necessitates a decoupling element, it still exhibits behavior typical of an  
245 impedance pump. Notably, it displays a resonance behavior, particularly pronounced at 4 Hz  
246 (as shown in **Figure 3**), a trait commonly observed in impedance pumps (19). As a result of this  
247 behavior, it is reasonable to conclude that the DEA pump indeed functions as an impedance  
248 pump. The resonant frequency is precisely identified at 4.0 Hz, and the pump demonstrates  
249 the capability to generate a substantial flow rate of 1.20 L/min (as shown in **Figure 2b**) when  
250 operating under internal pressure and maximum voltage conditions of 15 mmHg and 5.5 kV,  
251 respectively (refer to **Figure 2c-d**). **Figure 4** displays a time series representing the working  
252 principle of the DEA pump at the resonant frequency.

253 Our DEA pump is purposefully designed to seamlessly integrate with the Fontan procedure,  
254 introducing no changes except for replacing the traditional passive conduit with our active  
255 conduit. When not activated (no applied voltage), our conduit functions as a conventional  
256 passive conduit. However, upon activation, the pump amplifies the existing flow in the  
257 pulmonary arteries. The DEA tube inflates like a balloon during activation, generating the  
258 waves essential for impedance pumping. Most importantly, whether active or not, the DEA  
259 pump never obstructs the flow, and in the event of malfunction, it simply functions as a  
260 traditional passive Fontan conduit.

261  
262 By replacing the Fontan conduit with a dedicated pump, medical practitioners could further  
263 enhance the oxygenation of blood and alleviate potential complications arising from the  
264 modified circulatory system. This innovative approach seeks to address challenges associated  
265 with the Fontan procedure and improve the overall cardiac function of patients with  
266 congenital heart defects.

### 267 268 Limitations

269 The tubular DEA Pump exhibits remarkable capabilities in generating substantial flow rates  
270 without the need for any valves; however, its limitations are evident. Despite its substantial  
271 contributions, it falls short of being a full cardiac replacement, living up to the true meaning  
272 of the name only as a heart assist device. Its size, especially the length, reaching up to 110 mm  
273 and potentially longer with pre-stretching, poses challenges in terms of implantation. To pave  
274 the way for its practical implementation, extensive efforts are required to enhance flow  
275 output and minimize its dimensions. Additionally, a comprehensive exploration of its  
276 performance within an in-vivo environment is imperative—considering variables such as  
277 blood viscosity and lung resistance—to ensure optimal functionality. Despite these challenges,  
278 this technology harbors immense potential for the next generation of heart assist devices,  
279 characterized by their flexibility, lightweight nature, absence of valves and blades, pulsatile  
280 operation, and energy efficiency.

### 281 282 **Conclusion:**

283 The developed system demonstrates high capabilities, generating substantial flow rates of up  
284 to 1.20 L/min. This device operates effectively across a diverse pressure spectrum, ranging

285 from less than 10 to more than 20 mmHg. Notably, it showcases the ability to manipulate flow  
 286 properties such as the magnitude by simply adjusting the input signal and frequency.  
 287 In terms of future endeavors, the focus will be on refining the design to enhance performance  
 288 while simultaneously reducing its overall size. **Additionally, the next steps involve conducting**  
 289 **thorough tests using a setup that closely mimics anatomical accuracy before advancing to**  
 290 **animal trials.** As research and technological advancements continue, the proposed pumping  
 291 device holds the potential to redefine the landscape of cardiac care, offering new avenues of  
 292 hope and improved health for patients in need.

293  
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 297 foundation.

298 **Conflict of interest statement:** None.

299 **Author contribution statement:**

300 **Figure:**

301 Central image: Novel DEA-based pump as a substitute for the Fontan conduit and *in-vitro* achieved flow rate.

302 **Figure 1:** a) Illustration depicting the utilization of the DEA pump as a substitute for the Fontan conduit. b)  
 303 Schematics outlining the working principle of the impedance pump in a closed-loop setup.

304 **Figure 2:** Experimental results at the resonant frequency (4 Hz) and under conditions of low internal pressure (15  
 305 mmHg), specifically for cavopulmonary assist device applications. a) Description of the experimental setup b)  
 306 reported mean filtered flow rate data generated from 5 experimental tests, c) the applied voltage signal, and d)  
 307 the measured pressure variation throughout the activation process.

308 **Figure 3:** Statistical experimental results for the DEA-based pump across frequencies ranging from 1 to 10 Hz and  
 309 a maximum applied voltage, and an internal pressure of 4.5 kV, and 13 mmHg, respectively.

