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The ATLAS Collaboration

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1. Introduction

Several extensions to the Standard Model predict the production of heavy particles with lifetimes that may be of order picoseconds up to about a nanosecond [1], at the Large Hadron Collider (LHC). One such scenario is gravity-mediated supersymmetry (SUGRA [2]) with R -parity violation (RPV) [3, 4]. If the results of R -parity conserving supersymmetry searches at the LHC (see, for example, Refs. [5, 6]) continue to disfavour light superpartners, then scenarios in which R -parity is violated may be required if supersymmetry is the solution to the hierarchy problem [7]. The present (largely indirect) constraints on RPV couplings [3, 4] would allow the decay of the lightest supersymmetric particle as it traverses a particle detector at the LHC. Signatures of heavy, long-lived particles also feature in models of gauge-mediated supersymmetry breaking [8], split-supersymmetry [9], hidden-valley [10], dark-sector gauge bosons [11] and stealth supersymmetry [12] though some of these models are disfavoured [13] by the recent results on the search for the Higgs boson [14, 15].

This Letter presents the results of a search for the decay of a heavy particle, producing a multi-track vertex that contains a muon with high transverse momentum (p_T) at a distance between millimetres and tens of centimetres from the pp interaction point. As in the earlier ATLAS

work [16], the results are interpreted in the context of an R -parity violating supersymmetric scenario. In this model, the signature under consideration corresponds to the decay of the lightest supersymmetric particle, resulting in a muon and many high- p_T charged tracks originating from a single displaced vertex (DV). This can arise from a diagram such as that shown in Fig. 1, where the decay occurs due to the non-zero RPV coupling λ'_{2ij} .

The CMS collaboration has performed a search for a related signature, where a long-lived neutral particle decays to a final state containing two leptons, using 5 pb^{-1} of pp collisions at $\sqrt{s} = 7$ TeV [17]¹. Similar searches have also been performed by the DØ collaboration at the Tevatron with $\sqrt{s} = 1.96$ TeV $p\bar{p}$ collisions [18], who also study decays to a $b\bar{b}$ pair [19], and at LEP [20]. The result reported here improves on the previous ATLAS search for this signature [16] in several ways. The dataset is around 100 times larger, corresponding to an integrated luminosity of 4.4 fb^{-1} [21]. Furthermore, the signal efficiency is increased by improving the reconstruction efficiency for reconstructing tracks that do not originate from the primary vertex. The dependence on simulation to estimate background levels is also removed. Finally, while the pre-

¹Following submission of our paper, this paper was submitted addressing the same physics, but for a different final state.

vious analysis did not require muons to be associated vertices, this association requirement is now imposed, which greatly simplifies both the analysis itself, and also the re-interpretation of these results for scenarios containing different numbers of long-lived particles.

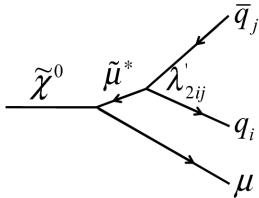


Figure 1: Diagram of the massive lightest neutralino $\tilde{\chi}^0$ decaying into a muon and two jets via a virtual smuon, with lepton-number and R -parity violating coupling λ'_{2ij} .

2. The ATLAS detector

The ATLAS detector [22] is a multipurpose apparatus at the LHC. The detector consists of several layers of sub-detectors. From the interaction point (IP) outwards there is an inner detector (ID), measuring the tracks of charged particles, electromagnetic and hadronic calorimeters, and an outer muon spectrometer (MS).

The ID is immersed in a 2 T axial magnetic field, and extends from a radius² of about 45 mm to 1100 mm and to $|z|$ of about 3100 mm. It provides tracking and vertex information for charged particles within the pseudorapidity region $|\eta| < 2.5$. At small radii, silicon pixel layers and stereo pairs of silicon microstrip detectors provide high resolution pattern recognition. The pixel system consists of three barrel layers, and three forward disks on either side of the interaction point (the beam pipe envelope is at a radius of about 30 mm). The barrel pixel layers, which are positioned at radii of 50.5 mm, 88.5 mm, and 122.5 mm are of particular relevance to this work. The silicon microstrip tracker (SCT) comprises four double layers in the barrel, and nine forward disks on either side. A further tracking system, a transition-radiation tracker (TRT), is positioned at larger radii. This device is made of straw-tube elements interleaved with transition-radiation material; it provides coverage within the region $|\eta| < 2.0$.

The calorimeter provides coverage over the pseudorapidity range $|\eta| < 4.9$. It consists of a lead/liquid-argon

electromagnetic calorimeter, a hadronic calorimeter comprising a steel and scintillator-tile system in the barrel region and a liquid-argon system with copper and tungsten absorbers in the end-caps.

Muon identification and momentum measurement is provided by the MS. This device has a coverage in pseudorapidity of $|\eta| < 2.7$ and is a three-layer system of gas-filled precision-tracking chambers. The pseudorapidity region $|\eta| < 2.4$ is additionally covered by separate trigger chambers, used by the hardware trigger for the first level of triggering (level-1). The MS is immersed in a magnetic field which is produced by a set of toroid magnets, one for the barrel and one each for the two end-caps. Online event selection is performed with a three-level trigger system. It comprises a hardware-based level-1 trigger, which uses information from the MS trigger chambers and the calorimeters, followed by two software-based trigger levels.

3. Data and simulation

The data used in this analysis were collected between March and October, 2011. After the application of beam, detector, and data-quality requirements, the integrated luminosity considered corresponds to 4.4 fb^{-1} , with an uncertainty of $\pm 3.9\%$ [21].

Signal Monte Carlo (MC) events are generated with PYTHIA 6 [23], using the MRST LO** [24] set of parton distribution functions (PDFs). Processes are simulated in which a $\tilde{q}\tilde{q}$, $\tilde{q}\tilde{q}$, or $\tilde{q}\tilde{q}$ pair is produced in the pp collision, with each squark (antisquark) decaying into a long-lived lightest neutralino and a quark (antiquark). Degeneracy of the first and second generations and for the left-handed and right-handed squarks is assumed. The masses of the gluino, sleptons and third-generation squarks are set at such a high value (5 TeV) that they are not directly produced in the supersymmetry scenario considered here.

The parameter settings for the samples of signal MC events are summarised in Table 1. The chosen values of squark and neutralino masses correspond to a wide range in the quantities to which the signal efficiency is most sensitive: neutralino speed and final-state multiplicities (see Section 5). The Higgsino-gaugino mixing determines the neutralino mass values. The signal MC samples are labelled in Table 1 according to the squark mass and neutralino mass, respectively: MH (medium-mass squark, heavy neutralino), ML (medium-mass squark, light neutralino), and HH (heavy squark and heavy neutralino). It is assumed that all RPV couplings other than λ'_{211} are zero. This leads to each neutralino decaying to $\mu^- u \bar{d}$ (or the charge-conjugate state). Decays of neutralinos to a neutrino and jets final state, which would also occur via a non-zero λ'_{211} , are not considered in this work.

The PROSPINO [25] program is used to calculate the signal cross section (hereafter referred to as the supersymmetry production cross section) at next-to-leading order; cross section values are listed in Table 1. The CTEQ6.6

²ATLAS uses a right-handed coordinate system with its origin at the nominal IP in the centre of the detector and the z -axis along the beam pipe. The x -axis points from the IP to the centre of the LHC ring, and the y -axis points upward. Cylindrical coordinates (r, ϕ) are used in the transverse plane, ϕ being the azimuthal angle around the beam pipe. The pseudorapidity is defined in terms of the polar angle θ as $\eta = -\ln \tan(\theta/2)$.

Sample	$m_{\tilde{q}}$ [GeV]	σ [fb]	$m_{\tilde{\chi}_1^0}$ [GeV]	$\langle\gamma\beta\rangle_{\tilde{\chi}_1^0}$	$c\tau_{\text{MC}}$ [mm]	λ'_{211} $\times 10^{-5}$
MH	700	66.4	494	1.0	78	0.3
ML	700	66.4	108	3.1	101	1.5
HH	1500	0.2	494	1.9	82	1.5

Table 1: The parameter values for the three signal MC samples used in this work: the assumed squark mass, production cross section (calculated with PROSPINO), neutralino mass, average value of the Lorentz boost factor (from PYTHIA), average proper decay length, and value of λ'_{211} coupling used in the generation of the signal MC samples.

PDF set [26] is used. Owing to differences in the predicted cross sections for the $\tilde{q}\tilde{q}$ and $\tilde{q}\tilde{\bar{q}}$ processes from PYTHIA and PROSPINO, and the possible sensitivity of the neutralino-speed distribution to the assumed process, signal samples are generated for each process separately with PYTHIA and reweighted according to the relative cross sections of the two processes as estimated with PROSPINO. The reweighting procedure, however, has a minimal effect on the distributions of physical quantities used in this work and typically leads to changes of much less than 1%.

Each generated event in the signal samples is processed with the GEANT4-based [27] ATLAS detector simulation [28] and treated in the same way as the collision data. The samples include a realistic modelling of the effects of multiple pp collision per bunch crossing (pile-up) observed in the data, obtained by overlaying simulated Minimum Bias events generated using PYTHIA, on top of the hard scattering events, and reweighting events such that the distribution of the number of interactions per bunch crossing matches that in the data..

4. Vertex reconstruction and event selection

It is required that the trigger identifies a muon candidate with transverse momentum $p_T > 40$ GeV and $|\eta| < 1.05$, i.e., in the barrel region of the MS. The latter selection is necessary since there is no ID track requirement in the trigger, and the trigger rate arising from muons with badly measured momenta in the (larger $|\eta|$) end-cap region, where the magnetic field is highly complex, would have consumed too much bandwidth to be viable in the 2011 running conditions.

Owing to the higher instantaneous luminosity of the LHC in 2011 compared to that in 2010, most events contain more than one primary vertex (PV). The PV with the highest sum of p_T^2 of the tracks associated to it is required to have at least five tracks and a z position in the range $|z_{\text{PV}}| < 200$ mm. In order to reduce cosmic-ray background, events are rejected if they contain two muons which appear back-to-back. A selection $\sqrt{(\pi - (\phi_1 - \phi_2))^2 - (\eta_1 + \eta_2)^2} > 0.1$ is applied where ϕ_1 ,

ϕ_2 , η_1 and η_2 are the azimuthal angles and pseudorapidities of the two reconstructed muons.

A muon candidate is required to have been reconstructed in both the MS and the ID with transverse momentum $p_T > 50$ GeV (which is well into the region where the trigger efficiency is approximately independent of the muon momentum) and $|\eta| < 1.07$. The impact parameter relative to the transverse position of the primary vertex (d_0) is required to satisfy $|d_0| > 1.5$ mm. To ensure that the muon candidate is associated with the muon that satisfied the trigger requirement, the selection $\sqrt{(\Delta\phi)^2 + (\Delta\eta)^2} < 0.15$ is imposed, where $\Delta\phi$ ($\Delta\eta$) is the difference between the azimuthal angle (pseudorapidity) of the reconstructed muon and that of the muon identified by the trigger. The ID track associated with the muon candidate is required to have at least six SCT hits, and at most one SCT hit that is expected but not found i.e. in an active detector element with no known read-out problems. Furthermore, the track must satisfy an $|\eta|$ -dependent requirement on the number of TRT hits. No pixel-hit requirements are applied to the muon track. The combination of requirements described above is referred to as the muon-selection criteria.

In order to reconstruct a DV it is first necessary to select high quality tracks. This is done by requiring that candidate tracks have two or more associated SCT hits and a value of $|d_0|$ greater than 2 mm. Studies made with the MC simulation show that 98% of all tracks originating from the primary pp interaction are rejected by the selection on $|d_0|$. Standard ATLAS tracking [22] is based on three passes in which the initial track candidates are formed in different ways: initially found in the silicon detectors, initially found in the TRT detector, and only found in the TRT detector. The algorithms all assume that tracks originate from close to the PV, and hence have reduced reconstruction efficiency for signal tracks which originate at a DV. To counter this problem and recover some of these lost tracks, the silicon-seeded tracking algorithm is re-run with looser requirements on the radial and z impact parameters, and on the number of detector hits that can be shared among more than one seed track. To reduce the rate of false seed tracks, it is required that these additional tracks have $p_T > 1$ GeV, which is greater than the standard-tracking requirement of $p_T > 400$ MeV. This procedure is termed “re-tracking”. Fig. 2 shows the efficiency for vertex reconstruction (described later) as a function of the radial position of the vertex r_{DV} when using standard tracking and re-tracking for sample MH. As can be seen, there is a substantial improvement due to re-tracking at values of r_{DV} greater than about 10 mm. The dips in the plot correspond to losses in efficiency for decays immediately before a pixel layer, where many tracks from the vertex have shared pixel hits and therefore fail the selection.

Using an algorithm based on the incompatibility-graph approach [29], DVs are sought with the selected tracks. The method adopted is similar to that used in Ref. [30].

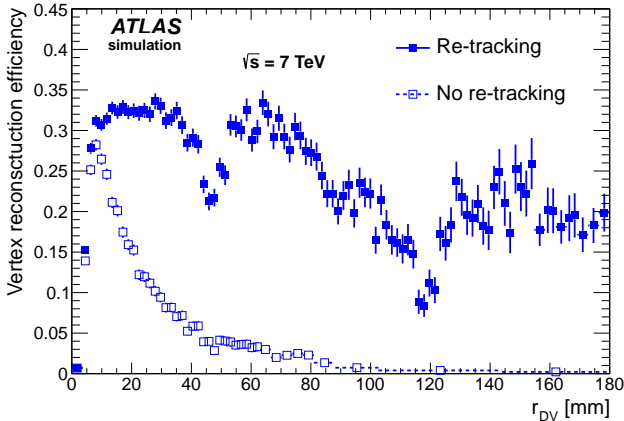


Figure 2: The vertex reconstruction efficiency as a function of r_{DV} for the MH sample, with and without re-tracking. All selection criteria, except for the material veto, have been applied.

The algorithm starts by finding two-track seed vertices from all pairs of tracks; those that have a vertex-fit χ^2 of less than 5.0 per degree of freedom are retained. A seed vertex is rejected if at least one of its tracks has hits between the vertex and the PV. Multi-track vertices are formed from combinations of seed vertices in an iterative process. The following method is used to do this. If a track is assigned to two different vertices, the action taken depends on the distance D between the vertices. If $D < 3\sigma_D$, where σ_D is the estimated uncertainty on D , a single vertex is formed from the tracks of the two vertices. Otherwise, a track is associated with that vertex for which the track has the smaller χ^2 value. In the event of the χ^2 of a track relative to the resulting vertex exceeding 3.0 per degree of freedom, the track is removed from the vertex, and the vertex is refitted. This process continues until no track is associated with more than one vertex. Finally, vertices are combined and refitted if they are separated by less than 1 mm.

To ensure a good quality DV fit, the χ^2 per degree of freedom of the fit must be less than 5. Furthermore, the DV position is required to be in the fiducial region, defined as $|z_{DV}| < 300$ mm and $r_{DV} < 180$ mm, where r_{DV} and z_{DV} are the radial and longitudinal vertex positions with respect to the origin. To minimise background coming from the PVs, the transverse distance $\sqrt{(x_{DV} - x_{PV})^2 + (y_{DV} - y_{PV})^2}$ between any of the PVs and the DV must be at least 4 mm. Here x and y are the transverse coordinates of a given vertex, with the subscripts PV and DV denoting the type of vertex. The number of tracks N_{DV}^{trk} associated with the DV is required to be at least five. This reduces background from random combinations of tracks and from material interactions. Background due to particle interactions with material is suppressed by requiring $m_{DV} > 10$ GeV. Here, m_{DV} is the invariant mass of the set of tracks associated with the DV, using the charged-pion mass hypothesis for each track.

Candidate vertices which pass (fail) the $m_{DV} > 10$ GeV requirement are hereafter referred to as being high- m_{DV} (low- m_{DV}) vertices.

The typical position resolution of the DV in the signal MC samples is tens of microns for r_{DV} and about 200 μm for z_{DV} near the interaction point. For vertices beyond the outermost pixel layer, which is located at a radius of 122.5 mm, the typical resolution is several hundred microns for both coordinates.