310 **Figure 4:** The working behavior of the DEA pump observed at the resonant frequency of 4 Hz and an internal  
 311 pressure of 15 mmHg. a) A time-lapse representation of particles movement within the fluid during the activation  
 312 process, b) DEA pump at 5.5 kV, c) DEA pump at 0 kV, and d) the applied voltage signal.

313

314

315 **Tables:**

316 **Table 1:** Geometric specifications of the DEA pump are provided for: DEA tube, passive tube, and PMMA link.

Scenario	Input (kV)	Working Pressure (mmHg)	DEA Length (mm)	DEA Diameter (mm)	DEA Thickness (mm)
DEA tube	0 - 5,5	10 -20	50	30	0.12
Passive tube	-	-	50	30	0.1
PMMA link	-	-	10	30	1

317

318 **Data availability statement**



319 Data are available from the corresponding author upon reasonable request.

320

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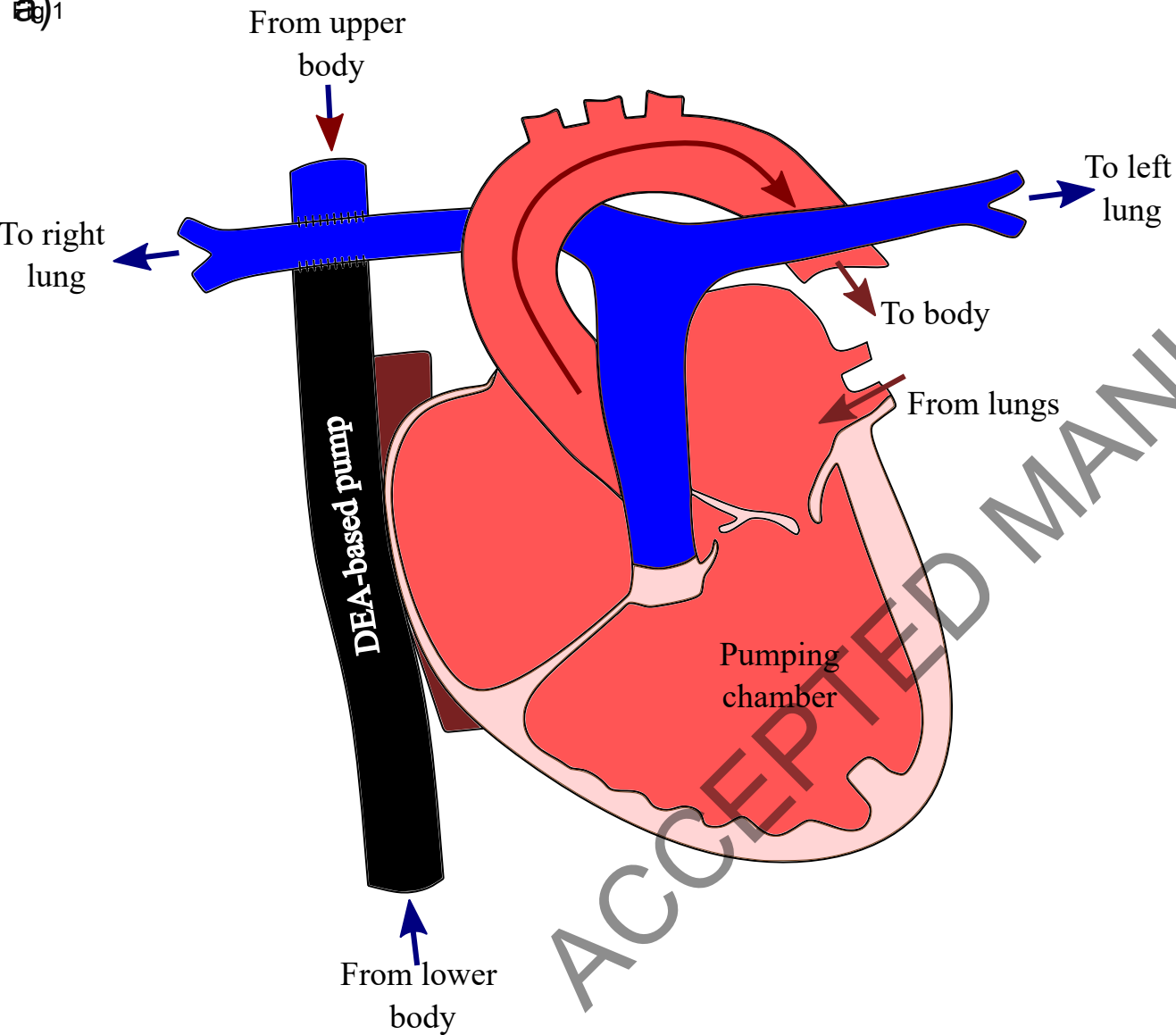
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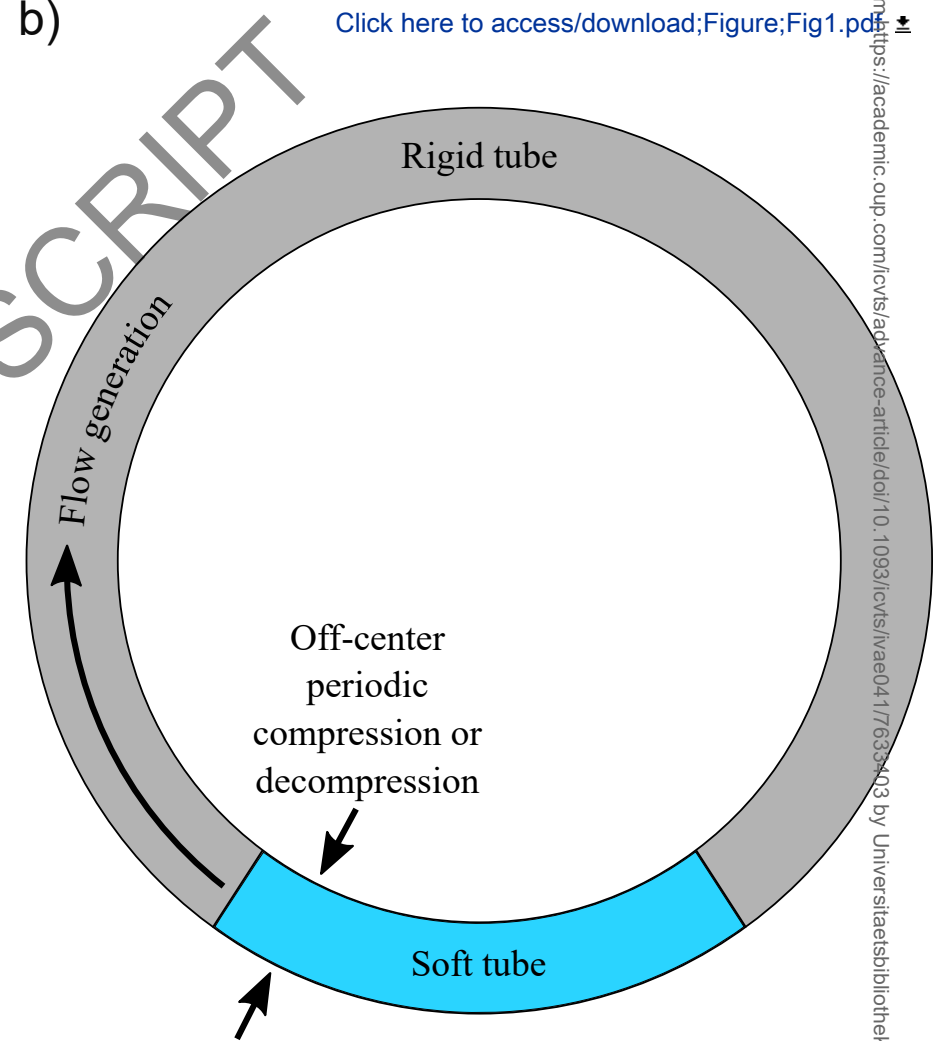
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a) 1



b)



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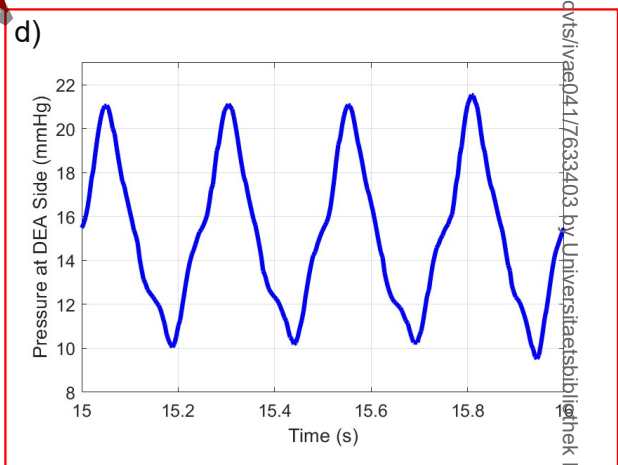
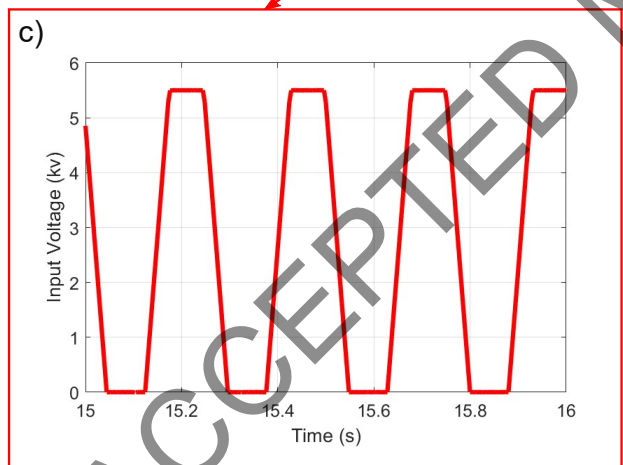
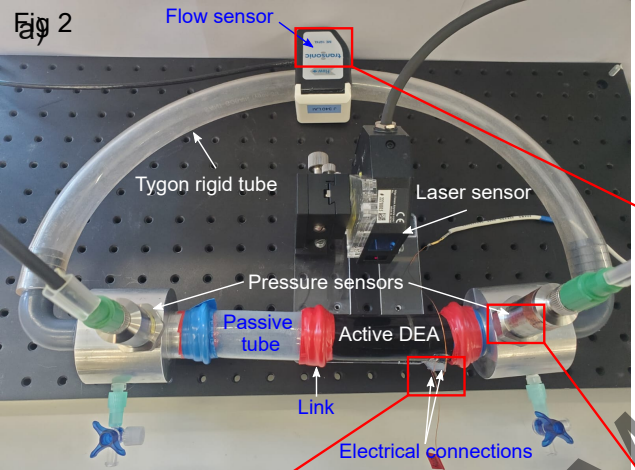
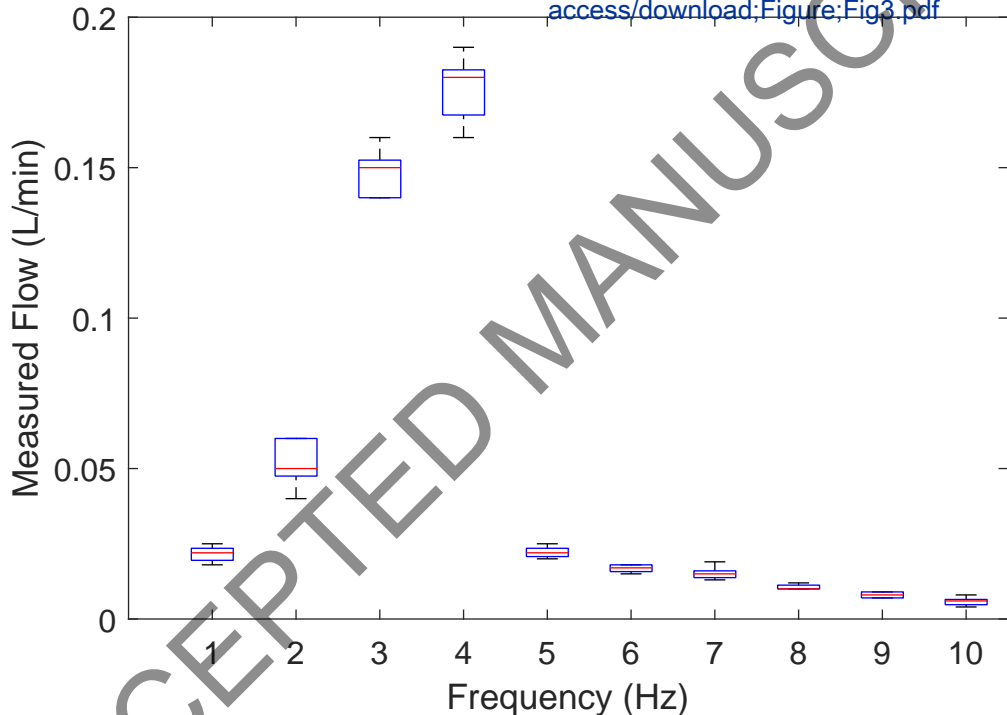
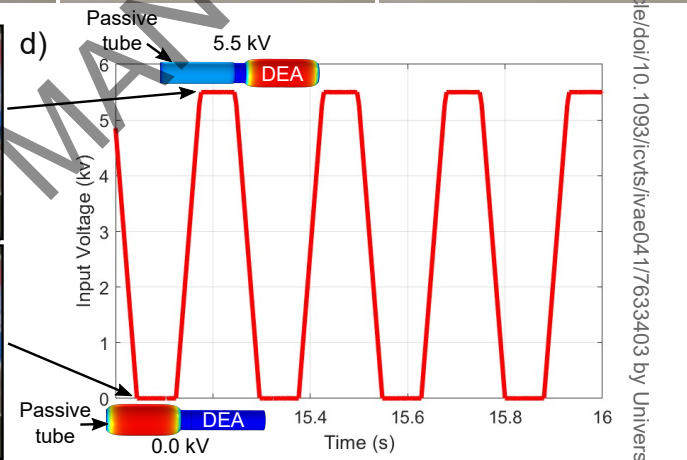