Low- m_{DV} ($m_{DV} < 4\text{GeV}$) vertices from particle-material interactions are abundant in regions in which the detector material is dense. High- m_{DV} background may arise from the random spatial coincidence of a material-interaction vertex with a high- p_T track, especially when this track and the particle that initiated the material-interaction vertex originate from different primary interactions, resulting in a large angle between their momentum vectors.

To reduce this source of background, vertices that are reconstructed in regions of high-density material are removed. The high-density material was mapped using low- m_{DV} material-interaction candidate vertices in data and true material-interaction vertices in minimum-bias MC events. The z_{DV} and r_{DV} positions of these vertices are used to make a two-dimensional material-density distribution with a bin size of 4 mm in z_{DV} and 1 mm in r_{DV} . It has been demonstrated [30] that the detector simulation describes the positions of pixel layers and associated material reasonably well, while the simulated position of the beampipe is shifted with respect to the actual position. The use of data events to construct the material map therefore ensures that the beampipe material is correctly mapped, while the use of the simulation provides a high granularity of the map at the outer pixel layers, where material-interaction vertices in the data are comparatively rare. Material-map bins with vertex density greater than an r_{DV} - and z_{DV} -dependent density criterion are characterised as high-density-material regions. These make up 34% of the volume at $|z_{DV}| < 300$ mm, $r_{DV} < 180$ mm.

To ensure that the muon candidate is associated with the reconstructed DV, the distance of closest approach of the muon with respect to the DV is required to be less than 0.5 mm. This requirement ensures that the vertex that we reconstruct gave rise to the muon that triggered the event, and so the selection efficiency for each neutralino decay is independent of the rest of the event. This facilitates a straightforward calculation of the event selection efficiency for scenarios with different numbers of long-lived neutralinos in the event. The aforementioned selections are collectively referred to as the vertex-selection criteria. Events containing one or more vertices passing these criteria are accepted.

5. Signal efficiency

The signal efficiency depends strongly on the efficiencies for track reconstruction and track selection, which are

affected by several factors: (1) The number of tracks originating from the DV and their total invariant mass increase with the neutralino mass. (2) More tracks fail the $|d_0| > 2$ mm requirement for small r_{DV} or if a neutralino with large p_T has a small decay length, thereby leaving its daughters pointing back closer to the PV. (3) The efficiency for reconstructing tracks decreases with increasing values of $|d_0|$. Because the MH and HH samples have the same neutralino mass, but different boosts, a cross-check of the efficiency estimation procedure can be made. The HH sample is reweighted vertex-by-vertex such that the $\beta\gamma$ versus η distributions match the MH sample. It was checked that they have the same efficiency as a function of decay position.

The total efficiency for each of the signal MC samples is shown in Fig. 3 as a function of $c\tau$. This is an overall event efficiency, derived from the determination of (the single) vertex efficiency, and is based on having two displaced vertices per event in the signal MC. This efficiency as a function of $c\tau$ is calculated from the samples generated with a single- $c\tau$ value (see Table 1) using a two-dimensional map in $(|z_{DV}|, r_{DV})$ (Fig. 4) and distributions of decay positions for different values of $c\tau$. Events are reweighted according to their probability of being found at different positions in the map, where the probability depends on $c\tau$. Figure 3 includes systematic corrections and uncertainties that are discussed in Section 7.

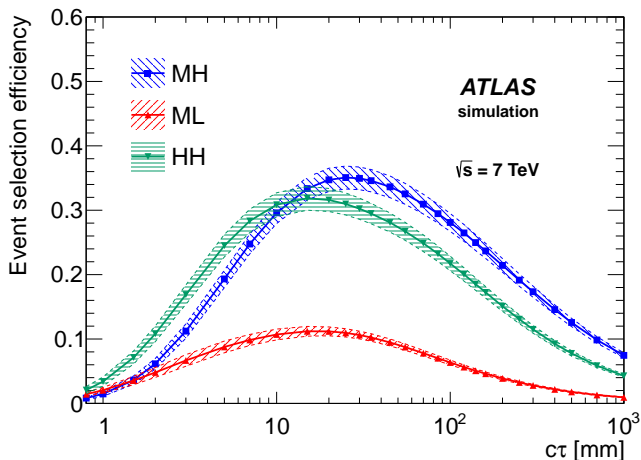


Figure 3: The event selection efficiency as a function of $c\tau$ for the three signal samples. The total uncertainties on the efficiency are shown as bands; the estimation of the uncertainties is discussed in Section 7.

6. Background estimation

Spurious high- m_{DV} , high-multiplicity vertices in non-material regions could come from one of two sources: (1) Purely random combinations of tracks (real or fake). This type of background is expected to form the largest contribution at small radii where the track density is highest. (2) Vertices from real hadronic interactions with gas

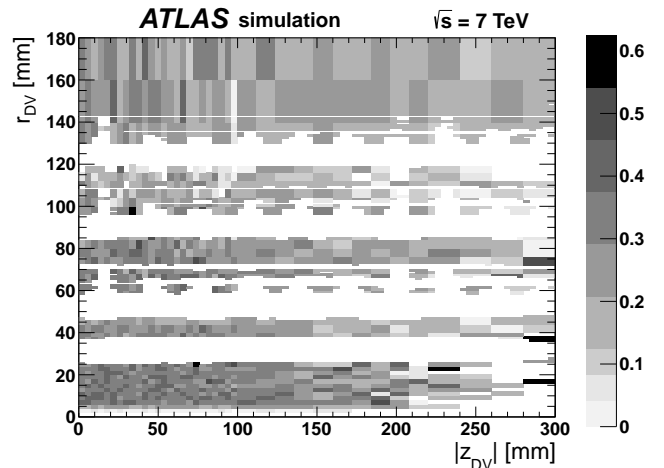


Figure 4: The efficiency as a function of r_{DV} and z_{DV} for vertices in the signal MC sample MH. The blank areas represent regions of dense material which are not considered when looking for DVs. Bin-to-bin fluctuations due to limited MC sample size are compensated for by recalculating this map many times, varying each bin content within its statistical uncertainty.

molecules. Although most of these events will have masses below the 10 GeV requirement, the high-mass tail of the distribution indicates a potential background, in particular if the vertex is crossed by a random track (real or fake) at large crossing angle.

The first source of background mentioned above gives rise to displaced vertices inside the beampipe (where there are few real hadronic interactions due to the good vacuum, but where random combinations are expected to dominate). The expected contribution from this source of background is evaluated using a large sample of jet-triggered events, and examining the ratio of the number of vertices with $m_{DV} > 10\text{GeV}$ to the number in a mass control region, $4\text{GeV} < m_{DV} < 10\text{GeV}$. Since the number of random combinations of tracks depends primarily on the pile-up conditions, and is therefore independent of the type of event that fired the trigger, this ratio can also be applied to the number of vertices in the mass control region in muon-triggered events. All of this information is used as input to a simple maximum likelihood fit, which yields a background expectation of $0.00^{+0.06}_0$ vertices passing our cuts, that arise from random combinations of tracks.

To estimate the second source of background i.e. vertices arising from real hadronic interactions, including those crossed by tracks from different PVs, two m_{DV} -distributions are constructed. One distribution is formed from vertices which do not include a so-called large-angle track, i.e. the average angle between a constituent track and the rest of the tracks in the vertex must be less than one radian. The four-momentum of a randomly-selected track in the event is added to the vertex to build the second distribution. Both of these distributions are taken from a large control sample of jet-triggered events. The relative normalisations of these distributions are determined using

an estimate of the “crossing probability”. This is obtained by fitting a function representing a K_S mass peak to the invariant mass distribution of all two-track combinations within three-track vertices, and comparing the integral of this function (which is a measure of how many real K_S were crossed by a random track to form a three-track vertex), to the number of two-track K_S mesons observed.

With the shape of the m_{DV} -distribution determined in this manner, the absolute normalisation for the muon-triggered sample can be found. It is extracted from a maximum likelihood fit, which takes as input the numbers of vertices in each material layer (i.e., the beam pipe and three pixel detector layers³), and the numbers of low-track-multiplicity vertices in the regions in which there is no material, which are termed “air gaps”. It has been empirically observed that in each material layer or air gap, the relation between the numbers of n -track, $(n+1)$ -track, $(n+2)$ -track vertices etc., is well modelled by an exponential function. Furthermore, the ratio of the number of n -track vertices in a material layer to the number in the air gap immediately outside it, is consistent between several different control samples. These relations can therefore be used in the fit to predict the number of vertices with at least five tracks in the air gaps. This procedure was tested on various control samples, giving consistent results for the $m_{\text{DV}} < 10\text{GeV}$ control region in all cases. For instance, in events that fail the muon trigger requirement, the fit predicted 105.4 ± 5.7 events, whereas 110 events were observed. The m_{DV} distribution, scaled by the prediction, is then integrated to obtain an estimate of the number of vertices with $m_{\text{DV}} > 10\text{ GeV}$, and a final scale factor is applied, based on the fraction of events in our muon-triggered sample that pass the offline muon requirements. Systematic uncertainties are evaluated by varying the relevant input parameters (the crossing probability, the parameters of the exponential function and material-to-airgap ratio, and the final scale factor) within their respective uncertainties, and taking the largest deviation. Finally, the background from hadronic interactions in the air gaps is estimated to be $3.7^{+4.4}_{-3.7} \times 10^{-3}$ vertices. Note that this is somewhat conservative, as the “crossing probability” used here is derived from tracks crossing K_S vertices, which have worse position resolution than vertices with four or more tracks.

The total background estimate is therefore taken to be $4^{+60}_{-4} \times 10^{-3}$ vertices.

7. Systematic corrections and uncertainties

Several categories of uncertainties and corrections are considered. The values of the uncertainties depend on the neutralino lifetime and the signal sample under investigation. However, they can be ordered in approximately decreasing size. Uncertainties on the muon reconstruction

efficiency are largest (typically $\approx 7\%$), followed by trigger ($\approx 6\%$) and tracking ($\approx 4\%$) efficiency uncertainties. The relative luminosity uncertainty is 3.9%, while the uncertainty due to limited numbers of events in the signal samples is around 1.5%. Other systematic effects, such as the uncertainty on the modelling of pile-up, contribute less than 1% to the total uncertainty. The effect on the efficiency associated with PDF uncertainties is negligible.

To estimate the uncertainty on the efficiency as a function of $c\tau$ (Fig. 3) from finite MC sample size, the efficiency in each bin of the two-dimensional efficiency map (Fig. 4) was varied randomly within its statistical uncertainty and the total efficiency was repeatedly re-measured. The spread in those results is taken as the contribution to the systematic uncertainty on the efficiency at each $c\tau$ value.

To compensate for the different z -distributions of the primary vertices in data and MC simulation, a weight is applied to each simulated event such that the reweighted z_{PV} distribution matches that in data. This weight is applied to both the numerator and denominator in the efficiency calculation.

Similarly, a weight is applied to each simulated event such that the distribution of $\langle\mu\rangle$, the average number of interactions per bunch-crossing, matches that in data. An uncertainty associated with this procedure is estimated by scaling the $\langle\mu\rangle$ values used as input to this correction calculation by a factor 0.9 (motivated by taking the difference between scaling the MC simulation by $\langle\mu\rangle$ calculated from luminosity measurements and by using the number of reconstructed PVs in data and MC simulation). The difference in the efficiency is evaluated as a function of $c\tau$, and is applied as a symmetric systematic uncertainty.

A trigger efficiency correction and its associated systematic uncertainty are derived from a study of $Z \rightarrow \mu^+\mu^-$ events in which at least one of the muons was selected with a single-muon trigger. The trigger efficiency for selecting a signal event is about 90%. The ratio of the trigger efficiencies in data and simulation is applied as a correction factor. Furthermore, the statistical uncertainty on this ratio is added in quadrature to the differences in trigger efficiency between the $Z \rightarrow \mu^+\mu^-$ sample and the signal samples to estimate a systematic uncertainty.

The modelling of track reconstruction efficiency for prompt tracks has been extensively studied in ATLAS [31]. In order to estimate the systematic uncertainty on the track reconstruction for secondary tracks, a study is performed where the number of K_S vertices in data and simulation are compared over a range of radii and η -values. Based on the outcome of this study, some fraction of tracks in the signal MC are randomly removed from the input to the vertexing algorithm, and the same procedure is used to obtain efficiency-vs- $c\tau$ is performed. The difference between this and the nominal efficiency at each $c\tau$ point is taken as the systematic uncertainty.

Since the distribution of the true values of d_0 for cosmic-ray muons is flat over the limited d_0 range considered here,

³A detailed study of the material distribution within the ID is provided in Ref. [30].

as predicted by cosmic-ray simulation, the shapes of the measured (and simulated) d_0 -spectra of such muons are used to determine the accuracy to which the simulation reproduces the muon-finding efficiency as a function of d_0 . The ratio of the number of observed cosmic-ray muons (recorded during 2011) and the simulated muon-finding efficiency is studied as a function of d_0 . The degree to which the distribution is not flat is used to estimate the d_0 -dependent muon-finding efficiency, which is used for the results in Figs. 3 and 4. The uncertainties on the efficiency (largely due to the limited statistical precision of the cosmic-ray background sample) are propagated to uncertainties of between $\pm 3.5\%$ (MH) and $\pm 8\%$ (ML) on the signal reconstruction efficiency, depending on the signal sample.

8. Results

Figure 5 shows the distribution of m_{DV} vs. N_{DV}^{trk} for vertices in the selected data events, including vertices that are rejected by the selection on m_{DV} and N_{DV}^{trk} . The signal distribution for the MH sample is also indicated. The signal region, corresponding to a minimum number of five tracks in a vertex and a minimum vertex mass of 10 GeV, is also shown. No events are observed in the signal region.

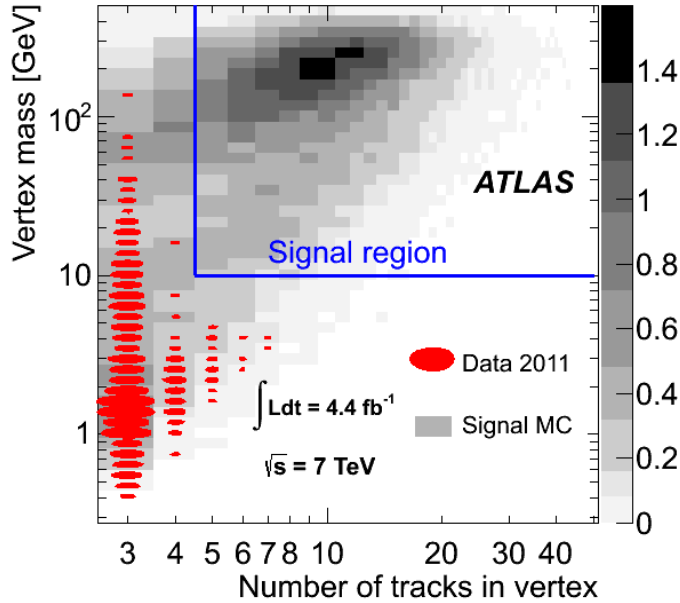


Figure 5: Vertex mass (m_{DV}) vs. vertex track multiplicity (N_{DV}^{trk}) for DVs in events with no muon requirements other than the trigger, and all other selection criteria except the m_{DV} and N_{DV}^{trk} requirements. Shaded bins show the distribution for the signal MC MH sample (see Table 1), and data are shown as filled ellipses, with the area of the ellipse proportional to the number of vertices in the corresponding bin.

Given the lack of candidate events in data, upper limits are evaluated on the supersymmetry production cross sec-

tion (σ) times the square of the branching ratio (BR^2) for produced squarks to decay via long-lived neutralinos to muons and quarks. The limits are presented for different assumed values of squark and neutralino mass and $c\tau$, where τ is the neutralino lifetime. Based on the efficiency, background estimate, and luminosity of 4.4 fb^{-1} (with the uncertainties on each of these treated as nuisance parameters), the CL_s method [32] is used to set limits on the plane of $\sigma \cdot BR^2$ versus $c\tau$. The resulting limits are shown in Fig. 6, with the PROSPINO-calculated cross sections for squark masses of 700 GeV and 1500 GeV. The PROSPINO predictions are shown as a band which represents the variation in predicted cross section when using two different sets of PDFs (CTEQ6.6 and MSTW2008NLO [33]) and varying the factorisation and renormalisation scales each up and down by a factor of two. Since essentially no background is expected and no events are observed, the expected and observed limits are indistinguishable. Based on the observation of no signal events in a data sample of 4.4 fb^{-1} , a 95% confidence-level upper limit of 0.68 fb is set on $\sigma \cdot BR^2$ multiplied by the detector acceptance and the reconstruction efficiency for any signal vertex.

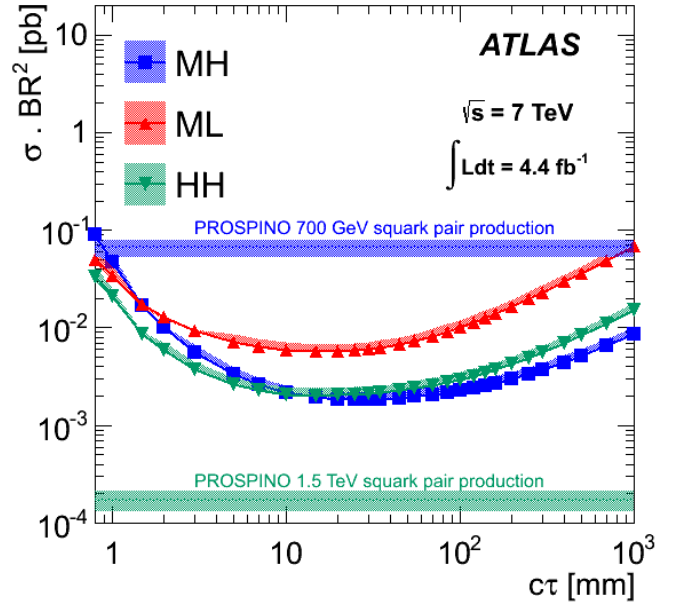


Figure 6: Upper limits at 95% confidence level on $\sigma \cdot BR^2$ vs. the neutralino lifetime for different combinations of squark and neutralino masses, based on the observation of zero events satisfying all criteria in a 4.4 fb^{-1} data sample. The shaded areas around these curves represent the $\pm 1\sigma$ uncertainty bands on the expected limits. The horizontal lines show the cross sections calculated from PROSPINO for squark masses of 700 GeV and 1500 GeV. The shaded regions around these lines represent the uncertainties on the cross sections obtained from the procedure described in the text.

9. Summary and conclusions

An improved search is presented for new, heavy particles that decay at radial distances between 4 mm and 180 mm from the pp interaction point, in association with a high-transverse-momentum muon. This search is based on data collected by the ATLAS detector at the LHC at a center-of-mass energy of 7 TeV. Fewer than 0.06 background events are expected in the data sample of 4.4 fb^{-1} , and no events are observed. Limits are derived on the product of di-squark production cross section and decay chain branching fraction squared, in a SUGRA scenario where the lightest neutralino produced in the primary-squark decay undergoes an R -parity violating decay into a muon and two quarks. The limits are reported as a function of the neutralino lifetime and for a range of neutralino masses and velocities, which are the factors with greatest impact on the reconstruction efficiency. Limits for a variety of other models can thus be approximated from these results, based on the neutralino mass and velocity distribution in a given model. Comparing to the results of the previous analysis reported in [16], for lifetimes $c\tau < 100\text{mm}$, the limits presented here are somewhat less stringent than could be expected from the factor ≈ 130 increase in integrated luminosity, as a result of tighter trigger and offline muon selection requirements. For longer lifetimes, these factors are more than outweighed by the increase in efficiency afforded by re-tracking, so the limits are somewhat better than would be expected by simple scaling according to the integrated luminosity of the data samples.

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The ATLAS Collaboration

G. Aad⁴⁸, T. Abajyan²¹, B. Abbott¹¹¹, J. Abdallah¹²,
 S. Abdel Khalek¹¹⁵, A.A. Abdelalim⁴⁹, O. Abdinov¹¹,
 R. Aben¹⁰⁵, B. Abi¹¹², M. Abolins⁸⁸, O.S. AbouZeid¹⁵⁸,
 H. Abramowicz¹⁵³, H. Abreu¹³⁶, B.S. Acharya^{164a,164b},
 L. Adamczyk³⁸, D.L. Adams²⁵, T.N. Addy⁵⁶,
 J. Adelman¹⁷⁶, S. Adomeit⁹⁸, P. Adragna⁷⁵, T. Adye¹²⁹,
 S. Aefsky²³, J.A. Aguilar-Saavedra^{124b,a}, M. Agustoni¹⁷,
 M. Aharrouche⁸¹, S.P. Ahlen²², F. Ahles⁴⁸, A. Ahmad¹⁴⁸,
 M. Ahsan⁴¹, G. Aielli^{133a,133b}, T. Akdogan^{19a},
 T.P.A. Åkesson⁷⁹, G. Akimoto¹⁵⁵, A.V. Akimov⁹⁴,
 M.S. Alam², M.A. Alam⁷⁶, J. Albert¹⁶⁹, S. Albrand⁵⁵,
 M. Aleksa³⁰, I.N. Aleksandrov⁶⁴, F. Alessandria^{89a},
 C. Alexa^{26a}, G. Alexander¹⁵³, G. Alexandre⁴⁹,
 T. Alexopoulos¹⁰, M. Alhroob^{164a,164c}, M. Aliev¹⁶,
 G. Alimonti^{89a}, J. Alison¹²⁰, B.M.M. Allbrooke¹⁸,
 P.P. Allport⁷³, S.E. Allwood-Spiers⁵³, J. Almond⁸²,
 A. Aloisio^{102a,102b}, R. Alon¹⁷², A. Alonso⁷⁹, F. Alonso⁷⁰,
 A. Altheimer³⁵, B. Alvarez Gonzalez⁸⁸,
 M.G. Alviggi^{102a,102b}, K. Amako⁶⁵, C. Amelung²³,
 V.V. Ammosov^{128,*}, S.P. Amor Dos Santos^{124a},
 A. Amorim^{124a,b}, N. Amram¹⁵³, C. Anastopoulos³⁰,
 L.S. Ancu¹⁷, N. Andari¹¹⁵, T. Andeen³⁵, C.F. Anders^{58b},
 G. Anders^{58a}, K.J. Anderson³¹, A. Andreazza^{89a,89b},
 V. Andrej^{58a}, M-L. Andrieux⁵⁵, X.S. Anduaga⁷⁰,
 S. Angelidakis⁹, P. Anger⁴⁴, A. Angerami³⁵,
 F. Anghinolfi³⁰, A. Anisenkov¹⁰⁷, N. Anjos^{124a},
 A. Annovi⁴⁷, A. Antonaki⁹, M. Antonelli⁴⁷,
 A. Antonov⁹⁶, J. Antos^{144b}, F. Anulli^{132a}, M. Aoki¹⁰¹,
 S. Aoun⁸³, L. Aperio Bella⁵, R. Apolle^{118,c},
 G. Arabidze⁸⁸, I. Aracena¹⁴³, Y. Arai⁶⁵, A.T.H. Arce⁴⁵,
 S. Arfaoui¹⁴⁸, J-F. Arguin⁹³, E. Arik^{19a,*}, M. Arik^{19a},
 A.J. Armbruster⁸⁷, O. Arnaez⁸¹, V. Arnal⁸⁰,
 C. Arnault¹¹⁵, A. Artamonov⁹⁵, G. Artoni^{132a,132b},
 D. Arutinov²¹, S. Asai¹⁵⁵, S. Ask²⁸, B. Åsman^{146a,146b},
 L. Asquith⁶, K. Assamagan²⁵, A. Astbury¹⁶⁹,
 M. Atkinson¹⁶⁵, B. Aubert⁵, E. Auge¹¹⁵, K. Augsten¹²⁷,
 M. Aourousseau^{145a}, G. Avolio³⁰, R. Avramidou¹⁰,
 D. Axen¹⁶⁸, G. Azuelos^{93,d}, Y. Azuma¹⁵⁵, M.A. Baak³⁰,
 G. Baccaglioni^{89a}, C. Bacci^{134a,134b}, A.M. Bach¹⁵,
 H. Bachacou¹³⁶, K. Bachas³⁰, M. Backes⁴⁹,
 M. Backhaus²¹, J. Backus Mayes¹⁴³, E. Badescu^{26a},
 P. Bagnaia^{132a,132b}, S. Bahinipati³, Y. Bai^{33a},
 D.C. Bailey¹⁵⁸, T. Bain¹⁵⁸, J.T. Baines¹²⁹,
 O.K. Baker¹⁷⁶, M.D. Baker²⁵, S. Baker⁷⁷, P. Balek¹²⁶,
 E. Banas³⁹, P. Banerjee⁹³, Sw. Banerjee¹⁷³, D. Banfi³⁰,
 A. Bangert¹⁵⁰, V. Bansal¹⁶⁹, H.S. Bansil¹⁸, L. Barak¹⁷²,
 S.P. Baranov⁹⁴, A. Barbaro Galtieri¹⁵, T. Barber⁴⁸,
 E.L. Barberio⁸⁶, D. Barberis^{50a,50b}, M. Barbero²¹,
 D.Y. Bardin⁶⁴, T. Barillari⁹⁹, M. Barisonzi¹⁷⁵,
 T. Barklow¹⁴³, N. Barlow²⁸, B.M. Barnett¹²⁹,
 R.M. Barnett¹⁵, A. Baroncelli^{134a}, G. Barone⁴⁹,
 A.J. Barr¹¹⁸, F. Barreiro⁸⁰,
 J. Barreiro Guimarães da Costa⁵⁷, P. Barrillon¹¹⁵,
 R. Bartoldus¹⁴³, A.E. Barton⁷¹, V. Bartsch¹⁴⁹,
 A. Basye¹⁶⁵, R.L. Bates⁵³, L. Batkova^{144a}, J.R. Batley²⁸,
 A. Battaglia¹⁷, M. Battistin³⁰, F. Bauer¹³⁶,
 H.S. Bawa^{143,e}, S. Beale⁹⁸, T. Beau⁷⁸,
 P.H. Beauchemin¹⁶¹, R. Beccherle^{50a}, P. Bechtel²¹,
 H.P. Beck¹⁷, A.K. Becker¹⁷⁵, S. Becker⁹⁸,
 M. Beckingham¹³⁸, K.H. Becks¹⁷⁵, A.J. Beddall^{19c},
 A. Beddall^{19c}, S. Bedikian¹⁷⁶, V.A. Bednyakov⁶⁴,
 C.P. Bee⁸³, L.J. Beemster¹⁰⁵, M. Begel²⁵,
 S. Behar Harpaz¹⁵², P.K. Behera⁶², M. Beimforde⁹⁹,
 C. Belanger-Champagne⁸⁵, P.J. Bell⁴⁹, W.H. Bell⁴⁹,
 G. Bella¹⁵³, L. Bellagamba^{20a}, M. Bellomo³⁰,
 A. Belloni⁵⁷, O. Beloborodova^{107,f}, K. Belotskiy⁹⁶,
 O. Beltramello³⁰, O. Benary¹⁵³, D. Benchehroun^{135a},
 K. Bendtz^{146a,146b}, N. Benekos¹⁶⁵, Y. Benhammou¹⁵³,
 E. Benhar Noccioli⁴⁹, J.A. Benitez Garcia^{159b},
 D.P. Benjamin⁴⁵, M. Benoit¹¹⁵, J.R. Bensinger²³,
 K. Benslama¹³⁰, S. Bentvelsen¹⁰⁵, D. Berge³⁰,
 E. Bergeas Kuutmann⁴², N. Berger⁵, F. Berghaus¹⁶⁹,
 E. Berglund¹⁰⁵, J. Beringer¹⁵, P. Bernat⁷⁷,
 R. Bernhard⁴⁸, C. Bernius²⁵, T. Berry⁷⁶, C. Bertella⁸³,
 A. Bertin^{20a,20b}, F. Bertolucci^{122a,122b},
 M.I. Besana^{89a,89b}, G.J. Besjes¹⁰⁴, N. Besson¹³⁶,
 S. Bethke⁹⁹, W. Bhimji⁴⁶, R.M. Bianchi³⁰,
 L. Bianchini²³, M. Bianco^{72a,72b}, O. Biebel⁹⁸,
 S.P. Bieniek⁷⁷, K. Bierwagen⁵⁴, J. Biesiada¹⁵,
 M. Biglietti^{134a}, H. Bilokon⁴⁷, M. Bindi^{20a,20b},
 S. Binet¹¹⁵, A. Bingul^{19c}, C. Bini^{132a,132b}, C. Biscarat¹⁷⁸,
 B. Bittner⁹⁹, K.M. Black²², R.E. Blair⁶,
 J.-B. Blanchard¹³⁶, G. Blanchot³⁰, T. Blazek^{144a},
 I. Bloch⁴², C. Blocker²³, J. Blocki³⁹, A. Blondel⁴⁹,
 W. Blum⁸¹, U. Blumenschein⁵⁴, G.J. Bobbink¹⁰⁵,
 V.B. Bobrovnikov¹⁰⁷, S.S. Bocchetta⁷⁹, A. Bocci⁴⁵,
 C.R. Boddy¹¹⁸, M. Boehler⁴⁸, J. Boek¹⁷⁵, N. Boelaert³⁶,
 J.A. Bogaerts³⁰, A. Bogdanchikov¹⁰⁷, A. Bogouch^{90,*},
 C. Bohm^{146a}, J. Bohm¹²⁵, V. Boisvert⁷⁶, T. Bold³⁸,
 V. Boldea^{26a}, N.M. Bolnet¹³⁶, M. Bomben⁷⁸, M. Bona⁷⁵,
 M. Boonekamp¹³⁶, S. Bordon⁷⁸, C. Borer¹⁷,
 A. Borisov¹²⁸, G. Borissov⁷¹, I. Borjanovic^{13a}, M. Borri⁸²,
 S. Borroni⁸⁷, J. Bortfeldt⁹⁸, V. Bortolotto^{134a,134b},
 K. Bos¹⁰⁵, D. Boscherini^{20a}, M. Bosman¹²,
 H. Boterenbrood¹⁰⁵, J. Bouchami⁹³, J. Boudreau¹²³,
 E.V. Bouhova-Thacker⁷¹, D. Boumediene³⁴,
 C. Bourdarios¹¹⁵, N. Bousson⁸³, A. Boveia³¹, J. Boyd³⁰,
 I.R. Boyko⁶⁴, I. Bozovic-Jelisavcic^{13b}, J. Bracinik¹⁸,
 P. Branchini^{134a}, A. Brandt⁸, G. Brandt¹¹⁸, O. Brandt⁵⁴,
 U. Bratzler¹⁵⁶, B. Brau⁸⁴, J.E. Brau¹¹⁴, H.M. Braun^{175,*},
 S.F. Brazzale^{164a,164c}, B. Brelier¹⁵⁸, J. Bremer³⁰,
 K. Brendlinger¹²⁰, R. Brenner¹⁶⁶, S. Bressler¹⁷²,
 D. Britton⁵³, F.M. Brochu²⁸, I. Brock²¹, R. Brock⁸⁸,
 F. Broggi^{89a}, C. Bromberg⁸⁸, J. Bronner⁹⁹,
 G. Brooijmans³⁵, T. Brooks⁷⁶, W.K. Brooks^{32b},
 G. Brown⁸², H. Brown⁸, P.A. Bruckman de Renstrom³⁹,
 D. Bruncko^{144b}, R. Bruneliere⁴⁸, S. Brunet⁶⁰,
 A. Bruni^{20a}, G. Bruni^{20a}, M. Bruschi^{20a}, T. Buanes¹⁴,
 Q. Buat⁵⁵, F. Bucci⁴⁹, J. Buchanan¹¹⁸, P. Buchholz¹⁴¹,
 R.M. Buckingham¹¹⁸, A.G. Buckley⁴⁶, S.I. Buda^{26a},
 I.A. Budagov⁶⁴, B. Budick¹⁰⁸, V. Büscher⁸¹, L. Bugge¹¹⁷,
 O. Bulekov⁹⁶, A.C. Bundock⁷³, M. Bunse⁴³, T. Buran¹¹⁷,