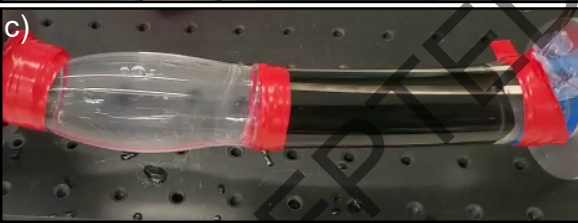
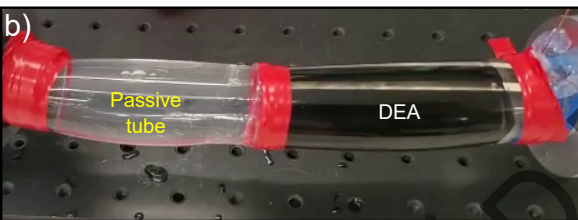
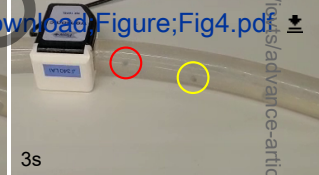
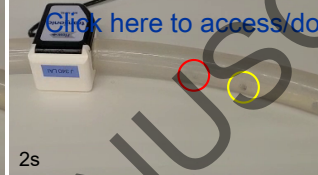
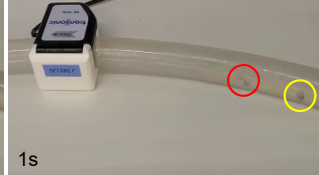
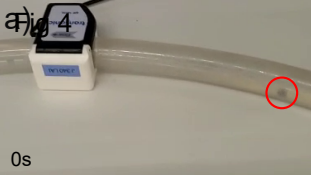