H. Burckhart³⁰, S. Burdin⁷³, T. Burgess¹⁴, S. Burke¹²⁹,
 E. Busato³⁴, P. Bussey⁵³, C.P. Buszello¹⁶⁶, B. Butler¹⁴³,
 J.M. Butler²², C.M. Buttar⁵³, J.M. Butterworth⁷⁷,
 W. Buttinger²⁸, M. Byszewski³⁰, S. Cabrera Urbán¹⁶⁷,
 D. Caforio^{20a,20b}, O. Cakir^{4a}, P. Calafiura¹⁵,
 G. Calderini⁷⁸, P. Calfayan⁹⁸, R. Calkins¹⁰⁶,
 L.P. Caloba^{24a}, R. Caloi^{132a,132b}, D. Calvet³⁴,
 S. Calvet³⁴, R. Camacho Toro³⁴, P. Camarri^{133a,133b},
 D. Cameron¹¹⁷, L.M. Caminada¹⁵,
 R. Caminal Armadans¹², S. Campana³⁰,
 M. Campanelli⁷⁷, V. Canale^{102a,102b}, F. Canelli³¹,
 A. Canepa^{159a}, J. Cantero⁸⁰, R. Cantrill⁷⁶,
 L. Capasso^{102a,102b}, M.D.M. Capeans Garrido³⁰,
 I. Caprini^{26a}, M. Caprini^{26a}, D. Capriotti⁹⁹,
 M. Capua^{37a,37b}, R. Caputo⁸¹, R. Cardarelli^{133a},
 T. Carli³⁰, G. Carlino^{102a}, L. Carminati^{89a,89b},
 B. Caron⁸⁵, S. Caron¹⁰⁴, E. Carquin^{32b},
 G.D. Carrillo-Montoya¹⁷³, A.A. Carter⁷⁵, J.R. Carter²⁸,
 J. Carvalho^{124a,g}, D. Casadei¹⁰⁸, M.P. Casado¹²,
 M. Cascella^{122a,122b}, C. Caso^{50a,50b,*},
 A.M. Castaneda Hernandez^{173,h},
 E. Castaneda-Miranda¹⁷³, V. Castillo Gimenez¹⁶⁷,
 N.F. Castro^{124a}, G. Cataldi^{72a}, P. Catastini⁵⁷,
 A. Catinaccio³⁰, J.R. Catmore³⁰, A. Cattai³⁰,
 G. Cattani^{133a,133b}, S. Caughron⁸⁸, V. Cavaliere¹⁶⁵,
 P. Cavalleri⁷⁸, D. Cavalli^{89a}, M. Cavalli-Sforza¹²,
 V. Cavasinni^{122a,122b}, F. Ceradini^{134a,134b},
 A.S. Cerqueira^{24b}, A. Cerri³⁰, L. Cerrito⁷⁵, F. Cerutti⁴⁷,
 S.A. Cetin^{19b}, A. Chafaq^{135a}, D. Chakraborty¹⁰⁶,
 I. Chalupkova¹²⁶, K. Chan³, P. Chang¹⁶⁵, B. Chapleau⁸⁵,
 J.D. Chapman²⁸, J.W. Chapman⁸⁷, E. Chareyre⁷⁸,
 D.G. Charlton¹⁸, V. Chavda⁸², C.A. Chavez Barajas³⁰,
 S. Cheatham⁸⁵, S. Chekanov⁶, S.V. Chekulaev^{159a},
 G.A. Chelkov⁶⁴, M.A. Chelstowska¹⁰⁴, C. Chen⁶³,
 H. Chen²⁵, S. Chen^{33c}, X. Chen¹⁷³, Y. Chen³⁵,
 Y. Cheng³¹, A. Cheplakov⁶⁴,
 R. Cherkaoui El Moursli^{135e}, V. Chernyatin²⁵, E. Cheu⁷,
 S.L. Cheung¹⁵⁸, L. Chevalier¹³⁶, G. Chiefari^{102a,102b},
 L. Chikovani^{51a,*}, J.T. Childers³⁰, A. Chilingarov⁷¹,
 G. Chioldini^{72a}, A.S. Chisholm¹⁸, R.T. Chislett⁷⁷,
 A. Chitan^{26a}, M.V. Chizhov⁶⁴, G. Choudalakis³¹,
 S. Chouridou¹³⁷, I.A. Christidi⁷⁷, A. Christov⁴⁸,
 D. Chromek-Burckhart³⁰, M.L. Chu¹⁵¹, J. Chudoba¹²⁵,
 G. Ciapetti^{132a,132b}, A.K. Ciftci^{4a}, R. Ciftci^{4a},
 D. Cinca³⁴, V. Cindro⁷⁴, C. Ciocca^{20a,20b}, A. Ciocio¹⁵,
 M. Cirilli⁸⁷, P. Cirkovic^{13b}, Z.H. Citron¹⁷²,
 M. Citterio^{89a}, M. Ciubancan^{26a}, A. Clark⁴⁹,
 P.J. Clark⁴⁶, R.N. Clarke¹⁵, W. Cleland¹²³,
 J.C. Clemens⁸³, B. Clement⁵⁵, C. Clement^{146a,146b},
 Y. Coadou⁸³, M. Cobal^{164a,164c}, A. Coccaro¹³⁸,
 J. Cochran⁶³, L. Coffey²³, J.G. Cogan¹⁴³,
 J. Coggeshall¹⁶⁵, E. Cogneras¹⁷⁸, J. Colas⁵, S. Cole¹⁰⁶,
 A.P. Colijn¹⁰⁵, N.J. Collins¹⁸, C. Collins-Tooth⁵³,
 J. Collot⁵⁵, T. Colombo^{119a,119b}, G. Colon⁸⁴,
 G. Compostella⁹⁹, P. Conde Muino^{124a}, E. Coniavitis¹⁶⁶,
 M.C. Conidi¹², S.M. Consonni^{89a,89b}, V. Consorti⁴⁸,
 S. Constantinescu^{26a}, C. Conta^{119a,119b}, G. Conti⁵⁷,
 F. Conventi^{102a,i}, M. Cooke¹⁵, B.D. Cooper⁷⁷,
 A.M. Cooper-Sarkar¹¹⁸, K. Copic¹⁵, T. Cornelissen¹⁷⁵,
 M. Corradi^{20a}, F. Corriveau^{85,j}, A. Cortes-Gonzalez¹⁶⁵,
 G. Cortiana⁹⁹, G. Costa^{89a}, M.J. Costa¹⁶⁷,
 D. Costanzo¹³⁹, D. Côté³⁰, L. Courneyea¹⁶⁹, G. Cowan⁷⁶,
 C. Cowden²⁸, B.E. Cox⁸², K. Cranmer¹⁰⁸,
 F. Crescioli^{122a,122b}, M. Cristinziani²¹, G. Crosetti^{37a,37b},
 S. Crépe-Renaudin⁵⁵, C.-M. Cuciuc^{26a},
 C. Cuenca Almenar¹⁷⁶, T. Cuhadar Donszelmann¹³⁹,
 J. Cummings¹⁷⁶, M. Curatolo⁴⁷, C.J. Curtis¹⁸,
 C. Cuthbert¹⁵⁰, P. Cwetanski⁶⁰, H. Cziri¹⁴¹,
 P. Czodrowski⁴⁴, Z. Czyczula¹⁷⁶, S. D'Auria⁵³,
 M. D'Onofrio⁷³, A. D'Orazio^{132a,132b},
 M.J. Da Cunha Sargedas De Sousa^{124a}, C. Da Via⁸²,
 W. Dabrowski³⁸, A. Dafinca¹¹⁸, T. Dai⁸⁷,
 C. Dallapiccola⁸⁴, M. Dam³⁶, M. Dameri^{50a,50b},
 D.S. Damiani¹³⁷, H.O. Danielsson³⁰, V. Dao⁴⁹,
 G. Darbo^{50a}, G.L. Darlea^{26b}, J.A. Dassoulas⁴²,
 W. Davey²¹, T. Davidek¹²⁶, N. Davidson⁸⁶,
 R. Davidson⁷¹, E. Davies^{118,c}, M. Davies⁹³,
 O. Davignon⁷⁸, A.R. Davison⁷⁷, Y. Davygora^{58a},
 E. Dawe¹⁴², I. Dawson¹³⁹, R.K. Daya-Ishmukhametova²³,
 K. De⁸, R. de Asmundis^{102a}, S. De Castro^{20a,20b},
 S. De Cecco⁷⁸, J. de Graat⁹⁸, N. De Groot¹⁰⁴,
 P. de Jong¹⁰⁵, C. De La Taille¹¹⁵, H. De la Torre⁸⁰,
 F. De Lorenzi⁶³, L. de Mora⁷¹, L. De Nooij¹⁰⁵,
 D. De Pedis^{132a}, A. De Salvo^{132a}, U. De Sanctis^{164a,164c},
 A. De Santo¹⁴⁹, J.B. De Vivie De Regie¹¹⁵,
 G. De Zorzi^{132a,132b}, W.J. Dearnaley⁷¹, R. Debbe²⁵,
 C. Debenedetti⁴⁶, B. Dechenaux⁵⁵, D.V. Dedovich⁶⁴,
 J. Degenhardt¹²⁰, J. Del Peso⁸⁰, T. Del Prete^{122a,122b},
 T. Delemontex⁵⁵, M. Deliyergiyev⁷⁴, A. Dell'Acqua³⁰,
 L. Dell'Asta²², M. Della Pietra^{102a,i},
 D. della Volpe^{102a,102b}, M. Delmastro⁵, P.A. Delsart⁵⁵,
 C. Deluca¹⁰⁵, S. Demers¹⁷⁶, M. Demichev⁶⁴,
 B. Demirkoz^{12,k}, J. Deng¹⁶³, S.P. Denisov¹²⁸,
 D. Derendarz³⁹, J.E. Derkaoui^{135d}, F. Derue⁷⁸,
 P. Dervan⁷³, K. Desch²¹, E. Devetak¹⁴⁸,
 P.O. Deviveiros¹⁰⁵, A. Dewhurst¹²⁹, B. DeWilde¹⁴⁸,
 S. Dhaliwal¹⁵⁸, R. Dhullipudi^{25,l}, A. Di Ciaccio^{133a,133b},
 L. Di Ciaccio⁵, C. Di Donato^{102a,102b}, A. Di Girolamo³⁰,
 B. Di Girolamo³⁰, S. Di Luise^{134a,134b}, A. Di Mattia¹⁷³,
 B. Di Micco³⁰, R. Di Nardo⁴⁷, A. Di Simone^{133a,133b},
 R. Di Sipio^{20a,20b}, M.A. Diaz^{32a}, E.B. Diehl⁸⁷,
 J. Dietrich⁴², T.A. Dietzsch^{58a}, S. Diglio⁸⁶,
 K. Dindar Yagci⁴⁰, J. Dingfelder²¹, F. Dinut^{26a},
 C. Dionisi^{132a,132b}, P. Dita^{26a}, S. Dita^{26a}, F. Dittus³⁰,
 F. Djama⁸³, T. Djobava^{51b}, M.A.B. do Vale^{24c},
 A. Do Valle Wemans^{124a,m}, T.K.O. Doan⁵, M. Dobbs⁸⁵,
 D. Dobos³⁰, E. Dobson^{30,n}, J. Dodd³⁵, C. Doglioni⁴⁹,
 T. Doherty⁵³, Y. Doi^{65,*}, J. Dolejsi¹²⁶, I. Dolenc⁷⁴,
 Z. Dolezal¹²⁶, B.A. Dolgoshein^{96,*}, T. Dohmae¹⁵⁵,
 M. Donadelli^{24d}, J. Donini³⁴, J. Dopke³⁰, A. Doria^{102a},
 A. Dos Anjos¹⁷³, A. Dotti^{122a,122b}, M.T. Dova⁷⁰,
 A.D. Doxiadis¹⁰⁵, A.T. Doyle⁵³, N. Dressnandt¹²⁰,
 M. Dris¹⁰, J. Dubbert⁹⁹, S. Dube¹⁵, E. Duchovni¹⁷²,
 G. Duckeck⁹⁸, D. Duda¹⁷⁵, A. Dudarev³⁰, F. Dudziak⁶³,

M. Dührssen³⁰, I.P. Duerdoth⁸², L. Duflot¹¹⁵,
M-A. Dufour⁸⁵, L. Duguid⁷⁶, M. Dunford^{58a},
H. Duran Yildiz^{4a}, R. Duxfield¹³⁹, M. Dwuznik³⁸,
F. Dydak³⁰, M. Düren⁵², W.L. Ebenstein⁴⁵, J. Ebke⁹⁸,
S. Eckweiler⁸¹, K. Edmonds⁸¹, W. Edson²,
C.A. Edwards⁷⁶, N.C. Edwards⁵³, W. Ehrenfeld⁴²,
T. Eifert¹⁴³, G. Eigen¹⁴, K. Einsweiler¹⁵,
E. Eisenhandler⁷⁵, T. Ekelof¹⁶⁶, M. El Kacimi^{135c},
M. Ellert¹⁶⁶, S. Elles⁵, F. Ellinghaus⁸¹, K. Ellis⁷⁵,
N. Ellis³⁰, J. Elmsheuser⁹⁸, M. Elsing³⁰,
D. Emeljanov¹²⁹, R. Engelmann¹⁴⁸, A. Engl⁹⁸,
B. Epp⁶¹, J. Erdmann⁵⁴, A. Ereditato¹⁷, D. Eriksson^{146a},
J. Ernst², M. Ernst²⁵, J. Ernwein¹³⁶, D. Errede¹⁶⁵,
S. Errede¹⁶⁵, E. Ertel⁸¹, M. Escalier¹¹⁵, H. Esch⁴³,
C. Escobar¹²³, X. Espinal Curull¹², B. Esposito⁴⁷,
F. Etienne⁸³, A.I. Etievre¹³⁶, E. Etzion¹⁵³,
D. Evangelakou⁵⁴, H. Evans⁶⁰, L. Fabbri^{20a,20b},
C. Fabre³⁰, R.M. Fakhruddinov¹²⁸, S. Falciano^{132a},
Y. Fang¹⁷³, M. Fanti^{89a,89b}, A. Farbin⁸, A. Farilla^{134a},
J. Farley¹⁴⁸, T. Farooque¹⁵⁸, S. Farrell¹⁶³,
S.M. Farrington¹⁷⁰, P. Farthouat³⁰, F. Fassi¹⁶⁷,
P. Fassnacht³⁰, D. Fassouliotis⁹, B. Fatholahzadeh¹⁵⁸,
A. Favareto^{89a,89b}, L. Fayard¹¹⁵, S. Fazio^{37a,37b},
R. Febbraro³⁴, P. Federic^{144a}, O.L. Fedin¹²¹,
W. Fedorko⁸⁸, M. Fehling-Kaschek⁴⁸, L. Felgioni⁸³,
D. Fellmann⁶, C. Feng^{33d}, E.J. Feng⁶, A.B. Fenyuk¹²⁸,
J. Ferencei^{144b}, W. Fernando⁶, S. Ferrag⁵³,
J. Ferrando⁵³, V. Ferrara⁴², A. Ferrari¹⁶⁶, P. Ferrari¹⁰⁵,
R. Ferrari^{119a}, D.E. Ferreira de Lima⁵³, A. Ferrer¹⁶⁷,
D. Ferrere⁴⁹, C. Ferretti⁸⁷, A. Ferretto Parodi^{50a,50b},
M. Fiascaris³¹, F. Fiedler⁸¹, A. Filipčić⁷⁴, F. Filthaut¹⁰⁴,
M. Fincke-Keeler¹⁶⁹, M.C.N. Fiolhais^{124a,g}, L. Fiorini¹⁶⁷,
A. Firan⁴⁰, G. Fischer⁴², M.J. Fisher¹⁰⁹, M. Flechl⁴⁸,
I. Fleck¹⁴¹, J. Fleckner⁸¹, P. Fleischmann¹⁷⁴,
S. Fleischmann¹⁷⁵, T. Flick¹⁷⁵, A. Floderus⁷⁹,
L.R. Flores Castillo¹⁷³, M.J. Flowerdew⁹⁹,
T. Fonseca Martin¹⁷, A. Formica¹³⁶, A. Forti⁸²,
D. Fortin^{159a}, D. Fournier¹¹⁵, A.J. Fowler⁴⁵, H. Fox⁷¹,
P. Francavilla¹², M. Franchini^{20a,20b},
S. Franchino^{119a,119b}, D. Francis³⁰, T. Frank¹⁷²,
M. Franklin⁵⁷, S. Franz³⁰, M. Fraternali^{119a,119b},
S. Fratina¹²⁰, S.T. French²⁸, C. Friedrich⁴²,
F. Friedrich⁴⁴, R. Froeschl³⁰, D. Froidevaux³⁰,
J.A. Frost²⁸, C. Fukunaga¹⁵⁶, E. Fullana Torregrosa³⁰,
B.G. Fulson¹⁴³, J. Fuster¹⁶⁷, C. Gabaldon³⁰,
O. Gabizon¹⁷², T. Gadfort²⁵, S. Gadomski⁴⁹,
G. Gagliardi^{50a,50b}, P. Gagnon⁶⁰, C. Galea⁹⁸,
B. Galhardo^{124a}, E.J. Gallas¹¹⁸, V. Gallo¹⁷,
B.J. Gallop¹²⁹, P. Gallus¹²⁵, K.K. Gan¹⁰⁹, Y.S. Gao^{143,e},
A. Gaponenko¹⁵, F. Garberson¹⁷⁶, M. Garcia-Sciveres¹⁵,
C. García¹⁶⁷, J.E. García Navarro¹⁶⁷, R.W. Gardner³¹,
N. Garelli³⁰, H. Garitaonandia¹⁰⁵, V. Garonne³⁰,
C. Gatti⁴⁷, G. Gaudio^{119a}, B. Gaur¹⁴¹, L. Gauthier¹³⁶,
P. Gauzzi^{132a,132b}, I.L. Gavrilenko⁹⁴, C. Gay¹⁶⁸,
G. Gaycken²¹, E.N. Gazis¹⁰, P. Ge^{33d}, Z. Gece¹⁶⁸,
C.N.P. Gee¹²⁹, D.A.A. Geerts¹⁰⁵, Ch. Geich-Gimbel²¹,
K. Gellerstedt^{146a,146b}, C. Gemme^{50a}, A. Gemmel⁵³,
M.H. Genest⁵⁵, S. Gentile^{132a,132b}, M. George⁵⁴,
S. George⁷⁶, P. Gerlach¹⁷⁵, A. Gershon¹⁵³,
C. Geweniger^{58a}, H. Ghazlane^{135b}, N. Ghodbane³⁴,
B. Giacobbe^{20a}, S. Giagu^{132a,132b}, V. Giakoumopoulou⁹,
V. Giangiobbe¹², F. Gianotti³⁰, B. Gibbard²⁵,
A. Gibson¹⁵⁸, S.M. Gibson³⁰, M. Gilchriese¹⁵,
D. Gillberg²⁹, A.R. Gillman¹²⁹, D.M. Gingrich^{3,d},
J. Ginzburg¹⁵³, N. Giokaris⁹, M.P. Giordani^{164c},
R. Giordano^{102a,102b}, F.M. Giorgi¹⁶, P. Giovannini⁹⁹,
P.F. Giraud¹³⁶, D. Giugni^{89a}, M. Giunta⁹³, P. Giusti^{20a},
B.K. Gjelsten¹¹⁷, L.K. Gladilin⁹⁷, C. Glasman⁸⁰,
J. Glatzer²¹, A. Glazov⁴², K.W. Glitza¹⁷⁵, G.L. Glonti⁶⁴,
J.R. Goddard⁷⁵, J. Godfrey¹⁴², J. Godlewski³⁰,
M. Goebel⁴², T. Göpfert⁴⁴, C. Goeringer⁸¹,
C. Gössling⁴³, S. Goldfarb⁸⁷, T. Golling¹⁷⁶,
A. Gomes^{124a,b}, L.S. Gomez Fajardo⁴², R. Gonçalves⁷⁶,
J. Goncalves Pinto Firmino Da Costa⁴², L. Gonella²¹,
S. González de la Hoz¹⁶⁷, G. Gonzalez Parra¹²,
M.L. Gonzalez Silva²⁷, S. Gonzalez-Sevilla⁴⁹,
J.J. Goodson¹⁴⁸, L. Goossens³⁰, P.A. Gorbounov⁹⁵,
H.A. Gordon²⁵, I. Gorelov¹⁰³, G. Gorfine¹⁷⁵, B. Gorini³⁰,
E. Gorini^{72a,72b}, A. Gorišek⁷⁴, E. Gornicki³⁹,
B. Gosdzik⁴², A.T. Goshaw⁶, M. Gosselink¹⁰⁵,
M.I. Gostkin⁶⁴, I. Gough Eschrich¹⁶³, M. Goughri^{135a},
D. Goujdami^{135c}, M.P. Goulette⁴⁹, A.G. Goussiou¹³⁸,
C. Goy⁵, S. Gozpinar²³, I. Grabowska-Bold³⁸,
P. Grafström^{20a,20b}, K.-J. Grahn⁴², E. Gramstad¹¹⁷,
F. Grancagnolo^{72a}, S. Grancagnolo¹⁶, V. Grassi¹⁴⁸,
V. Gratchev¹²¹, N. Grau³⁵, H.M. Gray³⁰, J.A. Gray¹⁴⁸,
E. Graziani^{134a}, O.G. Grebenyuk¹²¹, T. Greenshaw⁷³,
Z.D. Greenwood^{25,l}, K. Gregersen³⁶, I.M. Gregor⁴²,
P. Grenier¹⁴³, J. Griffiths⁸, N. Grigalashvili⁶⁴,
A.A. Grillo¹³⁷, S. Grinstein¹², Ph. Gris³⁴,
Y.V. Grishkevich⁹⁷, J.-F. Grivaz¹¹⁵, E. Gross¹⁷²,
J. Grosse-Knetter⁵⁴, J. Groth-Jensen¹⁷², K. Grybel¹⁴¹,
D. Guest¹⁷⁶, C. Guicheney³⁴, S. Guindon⁵⁴, U. Gul⁵³,
J. Gunther¹²⁵, B. Guo¹⁵⁸, J. Guo³⁵, P. Gutierrez¹¹¹,
N. Guttman¹⁵³, O. Gutzwiller¹⁷³, C. Guyot¹³⁶,
C. Gwenlan¹¹⁸, C.B. Gwilliam⁷³, A. Haas¹⁰⁸, S. Haas³⁰,
C. Haber¹⁵, H.K. Hadavand⁸, D.R. Hadley¹⁸,
P. Haefner²¹, F. Hahn³⁰, S. Haider³⁰, Z. Hajduk³⁹,
H. Hakobyan¹⁷⁷, D. Hall¹¹⁸, K. Hamacher¹⁷⁵,
P. Hamal¹¹³, K. Hamano⁸⁶, M. Hamer⁵⁴,
A. Hamilton^{145b,o}, S. Hamilton¹⁶¹, L. Han^{33b},
K. Hanagaki¹¹⁶, K. Hanawa¹⁶⁰, M. Hance¹⁵, C. Handel⁸¹,
P. Hanke^{58a}, J.R. Hansen³⁶, J.B. Hansen³⁶,
J.D. Hansen³⁶, P.H. Hansen³⁶, P. Hansson¹⁴³,
K. Hara¹⁶⁰, G.A. Hare¹³⁷, T. Harenberg¹⁷⁵,
S. Harkusha⁹⁰, D. Harper⁸⁷, R.D. Harrington⁴⁶,
O.M. Harris¹³⁸, J. Hartert⁴⁸, F. Hartjes¹⁰⁵,
T. Haruyama⁶⁵, A. Harvey⁵⁶, S. Hasegawa¹⁰¹,
Y. Hasegawa¹⁴⁰, S. Hassani¹³⁶, S. Haug¹⁷,
M. Hauschild³⁰, R. Hauser⁸⁸, M. Havranek²¹,
C.M. Hawkes¹⁸, R.J. Hawkins³⁰, A.D. Hawkins⁷⁹,
T. Hayakawa⁶⁶, T. Hayashi¹⁶⁰, D. Hayden⁷⁶,
C.P. Hays¹¹⁸, H.S. Hayward⁷³, S.J. Haywood¹²⁹,
S.J. Head¹⁸, V. Hedberg⁷⁹, L. Heelan⁸, S. Heim¹²⁰,

B. Heinemann¹⁵, S. Heisterkamp³⁶, L. Helary²²,
 C. Heller⁹⁸, M. Heller³⁰, S. Hellman^{146a,146b},
 D. Hellmich²¹, C. Helsens¹², R.C.W. Henderson⁷¹,
 M. Henke^{58a}, A. Henrichs¹⁷⁶, A.M. Henriques Correia³⁰,
 S. Henrot-Versille¹¹⁵, C. Hensel⁵⁴, T. Henß¹⁷⁵,
 C.M. Hernandez⁸, Y. Hernández Jiménez¹⁶⁷,
 R. Herrberg¹⁶, G. Herten⁴⁸, R. Hertenberger⁹⁸,
 L. Hervas³⁰, G.G. Hesketh⁷⁷, N.P. Hessey¹⁰⁵,
 E. Higón-Rodríguez¹⁶⁷, J.C. Hill²⁸, K.H. Hiller⁴²,
 S. Hillert²¹, S.J. Hillier¹⁸, I. Hinchliffe¹⁵, E. Hines¹²⁰,
 M. Hirose¹¹⁶, F. Hirsch⁴³, D. Hirschbuehl¹⁷⁵, J. Hobbs¹⁴⁸,
 N. Hod¹⁵³, M.C. Hodgkinson¹³⁹, P. Hodgson¹³⁹,
 A. Hoecker³⁰, M.R. Hoefkamp¹⁰³, J. Hoffman⁴⁰,
 D. Hoffmann⁸³, M. Hohlfield⁸¹, M. Holder¹⁴¹,
 S.O. Holmgren^{146a}, T. Holy¹²⁷, J.L. Holzbauer⁸⁸,
 T.M. Hong¹²⁰, L. Hooft van Huysduynen¹⁰⁸, S. Horner⁴⁸,
 J-Y. Hostachy⁵⁵, S. Hou¹⁵¹, A. Hoummada^{135a},
 J. Howard¹¹⁸, J. Howarth⁸², I. Hristova¹⁶, J. Hrivnac¹¹⁵,
 T. Hryn'ova⁵, P.J. Hsu⁸¹, S.-C. Hsu¹⁵, D. Hu³⁵,
 Z. Hubacek¹²⁷, F. Hubaut⁸³, F. Huegging²¹,
 A. Huettmann⁴², T.B. Huffman¹¹⁸, E.W. Hughes³⁵,
 G. Hughes⁷¹, M. Huhtinen³⁰, M. Hurwitz¹⁵,
 N. Huseynov^{64,p}, J. Huston⁸⁸, J. Huth⁵⁷, G. Iacobucci⁴⁹,
 G. Iakovidis¹⁰, M. Ibbotson⁸², I. Ibragimov¹⁴¹,
 L. Iconomidou-Fayard¹¹⁵, J. Idarraga¹¹⁵, P. Iengo^{102a},
 O. Igonkina¹⁰⁵, Y. Ikegami⁶⁵, M. Ikeno⁶⁵, D. Iliadis¹⁵⁴,
 N. Ilic¹⁵⁸, T. Ince⁹⁹, J. Inigo-Golfin³⁰, P. Ioannou⁹,
 M. Iodice^{134a}, K. Iordanidou⁹, V. Ippolito^{132a,132b},
 A. Irls Quiles¹⁶⁷, C. Isaksson¹⁶⁶, M. Ishino⁶⁷,
 M. Ishitsuka¹⁵⁷, R. Ishmukhametov¹⁰⁹, C. Issever¹¹⁸,
 S. Istin^{19a}, A.V. Ivashin¹²⁸, W. Iwanski³⁹, H. Iwasaki⁶⁵,
 J.M. Izen⁴¹, V. Izzo^{102a}, B. Jackson¹²⁰, J.N. Jackson⁷³,
 P. Jackson¹, M.R. Jaekel³⁰, V. Jain⁶⁰, K. Jakobs⁴⁸,
 S. Jakobsen³⁶, T. Jakoubek¹²⁵, J. Jakubek¹²⁷,
 D.O. Jamin¹⁵¹, D.K. Jana¹¹¹, E. Jansen⁷⁷, H. Jansen³⁰,
 A. Jantsch⁹⁹, M. Janus⁴⁸, R.C. Jared¹⁷³, G. Jarlskog⁷⁹,
 L. Jeanty⁵⁷, I. Jen-La Plante³¹, D. Jennens⁸⁶, P. Jenni³⁰,
 A.E. Loevschall-Jensen³⁶, P. Jež³⁶, S. Jézéquel⁵,
 M.K. Jha^{20a}, H. Ji¹⁷³, W. Ji⁸¹, J. Jia¹⁴⁸, Y. Jiang^{33b},
 M. Jimenez Belenguer⁴², S. Jin^{33a}, O. Jinnouchi¹⁵⁷,
 M.D. Joergensen³⁶, D. Joffe⁴⁰, M. Johansen^{146a,146b},
 K.E. Johansson^{146a}, P. Johansson¹³⁹, S. Johnert⁴²,
 K.A. Johns⁷, K. Jon-And^{146a,146b}, G. Jones¹⁷⁰,
 R.W.L. Jones⁷¹, T.J. Jones⁷³, C. Joram³⁰,
 P.M. Jorge^{124a}, K.D. Joshi⁸², J. Jovicevic¹⁴⁷, T. Jovin^{13b},
 X. Ju¹⁷³, C.A. Jung⁴³, R.M. Jungst³⁰, V. Juranek¹²⁵,
 P. Jussel⁶¹, A. Juste Rozas¹², S. Kabana¹⁷, M. Kaci¹⁶⁷,
 A. Kaczmarzka³⁹, P. Kadlecik³⁶, M. Kado¹¹⁵,
 H. Kagan¹⁰⁹, M. Kagan⁵⁷, E. Kajomovitz¹⁵²,
 S. Kalinin¹⁷⁵, L.V. Kalinovskaya⁶⁴, S. Kama⁴⁰,
 N. Kanaya¹⁵⁵, M. Kaneda³⁰, S. Kaneti²⁸, T. Kanno¹⁵⁷,
 V.A. Kantserov⁹⁶, J. Kanzaki⁶⁵, B. Kaplan¹⁰⁸,
 A. Kapliy³¹, J. Kaplon³⁰, D. Kar⁵³, M. Karagounis²¹,
 K. Karakostas¹⁰, M. Karnevskiy⁴², V. Kartvelishvili⁷¹,
 A.N. Karyukhin¹²⁸, L. Kashif¹⁷³, G. Kasieczka^{58b},
 R.D. Kass¹⁰⁹, A. Kastanas¹⁴, M. Kataoka⁵,
 Y. Kataoka¹⁵⁵, E. Katsoufis¹⁰, J. Katzy⁴², V. Kaushik⁷,
 K. Kawagoe⁶⁹, T. Kawamoto¹⁵⁵, G. Kawamura⁸¹,
 M.S. Kayl¹⁰⁵, S. Kazama¹⁵⁵, V.A. Kazanin¹⁰⁷,
 M.Y. Kazarinov⁶⁴, R. Keeler¹⁶⁹, P.T. Keener¹²⁰,
 R. Kehoe⁴⁰, M. Keil⁵⁴, G.D. Kekelidze⁶⁴, J.S. Keller¹³⁸,
 M. Kenyon⁵³, O. Kepka¹²⁵, N. Kerschen³⁰,
 B.P. Kerševan⁷⁴, S. Kersten¹⁷⁵, K. Kessoku¹⁵⁵,
 J. Keung¹⁵⁸, F. Khalil-zada¹¹, H. Khandanyan^{146a,146b},
 A. Khanov¹¹², D. Kharchenko⁶⁴, A. Khodinov⁹⁶,
 A. Khomich^{58a}, T.J. Khoo²⁸, G. Khoriali²¹,
 A. Khoroshilov¹⁷⁵, V. Khovanskiy⁹⁵, E. Khramov⁶⁴,
 J. Khubua^{51b}, H. Kim^{146a,146b}, S.H. Kim¹⁶⁰,
 N. Kimura¹⁷¹, O. Kind¹⁶, B.T. King⁷³, M. King⁶⁶,
 R.S.B. King¹¹⁸, J. Kirk¹²⁹, A.E. Kiryunin⁹⁹,
 T. Kishimoto⁶⁶, D. Kisielewska³⁸, T. Kitamura⁶⁶,
 T. Kittelmann¹²³, K. Kiuchi¹⁶⁰, E. Kladiiva^{144b},
 M. Klein⁷³, U. Klein⁷³, K. Kleinknecht⁸¹, M. Klemetti⁸⁵,
 A. Klier¹⁷², P. Klimek^{146a,146b}, A. Klimentov²⁵,
 R. Klingenberg⁴³, J.A. Klinger⁸², E.B. Klinkby³⁶,
 T. Klioutchnikova³⁰, P.F. Klok¹⁰⁴, S. Klous¹⁰⁵,
 E.-E. Kluge^{58a}, T. Kluge⁷³, P. Kluit¹⁰⁵, S. Kluth⁹⁹,
 E. Kneringer⁶¹, E.B.F.G. Knoops⁸³, A. Knue⁵⁴,
 B.R. Ko⁴⁵, T. Kobayashi¹⁵⁵, M. Kobel⁴⁴, M. Kocian¹⁴³,
 P. Kodys¹²⁶, K. Köneke³⁰, A.C. König¹⁰⁴, S. Koenig⁸¹,
 L. Köpke⁸¹, F. Koetsveld¹⁰⁴, P. Koevesarki²¹,
 T. Koffas²⁹, E. Koffeman¹⁰⁵, L.A. Kogan¹¹⁸,
 S. Kohlmann¹⁷⁵, F. Kohn⁵⁴, Z. Kohout¹²⁷, T. Kohriki⁶⁵,
 T. Koi¹⁴³, G.M. Kolachev^{107,*}, H. Kolanoski¹⁶,
 V. Kolesnikov⁶⁴, I. Koletsou^{89a}, J. Koll⁸⁸, A.A. Komar⁹⁴,
 Y. Komori¹⁵⁵, T. Kond⁶⁵, T. Kono^{42,q}, A.I. Kononov⁴⁸,
 R. Konoplich^{108,r}, N. Konstantinidis⁷⁷,
 R. Kopeliansky¹⁵², S. Koperny³⁸, K. Korcyl³⁹,
 K. Kordas¹⁵⁴, A. Korn¹¹⁸, A. Korol¹⁰⁷, I. Korolkov¹²,
 E.V. Korolkova¹³⁹, V.A. Korotkov¹²⁸, O. Kortner⁹⁹,
 S. Kortner⁹⁹, V.V. Kostyukhin²¹, S. Kotov⁹⁹,
 V.M. Kotov⁶⁴, A. Kotwal⁴⁵, C. Kourkoumelis⁹,
 V. Kouskoura¹⁵⁴, A. Koutsman^{159a}, R. Kowalewski¹⁶⁹,
 T.Z. Kowalski³⁸, W. Kozanecki¹³⁶, A.S. Kozhin¹²⁸,
 V. Kral¹²⁷, V.A. Kramarenko⁹⁷, G. Kramberger⁷⁴,
 M.W. Krasny⁷⁸, A. Krasznahorkay¹⁰⁸, J.K. Kraus²¹,
 S. Kreiss¹⁰⁸, F. Krejci¹²⁷, J. Kretzschmar⁷³, N. Krieger⁵⁴,
 P. Krieger¹⁵⁸, K. Kroeninger⁵⁴, H. Kroha⁹⁹, J. Kroll¹²⁰,
 J. Kroseberg²¹, J. Krstic^{13a}, U. Kruchonak⁶⁴,
 H. Krüger²¹, T. Kruker¹⁷, N. Krumnack⁶³,
 Z.V. Krumshteyn⁶⁴, M.K. Kruse⁴⁵, T. Kubota⁸⁶,
 S. Kuday^{4a}, S. Kuehn⁴⁸, A. Kugel^{58c}, T. Kuhl⁴²,
 D. Kuhn⁶¹, V. Kukhtin⁶⁴, Y. Kulchitsky⁹⁰,
 S. Kuleshov^{32b}, C. Kummer⁹⁸, M. Kuna⁷⁸, J. Kunkle¹²⁰,
 A. Kupco¹²⁵, H. Kurashige⁶⁶, M. Kurata¹⁶⁰,
 Y.A. Kurochkin⁹⁰, V. Kus¹²⁵, E.S. Kuwertz¹⁴⁷,
 M. Kuze¹⁵⁷, J. Kvita¹⁴², R. Kwee¹⁶, A. La Rosa⁴⁹,
 L. La Rotonda^{37a,37b}, L. Labarga⁸⁰, J. Labbe⁵,
 S. Lablak^{135a}, C. Lacasta¹⁶⁷, F. Lacava^{132a,132b},
 J. Lacey²⁹, H. Lacker¹⁶, D. Lacour⁷⁸, V.R. Lacuesta¹⁶⁷,
 E. Ladygin⁶⁴, R. Lafaye⁵, B. Laforge⁷⁸, T. Lagouri¹⁷⁶,
 S. Lai⁴⁸, E. Laisne⁵⁵, M. Lamanna³⁰, L. Lambourne⁷⁷,
 C.L. Lampen⁷, W. Lampl⁷, E. Lancon¹³⁶, U. Landgraf⁴⁸,
 M.P.J. Landon⁷⁵, V.S. Lang^{58a}, C. Lange⁴²,