Fig 3

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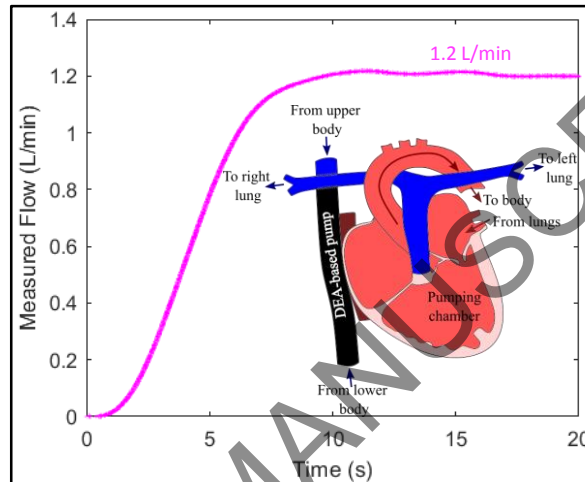




## Novel dielectric elastomer actuator pump as a substitute for the Fontan conduit

## Summary

This *in-vitro* study explores the viability of a bladeless impedance-driven cavopulmonary assist device utilizing dielectric elastomer actuators (DEA) as a potential solution for Fontan failure. The DEA-based pump undergoes testing within a closed-loop setup, demonstrating its capacity to produce substantial flow rates across various pressure levels.



Legend: Novel DEA-based pump as a substitute for the Fontan conduit and *in-vitro* achieved flow rate.

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