A.J. Lankford¹⁶³, F. Lanni²⁵, K. Lantzsche¹⁷⁵,
 S. Laplace⁷⁸, C. Lapoire²¹, J.F. Laporte¹³⁶, T. Lari^{89a},
 A. Larner¹¹⁸, M. Lassnig³⁰, P. Laurelli⁴⁷,
 V. Lavorini^{37a,37b}, W. Lavrijsen¹⁵, P. Laycock⁷³,
 O. Le Dortz⁷⁸, E. Le Guirrec⁸³, E. Le Menedeu¹²,
 T. LeCompte⁶, F. Ledroit-Guillon⁵⁵, H. Lee¹⁰⁵,
 J.S.H. Lee¹¹⁶, S.C. Lee¹⁵¹, L. Lee¹⁷⁶, M. Lefebvre¹⁶⁹,
 M. Legendre¹³⁶, F. Legger⁹⁸, C. Leggett¹⁵,
 M. Lehmacher²¹, G. Lehmann Miotto³⁰, M.A.L. Leite^{24d},
 R. Leitner¹²⁶, D. Lellouch¹⁷², B. Lemmer⁵⁴,
 V. Lendermann^{58a}, K.J.C. Leney^{145b}, T. Lenz¹⁰⁵,
 G. Lenzen¹⁷⁵, B. Lenzi³⁰, K. Leonhardt⁴⁴,
 S. Leontsinis¹⁰, F. Lepold^{58a}, C. Leroy⁹³,
 J-R. Lessard¹⁶⁹, C.G. Lester²⁸, C.M. Lester¹²⁰,
 J. Levêque⁵, D. Levin⁸⁷, L.J. Levinson¹⁷², A. Lewis¹¹⁸,
 G.H. Lewis¹⁰⁸, A.M. Leyko²¹, M. Leyton¹⁶, B. Li⁸³,
 H. Li¹⁴⁸, H.L. Li³¹, S. Li^{33b,s}, X. Li⁸⁷, Z. Liang^{118,t},
 H. Liao³⁴, B. Liberti^{133a}, P. Lichard³⁰, M. Lichtnecker⁹⁸,
 K. Lie¹⁶⁵, W. Liebig¹⁴, C. Limbach²¹, A. Limosani⁸⁶,
 M. Limper⁶², S.C. Lin^{151,u}, F. Linde¹⁰⁵,
 J.T. Linnemann⁸⁸, E. Lipeles¹²⁰, A. Lipniacka¹⁴,
 T.M. Liss¹⁶⁵, D. Lissauer²⁵, A. Lister⁴⁹, A.M. Litke¹³⁷,
 C. Liu²⁹, D. Liu¹⁵¹, H. Liu⁸⁷, J.B. Liu⁸⁷, L. Liu⁸⁷,
 M. Liu^{33b}, Y. Liu^{33b}, M. Livan^{119a,119b},
 S.S.A. Livermore¹¹⁸, A. Lleres⁵⁵, J. Llorente Merino⁸⁰,
 S.L. Lloyd⁷⁵, E. Lobodzinska⁴², P. Loch⁷,
 W.S. Lockman¹³⁷, T. Loddenkoetter²¹, F.K. Loebinger⁸²,
 A. Loginov¹⁷⁶, C.W. Loh¹⁶⁸, T. Lohse¹⁶, K. Lohwasser⁴⁸,
 M. Lokajicek¹²⁵, V.P. Lombardo⁵, R.E. Long⁷¹,
 L. Lopes^{124a}, D. Lopez Mateos⁵⁷, J. Lorenz⁹⁸,
 N. Lorenzo Martinez¹¹⁵, M. Losada¹⁶², P. Loscutoff¹⁵,
 F. Lo Sterzo^{132a,132b}, M.J. Losty^{159a,*}, X. Lou⁴¹,
 A. Lounis¹¹⁵, K.F. Loureiro¹⁶², J. Love⁶, P.A. Love⁷¹,
 A.J. Lowe^{143,e}, F. Lu^{33a}, H.J. Lubatti¹³⁸,
 C. Luci^{132a,132b}, A. Lucotte⁵⁵, A. Ludwig⁴⁴,
 D. Ludwig⁴², I. Ludwig⁴⁸, J. Ludwig⁴⁸, F. Luehring⁶⁰,
 G. Luijckx¹⁰⁵, W. Lukas⁶¹, L. Luminari^{132a}, E. Lund¹¹⁷,
 B. Lund-Jensen¹⁴⁷, B. Lundberg⁷⁹, J. Lundberg^{146a,146b},
 O. Lundberg^{146a,146b}, J. Lundquist³⁶, M. Lungwitz⁸¹,
 D. Lynn²⁵, E. Lytken⁷⁹, H. Ma²⁵, L.L. Ma¹⁷³,
 G. Maccarrone⁴⁷, A. Macchiolo⁹⁹, B. Maček⁷⁴,
 J. Machado Miguens^{124a}, R. Mackeprang³⁶,
 R.J. Madaras¹⁵, H.J. Maddocks⁷¹, W.F. Mader⁴⁴,
 R. Maenner^{58c}, T. Maeno²⁵, P. Mättig¹⁷⁵, S. Mättig⁸¹,
 L. Magnoni¹⁶³, E. Magradze⁵⁴, K. Mahboubi⁴⁸,
 J. Mahlstedt¹⁰⁵, S. Mahmoud⁷³, G. Mahout¹⁸,
 C. Maiani¹³⁶, C. Maidantchik^{24a}, A. Maio^{124a,b},
 S. Majewski²⁵, Y. Makida⁶⁵, N. Makovec¹¹⁵, P. Mal¹³⁶,
 B. Malaescu³⁰, Pa. Malecki³⁹, P. Malecki³⁹,
 V.P. Maleev¹²¹, F. Malek⁵⁵, U. Mallik⁶², D. Malon⁶,
 C. Malone¹⁴³, S. Maltezos¹⁰, V. Malyshev¹⁰⁷,
 S. Malyukov³⁰, R. Mameghani⁹⁸, J. Mamuzic^{13b},
 A. Manabe⁶⁵, L. Mandelli^{89a}, I. Mandić⁷⁴,
 R. Mandrysch¹⁶, J. Maneira^{124a}, A. Manfredini⁹⁹,
 P.S. Manguard⁸⁸, L. Manhaes de Andrade Filho^{24b},
 J.A. Manjarres Ramos¹³⁶, A. Mann⁵⁴, P.M. Manning¹³⁷,
 A. Manousakis-Katsikakis⁹, B. Mansoulie¹³⁶,
 A. Mapelli³⁰, L. Mapelli³⁰, L. March¹⁶⁷,
 J.F. Marchand²⁹, F. Marchese^{133a,133b}, G. Marchiori⁷⁸,
 M. Marcisovsky¹²⁵, C.P. Marino¹⁶⁹, F. Marroquim^{24a},
 Z. Marshall³⁰, F.K. Martens¹⁵⁸, L.F. Marti¹⁷,
 S. Marti-Garcia¹⁶⁷, B. Martin³⁰, B. Martin⁸⁸,
 J.P. Martin⁹³, T.A. Martin¹⁸, V.J. Martin⁴⁶,
 B. Martin dit Latour⁴⁹, S. Martin-Haugh¹⁴⁹,
 M. Martinez¹², V. Martinez Outschoorn⁵⁷,
 A.C. Martyniuk¹⁶⁹, M. Marx⁸², F. Marzano^{132a},
 A. Marzin¹¹¹, L. Masetti⁸¹, T. Mashimo¹⁵⁵,
 R. Mashinistov⁹⁴, J. Masik⁸², A.L. Maslennikov¹⁰⁷,
 I. Massa^{20a,20b}, G. Massaro¹⁰⁵, N. Massol⁵,
 P. Mastrandrea¹⁴⁸, A. Mastroberardino^{37a,37b},
 T. Masubuchi¹⁵⁵, P. Matricorn¹¹⁵, H. Matsunaga¹⁵⁵,
 T. Matsushita⁶⁶, C. Mattravers^{118,c}, J. Maurer⁸³,
 S.J. Maxfield⁷³, D.A. Maximov^{107,f}, A. Mayne¹³⁹,
 R. Mazini¹⁵¹, M. Mazur²¹, L. Mazzaferro^{133a,133b},
 M. Mazzanti^{89a}, J. Mc Donald⁸⁵, S.P. Mc Kee⁸⁷,
 A. McCarn¹⁶⁵, R.L. McCarthy¹⁴⁸, T.G. McCarthy²⁹,
 N.A. McCubbin¹²⁹, K.W. McFarlane^{56,*},
 J.A. Mcfayden¹³⁹, G. Mchedlidze^{51b}, T. Mclaughlan¹⁸,
 S.J. McMahan¹²⁹, R.A. McPherson^{169,j}, A. Meade⁸⁴,
 J. Mechnich¹⁰⁵, M. Mechtel¹⁷⁵, M. Medinnis⁴²,
 R. Meera-Lebbai¹¹¹, T. Meguro¹¹⁶, S. Mehlhase³⁶,
 A. Mehta⁷³, K. Meier^{58a}, B. Meirose⁷⁹, C. Melachrinis³¹,
 B.R. Mellado Garcia¹⁷³, F. Meloni^{89a,89b},
 L. Mendoza Navas¹⁶², Z. Meng^{151,v}, A. Mengarelli^{20a,20b},
 S. Menke⁹⁹, E. Meoni¹⁶¹, K.M. Mercurio⁵⁷, P. Mermod⁴⁹,
 L. Merola^{102a,102b}, C. Meroni^{89a}, F.S. Merritt³¹,
 H. Merritt¹⁰⁹, A. Messina^{30,w}, J. Metcalfe²⁵,
 A.S. Mete¹⁶³, C. Meyer⁸¹, C. Meyer³¹, J-P. Meyer¹³⁶,
 J. Meyer¹⁷⁴, J. Meyer⁵⁴, T.C. Meyer³⁰, S. Michal³⁰,
 L. Micu^{26a}, R.P. Middleton¹²⁹, S. Migas⁷³, L. Mijović¹³⁶,
 G. Mikenberg¹⁷², M. Mikestikova¹²⁵, M. Mikuž⁷⁴,
 D.W. Miller³¹, R.J. Miller⁸⁸, W.J. Mills¹⁶⁸, C. Mills⁵⁷,
 A. Milov¹⁷², D.A. Milstead^{146a,146b}, D. Milstein¹⁷²,
 A.A. Minaenko¹²⁸, M. Miñano Moya¹⁶⁷,
 I.A. Minashvili⁶⁴, A.I. Mincer¹⁰⁸, B. Mindur³⁸,
 M. Mineev⁶⁴, Y. Ming¹⁷³, L.M. Mir¹², G. Mirabelli^{132a},
 J. Mitrevski¹³⁷, V.A. Mitsou¹⁶⁷, S. Mitsui⁶⁵,
 P.S. Miyagawa¹³⁹, J.U. Mjörnmark⁷⁹, T. Moa^{146a,146b},
 V. Moeller²⁸, K. Mönig⁴², N. Möser²¹, S. Mohapatra¹⁴⁸,
 W. Mohr⁴⁸, R. Moles-Valls¹⁶⁷, A. Molfetas³⁰, J. Monk⁷⁷,
 E. Monnier⁸³, J. Montejo Berlingen¹², F. Monticelli⁷⁰,
 S. Monzani^{20a,20b}, R.W. Moore³, G.F. Moorhead⁸⁶,
 C. Mora Herrera⁴⁹, A. Moraes⁵³, N. Morange¹³⁶,
 J. Morel⁵⁴, G. Morello^{37a,37b}, D. Moreno⁸¹,
 M. Moreno Llácer¹⁶⁷, P. Morettini^{50a}, M. Morgenstern⁴⁴,
 M. Morii⁵⁷, A.K. Morley³⁰, G. Mornacchi³⁰,
 J.D. Morris⁷⁵, L. Morvaj¹⁰¹, H.G. Moser⁹⁹,
 M. Mosidze^{51b}, J. Moss¹⁰⁹, R. Mount¹⁴³,
 E. Mountricha^{10,x}, S.V. Mouraviev^{94,*}, E.J.W. Moyse⁸⁴,
 F. Mueller^{58a}, J. Mueller¹²³, K. Mueller²¹, T.A. Müller⁹⁸,
 T. Mueller⁸¹, D. Muenstermann³⁰, Y. Munwes¹⁵³,
 W.J. Murray¹²⁹, I. Mussche¹⁰⁵, E. Musto^{102a,102b},
 A.G. Myagkov¹²⁸, M. Myska¹²⁵, O. Nackenhorst⁵⁴,
 J. Nadal¹², K. Nagai¹⁶⁰, R. Nagai¹⁵⁷, K. Nagano⁶⁵,

A. Nagarkar¹⁰⁹, Y. Nagasaka⁵⁹, M. Nagel⁹⁹,
 A.M. Nairz³⁰, Y. Nakahama³⁰, K. Nakamura¹⁵⁵,
 T. Nakamura¹⁵⁵, I. Nakano¹¹⁰, G. Nanava²¹,
 A. Napier¹⁶¹, R. Narayan^{58b}, M. Nash^{77,c},
 T. Nattermann²¹, T. Naumann⁴², G. Navarro¹⁶²,
 H.A. Neal⁸⁷, P.Yu. Nechaeva⁹⁴, T.J. Neep⁸²,
 A. Negri^{119a,119b}, G. Negri³⁰, M. Negrini^{20a},
 S. Nektarijevic⁴⁹, A. Nelson¹⁶³, T.K. Nelson¹⁴³,
 S. Nemecek¹²⁵, P. Nemethy¹⁰⁸, A.A. Nepomuceno^{24a},
 M. Nessi^{30,y}, M.S. Neubauer¹⁶⁵, M. Neumann¹⁷⁵,
 A. Neusiedl⁸¹, R.M. Neves¹⁰⁸, P. Nevski²⁵,
 F.M. Newcomer¹²⁰, P.R. Newman¹⁸,
 V. Nguyen Thi Hong¹³⁶, R.B. Nickerson¹¹⁸,
 R. Nicolaidou¹³⁶, B. Niquevert³⁰, F. Niedercorn¹¹⁵,
 J. Nielsen¹³⁷, N. Nikiforou³⁵, A. Nikiforov¹⁶,
 V. Nikolaenko¹²⁸, I. Nikolic-Audit⁷⁸, K. Nikolics⁴⁹,
 K. Nikolopoulos¹⁸, H. Nilsen⁴⁸, P. Nilsson⁸,
 Y. Ninomiya¹⁵⁵, A. Nisati^{132a}, R. Nisius⁹⁹, T. Nobe¹⁵⁷,
 L. Nodulman⁶, M. Nomachi¹¹⁶, I. Nomidis¹⁵⁴,
 S. Norberg¹¹¹, M. Nordberg³⁰, P.R. Norton¹²⁹,
 J. Novakova¹²⁶, M. Nozaki⁶⁵, L. Nozka¹¹³,
 I.M. Nugent^{159a}, A.-E. Nuncio-Quiroz²¹,
 G. Nunes Hanninger⁸⁶, T. Nunnemann⁹⁸, E. Nurse⁷⁷,
 B.J. O'Brien⁴⁶, D.C. O'Neil¹⁴², V. O'Shea⁵³,
 L.B. Oakes⁹⁸, F.G. Oakham^{29,d}, H. Oberlack⁹⁹,
 J. Ocariz⁷⁸, A. Ochi⁶⁶, S. Oda⁶⁹, S. Odaka⁶⁵, J. Odier⁸³,
 H. Ogren⁶⁰, A. Oh⁸², S.H. Oh⁴⁵, C.C. Ohm³⁰,
 T. Ohshima¹⁰¹, W. Okamura¹¹⁶, H. Okawa²⁵,
 Y. Okumura³¹, T. Okuyama¹⁵⁵, A. Olariu^{26a},
 A.G. Olchevski⁶⁴, S.A. Olivares Pino^{32a},
 M. Oliveira^{124a,g}, D. Oliveira Damazio²⁵,
 E. Oliver Garcia¹⁶⁷, D. Olivito¹²⁰, A. Olszewski³⁹,
 J. Olszowska³⁹, A. Onofre^{124a,z}, P.U.E. Onyisi³¹,
 C.J. Oram^{159a}, M.J. Oreglia³¹, Y. Oren¹⁵³,
 D. Orestano^{134a,134b}, N. Orlando^{72a,72b}, I. Orlov¹⁰⁷,
 C. Oropeza Barrera⁵³, R.S. Orr¹⁵⁸, B. Osculati^{50a,50b},
 R. Ospanov¹²⁰, C. Osuna¹², G. Otero y Garzon²⁷,
 J.P. Ottersbach¹⁰⁵, M. Ouchrif^{135d}, E.A. Ouellette¹⁶⁹,
 F. Ould-Saada¹¹⁷, A. Ouraou¹³⁶, Q. Ouyang^{33a},
 A. Ovcharova¹⁵, M. Owen⁸², S. Owen¹³⁹, V.E. Ozcan^{19a},
 N. Ozturk⁸, A. Pacheco Pages¹², C. Padilla Aranda¹²,
 S. Pagan Griso¹⁵, E. Paganis¹³⁹, C. Pahl⁹⁹, F. Paige²⁵,
 P. Pais⁸⁴, K. Pajchel¹¹⁷, G. Palacino^{159b}, C.P. Paleari⁷,
 S. Palestini³⁰, D. Pallin³⁴, A. Palma^{124a}, J.D. Palmer¹⁸,
 Y.B. Pan¹⁷³, E. Panagiotopoulou¹⁰,
 J.G. Panduro Vazquez⁷⁶, P. Pani¹⁰⁵, N. Panikashvili⁸⁷,
 S. Panitkin²⁵, D. Pantea^{26a}, A. Papadelis^{146a},
 Th.D. Papadopoulos¹⁰, A. Paramonov⁶,
 D. Paredes Hernandez³⁴, W. Park^{25,aa}, M.A. Parker²⁸,
 F. Parodi^{50a,50b}, J.A. Parsons³⁵, U. Parzefall⁴⁸,
 S. Pashapour⁵⁴, E. Pasqualucci^{132a}, S. Passaggio^{50a},
 A. Passeri^{134a}, F. Pastore^{134a,134b,*}, Fr. Pastore⁷⁶,
 G. Pásztor^{49,ab}, S. Pataraiia¹⁷⁵, N. Patel¹⁵⁰, J.R. Pater⁸²,
 S. Patricelli^{102a,102b}, T. Pauly³⁰, M. Pecsya^{144a},
 S. Pedraza Lopez¹⁶⁷, M.I. Pedraza Morales¹⁷³,
 S.V. Peleganchuk¹⁰⁷, D. Pelikan¹⁶⁶, H. Peng^{33b},
 B. Penning³¹, A. Penson³⁵, J. Penwell⁶⁰,
 M. Perantoni^{24a}, K. Perez^{35,ac}, T. Perez Cavalcanti⁴²,
 E. Perez Codina^{159a}, M.T. Pérez García-Estañ¹⁶⁷,
 V. Perez Reale³⁵, L. Perini^{89a,89b}, H. Pernegger³⁰,
 R. Perrino^{72a}, P. Perrodo⁵, V.D. Peshekhonov⁶⁴,
 K. Peters³⁰, B.A. Petersen³⁰, J. Petersen³⁰,
 T.C. Petersen³⁶, E. Petit⁵, A. Petridis¹⁵⁴, C. Petridou¹⁵⁴,
 E. Petrolo^{132a}, F. Petrucci^{134a,134b}, D. Petschull⁴²,
 M. Petteni¹⁴², R. Pezoa^{32b}, A. Phan⁸⁶, P.W. Phillips¹²⁹,
 G. Piacquadio³⁰, A. Picazio⁴⁹, E. Piccaro⁷⁵,
 M. Piccinini^{20a,20b}, S.M. Piec⁴², R. Piegai²⁷,
 D.T. Pignotti¹⁰⁹, J.E. Pilcher³¹, A.D. Pilkington⁸²,
 J. Pina^{124a,b}, M. Pinamonti^{164a,164c}, A. Pinder¹¹⁸,
 J.L. Pinfeld³, B. Pinto^{124a}, C. Pizio^{89a,89b},
 M. Plamondon¹⁶⁹, M.-A. Pleier²⁵, E. Plotnikova⁶⁴,
 A. Poblaguev²⁵, S. Poddar^{58a}, F. Podlyski³⁴,
 L. Poggioli¹¹⁵, D. Pohl²¹, M. Pohl⁴⁹, G. Polesello^{119a},
 A. Policicchio^{37a,37b}, A. Polini^{20a}, J. Poll⁷⁵,
 V. Polychronakos²⁵, D. Pomeroy²³, K. Pommès³⁰,
 L. Pontecorvo^{132a}, B.G. Pope⁸⁸, G.A. Popeneciu^{26a},
 D.S. Popovic^{13a}, A. Poppleton³⁰, X. Portell Bueso³⁰,
 G.E. Pospelov⁹⁹, S. Pospisil¹²⁷, I.N. Potrap⁹⁹,
 C.J. Potter¹⁴⁹, C.T. Potter¹¹⁴, G. Poulard³⁰,
 J. Poveda⁶⁰, V. Pozdnyakov⁶⁴, R. Prabhu⁷⁷,
 P. Pralavorio⁸³, A. Pranko¹⁵, S. Prasad³⁰,
 R. Pravahan²⁵, S. Prell⁶³, K. Pretzl¹⁷, D. Price⁶⁰,
 J. Price⁷³, L.E. Price⁶, D. Prieur¹²³, M. Primavera^{72a},
 K. Prokofiev¹⁰⁸, F. Prokoshin^{32b}, S. Protopopescu²⁵,
 J. Proudfoot⁶, X. Prudent⁴⁴, M. Przybycien³⁸,
 H. Przysiezniak⁵, S. Psoroulas²¹, E. Ptacek¹¹⁴,
 E. Pueschel⁸⁴, J. Purdham⁸⁷, M. Purohit^{25,aa},
 P. Puzo¹¹⁵, Y. Pylypchenko⁶², J. Qian⁸⁷, A. Quadt⁵⁴,
 D.R. Quarrie¹⁵, W.B. Quayle¹⁷³, F. Quinonez^{32a},
 M. Raas¹⁰⁴, V. Radeka²⁵, V. Radescu⁴², P. Radloff¹¹⁴,
 T. Rador^{19a}, F. Ragusa^{89a,89b}, G. Rahal¹⁷⁸,
 A.M. Rahimi¹⁰⁹, D. Rahm²⁵, S. Rajagopalan²⁵,
 M. Rammensee⁴⁸, M. Rammes¹⁴¹, A.S. Randle-Conde⁴⁰,
 K. Randrianarivony²⁹, F. Rauscher⁹⁸, T.C. Rave⁴⁸,
 M. Raymond³⁰, A.L. Read¹¹⁷, D.M. Rebutti^{119a,119b},
 A. Redelbach¹⁷⁴, G. Redlinger²⁵, R. Reece¹²⁰,
 K. Reeves⁴¹, E. Reinherz-Aronis¹⁵³, A. Reinsch¹¹⁴,
 I. Reisinger⁴³, C. Rembser³⁰, Z.L. Ren¹⁵¹, A. Renaud¹¹⁵,
 M. Rescigno^{132a}, S. Resconi^{89a}, B. Resende¹³⁶,
 P. Reznicek⁹⁸, R. Rezvani¹⁵⁸, R. Richter⁹⁹,
 E. Richter-Was^{5,ad}, M. Ridel⁷⁸, M. Rijpstra¹⁰⁵,
 M. Rijssenbeek¹⁴⁸, A. Rimoldi^{119a,119b}, L. Rinaldi^{20a},
 R.R. Rios⁴⁰, I. Riu¹², G. Rivoltella^{89a,89b},
 F. Rizatdinova¹¹², E. Rizvi⁷⁵, S.H. Robertson^{85,j},
 A. Robichaud-Veronneau¹¹⁸, D. Robinson²⁸,
 J.E.M. Robinson⁸², A. Robson⁵³, J.G. Rocha de Lima¹⁰⁶,
 C. Roda^{122a,122b}, D. Roda Dos Santos³⁰, A. Roe⁵⁴,
 S. Roe³⁰, O. Røhne¹¹⁷, S. Rolli¹⁶¹, A. Romaniouk⁹⁶,
 M. Romano^{20a,20b}, G. Romeo²⁷, E. Romero Adam¹⁶⁷,
 N. Rompotis¹³⁸, L. Roos⁷⁸, E. Ros¹⁶⁷, S. Rosati^{132a},
 K. Rosbach⁴⁹, A. Rose¹⁴⁹, M. Rose⁷⁶,
 G.A. Rosenbaum¹⁵⁸, E.I. Rosenberg⁶³, P.L. Rosendahl¹⁴,
 O. Rosenthal¹⁴¹, L. Rosselet⁴⁹, V. Rossetti¹²,
 E. Rossi^{132a,132b}, L.P. Rossi^{50a}, M. Rotaru^{26a}, I. Roth¹⁷²,

J. Rothberg¹³⁸, D. Rousseau¹¹⁵, C.R. Royon¹³⁶,
A. Rozanov⁸³, Y. Rozen¹⁵², X. Ruan^{33a,ae}, F. Rubbo¹²,
I. Rubinskiy⁴², N. Ruckstuhl¹⁰⁵, V.I. Rud⁹⁷,
C. Rudolph⁴⁴, G. Rudolph⁶¹, F. Rühr⁷,
A. Ruiz-Martinez⁶³, L. Rumyantsev⁶⁴, Z. Rurikova⁴⁸,
N.A. Rusakovich⁶⁴, A. Ruschke⁹⁸, J.P. Rutherford⁷,
P. Ruzicka¹²⁵, Y.F. Ryabov¹²¹, M. Rybar¹²⁶,
G. Rybkin¹¹⁵, N.C. Ryder¹¹⁸, A.F. Saavedra¹⁵⁰,
I. Sadeh¹⁵³, H.F.-W. Sadrozinski¹³⁷, R. Sadykov⁶⁴,
F. Safai Tehrani^{132a}, H. Sakamoto¹⁵⁵, G. Salamanna⁷⁵,
A. Salamon^{133a}, M. Saleem¹¹¹, D. Salek³⁰, D. Salihagic⁹⁹,
A. Salmikov¹⁴³, J. Salt¹⁶⁷, B.M. Salvachua Ferrando⁶,
D. Salvatore^{37a,37b}, F. Salvatore¹⁴⁹, A. Salvucci¹⁰⁴,
A. Salzburger³⁰, D. Sampsonidis¹⁵⁴, B.H. Samset¹¹⁷,
A. Sanchez^{102a,102b}, V. Sanchez Martinez¹⁶⁷,
H. Sandaker¹⁴, H.G. Sander⁸¹, M.P. Sanders⁹⁸,
M. Sandhoff¹⁷⁵, T. Sandoval²⁸, C. Sandoval¹⁶²,
R. Sandstroem⁹⁹, D.P.C. Sankey¹²⁹, A. Sansoni⁴⁷,
C. Santamarina Rios⁸⁵, C. Santoni³⁴,
R. Santonico^{133a,133b}, H. Santos^{124a}, J.G. Saraiva^{124a},
T. Sarangi¹⁷³, E. Sarkisyan-Grinbaum⁸, F. Sarri^{122a,122b},
G. Sartisohn¹⁷⁵, O. Sasaki⁶⁵, Y. Sasaki¹⁵⁵, N. Sasao⁶⁷,
I. Satsounkevitch⁹⁰, G. Sauvage^{5,*}, E. Sauvan⁵,
J.B. Sauvan¹¹⁵, P. Savard^{158,d}, V. Savinov¹²³,
D.O. Savu³⁰, L. Sawyer^{25,l}, D.H. Saxon⁵³, J. Saxon¹²⁰,
C. Sbarra^{20a}, A. Sbrizzi^{20a,20b}, D.A. Scannicchio¹⁶³,
M. Scarcella¹⁵⁰, J. Schaarschmidt¹¹⁵, P. Schacht⁹⁹,
D. Schaefer¹²⁰, U. Schäfer⁸¹, A. Schaelicke⁴⁶,
S. Schaepe²¹, S. Schaezel^{58b}, A.C. Schaffer¹¹⁵,
D. Schaile⁹⁸, R.D. Schamberger¹⁴⁸, A.G. Schamov¹⁰⁷,
V. Scharf^{58a}, V.A. Schegelsky¹²¹, D. Scheirich⁸⁷,
M. Schernau¹⁶³, M.I. Scherzer³⁵, C. Schiavi^{50a,50b},
J. Schieck⁹⁸, M. Schioppa^{37a,37b}, S. Schlenker³⁰,
E. Schmidt⁴⁸, K. Schmieden²¹, C. Schmitt⁸¹,
S. Schmitt^{58b}, M. Schmitz²¹, B. Schneider¹⁷,
U. Schnoor⁴⁴, L. Schoeffel¹³⁶, A. Schoening^{58b},
A.L.S. Schorlemmer⁵⁴, M. Schott³⁰, D. Schouten^{159a},
J. Schovancova¹²⁵, M. Schram⁸⁵, C. Schroeder⁸¹,
N. Schroer^{58c}, M.J. Schultens²¹, J. Schultes¹⁷⁵,
H.-C. Schultz-Coulon^{58a}, H. Schulz¹⁶, M. Schumacher⁴⁸,
B.A. Schumm¹³⁷, Ph. Schune¹³⁶, C. Schwanenberger⁸²,
A. Schwartzman¹⁴³, Ph. Schwegler⁹⁹, Ph. Schwemling⁷⁸,
R. Schwienhorst⁸⁸, R. Schwierz⁴⁴, J. Schwindling¹³⁶,
T. Schwindt²¹, M. Schwoerer⁵, G. Sciolla²³,
W.G. Scott¹²⁹, J. Searcy¹¹⁴, G. Sedov⁴², E. Sedykh¹²¹,
S.C. Seidel¹⁰³, A. Seiden¹³⁷, F. Seifert⁴⁴, J.M. Seixas^{24a},
G. Sekhniaidze^{102a}, S.J. Sekula⁴⁰, K.E. Selbach⁴⁶,
D.M. Seliverstov¹²¹, B. Sellden^{146a}, G. Sellers⁷³,
M. Seman^{144b}, N. Semprini-Cesari^{20a,20b}, C. Serfon⁹⁸,
L. Serin¹¹⁵, L. Serkin⁵⁴, R. Seuster^{159a}, H. Severini¹¹¹,
A. Sfyrta³⁰, E. Shabalina⁵⁴, M. Shamim¹¹⁴, L.Y. Shan^{33a},
J.T. Shank²², Q.T. Shao⁸⁶, M. Shapiro¹⁵,
P.B. Shatalov⁹⁵, K. Shaw^{164a,164c}, D. Sherman¹⁷⁶,
P. Sherwood⁷⁷, S. Shimizu¹⁰¹, M. Shimojima¹⁰⁰,
T. Shin⁵⁶, M. Shiyakova⁶⁴, A. Shmeleva⁹⁴,
M.J. Shochet³¹, D. Short¹¹⁸, S. Shrestha⁶³, E. Shulga⁹⁶,
M.A. Shupe⁷, P. Sicho¹²⁵, A. Sidoti^{132a}, F. Siegert⁴⁸,
Dj. Sijacki^{13a}, O. Silbert¹⁷², J. Silva^{124a}, Y. Silver¹⁵³,
D. Silverstein¹⁴³, S.B. Silverstein^{146a}, V. Simak¹²⁷,
O. Simard¹³⁶, Lj. Simic^{13a}, S. Simion¹¹⁵, E. Simioni⁸¹,
B. Simmons⁷⁷, R. Simoniello^{89a,89b}, M. Simonyan³⁶,
P. Sinervo¹⁵⁸, N.B. Sinev¹¹⁴, V. Sipica¹⁴¹, G. Siragusa¹⁷⁴,
A. Sircar²⁵, A.N. Sisakyan^{64,*}, S.Yu. Sivoklov⁹⁷,
J. Sjölin^{146a,146b}, T.B. Sjursen¹⁴, L.A. Skinnari¹⁵,
H.P. Skottowe⁵⁷, K. Skovpen¹⁰⁷, P. Skubic¹¹¹,
M. Slater¹⁸, T. Slavicek¹²⁷, K. Sliwa¹⁶¹, V. Smakhtin¹⁷²,
B.H. Smart⁴⁶, L. Smestad¹¹⁷, S.Yu. Smirnov⁹⁶,
Y. Smirnov⁹⁶, L.N. Smirnova⁹⁷, O. Smirnova⁷⁹,
B.C. Smith⁵⁷, D. Smith¹⁴³, K.M. Smith⁵³,
M. Smizanska⁷¹, K. Smolek¹²⁷, A.A. Snesarev⁹⁴,
S.W. Snow⁸², J. Snow¹¹¹, S. Snyder²⁵, R. Sobie^{169,j},
J. Sodomka¹²⁷, A. Soffer¹⁵³, C.A. Solans¹⁶⁷, M. Solar¹²⁷,
J. Solc¹²⁷, E.Yu. Soldatov⁹⁶, U. Soldevila¹⁶⁷,
E. Solfaroli Camillocci^{132a,132b}, A.A. Solodkov¹²⁸,
O.V. Solovyanov¹²⁸, V. Solovyev¹²¹, N. Soni¹,
V. Sopko¹²⁷, B. Sopko¹²⁷, M. Sosebee⁸,
R. Soualah^{164a,164c}, A. Soukharev¹⁰⁷, S. Spagnolo^{72a,72b},
F. Spanò⁷⁶, R. Spighi^{20a}, G. Spigo³⁰, R. Spiwoks³⁰,
M. Spousta^{126,af}, T. Spreitzer¹⁵⁸, B. Spurlock⁸,
R.D. St. Denis⁵³, J. Stahlman¹²⁰, R. Stamen^{58a},
E. Stanecka³⁹, R.W. Stanek⁶, C. Stanescu^{134a},
M. Stanescu-Bellu⁴², M.M. Stanitzki⁴², S. Stapnes¹¹⁷,
E.A. Starchenko¹²⁸, J. Stark⁵⁵, P. Staroba¹²⁵,
P. Starovoitov⁴², R. Staszewski³⁹, A. Staude⁹⁸,
P. Stavina^{144a,*}, G. Steele⁵³, P. Steinbach⁴⁴,
P. Steinberg²⁵, I. Stekl¹²⁷, B. Stelzer¹⁴², H.J. Stelzer⁸⁸,
O. Stelzer-Chilton^{159a}, H. Stenzel⁵², S. Stern⁹⁹,
G.A. Stewart³⁰, J.A. Stillings²¹, M.C. Stockton⁸⁵,
K. Stoerig⁴⁸, G. Stoicea^{26a}, S. Stonjek⁹⁹, P. Strachota¹²⁶,
A.R. Stradling⁸, A. Straessner⁴⁴, J. Strandberg¹⁴⁷,
S. Strandberg^{146a,146b}, A. Strandlie¹¹⁷, M. Strang¹⁰⁹,
E. Strauss¹⁴³, M. Strauss¹¹¹, P. Strizeneč^{144b},
R. Ströhmer¹⁷⁴, D.M. Strom¹¹⁴, J.A. Strong^{76,*},
R. Stroynowski⁴⁰, B. Stugu¹⁴, I. Stumer^{25,*},
J. Stupak¹⁴⁸, P. Sturm¹⁷⁵, N.A. Styles⁴², D.A. Soh^{151,t},
D. Su¹⁴³, H.S. Subramania³, R. Subramaniam²⁵,
A. Succurro¹², Y. Sugaya¹¹⁶, C. Suhr¹⁰⁶, M. Suk¹²⁶,
V.V. Sulin⁹⁴, S. Sultansoy^{4d}, T. Sumida⁶⁷, X. Sun⁵⁵,
J.E. Sundermann⁴⁸, K. Suruliz¹³⁹, G. Susinno^{37a,37b},
M.R. Sutton¹⁴⁹, Y. Suzuki⁶⁵, Y. Suzuki⁶⁶, M. Svatos¹²⁵,
S. Swedish¹⁶⁸, I. Sykora^{144a}, T. Sykora¹²⁶, J. Sánchez¹⁶⁷,
D. Ta¹⁰⁵, K. Tackmann⁴², A. Taffard¹⁶³, R. Tafirout^{159a},
N. Taiblum¹⁵³, Y. Takahashi¹⁰¹, H. Takai²⁵,
R. Takashima⁶⁸, H. Takeda⁶⁶, T. Takeshita¹⁴⁰,
Y. Takubo⁶⁵, M. Talby⁸³, A. Talyshev^{107,f},
M.C. Tamsett²⁵, K.G. Tan⁸⁶, J. Tanaka¹⁵⁵, R. Tanaka¹¹⁵,
S. Tanaka¹³¹, S. Tanaka⁶⁵, A.J. Tanasijczuk¹⁴²,
K. Tani⁶⁶, N. Tannoury⁸³, S. Tapprogge⁸¹, D. Tardif¹⁵⁸,
S. Tarem¹⁵², F. Tarrade²⁹, G.F. Tartarelli^{89a}, P. Tas¹²⁶,
M. Tasevsky¹²⁵, E. Tassi^{37a,37b}, M. Tatarkhanov¹⁵,
Y. Tayalati^{135d}, C. Taylor⁷⁷, F.E. Taylor⁹²,
G.N. Taylor⁸⁶, W. Taylor^{159b}, M. Teinturier¹¹⁵,
F.A. Teischinger³⁰, M. Teixeira Dias Castanheira⁷⁵,
P. Teixeira-Dias⁷⁶, K.K. Temming⁴⁸, H. Ten Kate³⁰,

P.K. Teng¹⁵¹, S. Terada⁶⁵, K. Terashi¹⁵⁵, J. Terron⁸⁰, M. Testa⁴⁷, R.J. Teuscher^{158,j}, J. Therhaag²¹, T. Theveneaux-Pelzer⁷⁸, S. Thoma⁴⁸, J.P. Thomas¹⁸, E.N. Thompson³⁵, P.D. Thompson¹⁸, P.D. Thompson¹⁵⁸, A.S. Thompson⁵³, L.A. Thomsen³⁶, E. Thomson¹²⁰, M. Thomson²⁸, W.M. Thong⁸⁶, R.P. Thun⁸⁷, F. Tian³⁵, M.J. Tibbetts¹⁵, T. Tic¹²⁵, V.O. Tikhomirov⁹⁴, Y.A. Tikhonov^{107,f}, S. Timoshenko⁹⁶, E. Tiouchichine⁸³, P. Tipton¹⁷⁶, S. Tisserant⁸³, T. Todorov⁵, S. Todorova-Nova¹⁶¹, B. Toggerson¹⁶³, J. Tojo⁶⁹, S. Tokár^{144a}, K. Tokushuku⁶⁵, K. Tollefson⁸⁸, M. Tomoto¹⁰¹, L. Tompkins³¹, K. Toms¹⁰³, A. Tonoyan¹⁴, C. Topfel¹⁷, N.D. Topilin⁶⁴, I. Torchiani³⁰, E. Torrence¹¹⁴, H. Torres⁷⁸, E. Torró Pastor¹⁶⁷, J. Toth^{83,ab}, F. Touchard⁸³, D.R. Tovey¹³⁹, T. Trefzger¹⁷⁴, L. Tremblet³⁰, A. Tricoli³⁰, I.M. Trigger^{159a}, S. Trincaz-Duvoid⁷⁸, M.F. Tripiana⁷⁰, N. Triplett²⁵, W. Trischuk¹⁵⁸, B. Trocmé⁵⁵, C. Troncon^{89a}, M. Trotter-McDonald¹⁴², P. True⁸⁸, M. Trzebinski³⁹, A. Trzupke³⁹, C. Tsarouchas³⁰, J.C.-L. Tseng¹¹⁸, M. Tsiakiris¹⁰⁵, P.V. Tsiareshka⁹⁰, D. Tsionou^{5,ag}, G. Tsiopolitis¹⁰, S. Tsiskaridze¹², V. Tsiskaridze⁴⁸, E.G. Tskhadadze^{51a}, I.I. Tsukerman⁹⁵, V. Tsulaia¹⁵, J.-W. Tsung²¹, S. Tsuno⁶⁵, D. Tsybychev¹⁴⁸, A. Tua¹³⁹, A. Tudorache^{26a}, V. Tudorache^{26a}, J.M. Tuggle³¹, M. Turala³⁹, D. Turecek¹²⁷, I. Turk Cakir^{4e}, E. Turlay¹⁰⁵, R. Turra^{89a,89b}, P.M. Tuts³⁵, A. Tykhonov⁷⁴, M. Tylmad^{146a,146b}, M. Tyndel¹²⁹, G. Tzanakos⁹, K. Uchida²¹, I. Ueda¹⁵⁵, R. Ueno²⁹, M. Ugland¹⁴, M. Uhlenbrock²¹, M. Uhrmacher⁵⁴, F. Ukegawa¹⁶⁰, G. Unal³⁰, A. Undrus²⁵, G. Unel¹⁶³, Y. Unno⁶⁵, D. Urbaniec³⁵, P. Urquijo²¹, G. Usai⁸, M. Uslenghi^{119a,119b}, L. Vacavant⁸³, V. Vacek¹²⁷, B. Vachon⁸⁵, S. Vahsen¹⁵, J. Valenta¹²⁵, S. Valentinetti^{20a,20b}, A. Valero¹⁶⁷, S. Valkar¹²⁶, E. Valladolid Gallego¹⁶⁷, S. Vallecorsa¹⁵², J.A. Valls Ferrer¹⁶⁷, R. Van Berg¹²⁰, P.C. Van Der Deijl¹⁰⁵, R. van der Geer¹⁰⁵, H. van der Graaf¹⁰⁵, R. Van Der Leeuw¹⁰⁵, E. van der Poel¹⁰⁵, D. van der Ster³⁰, N. van Eldik³⁰, P. van Gemmeren⁶, I. van Vulpen¹⁰⁵, M. Vanadia⁹⁹, W. Vandelli³⁰, A. Vaniachine⁶, P. Vankov⁴², F. Vannucci⁷⁸, R. Vari^{132a}, E.W. Varnes⁷, T. Varol⁸⁴, D. Varouchas¹⁵, A. Vartapetian⁸, K.E. Varvell¹⁵⁰, V.I. Vassilakopoulos⁵⁶, F. Vazeille³⁴, T. Vazquez Schroeder⁵⁴, G. Vegni^{89a,89b}, J.J. Veillet¹¹⁵, F. Veloso^{124a}, R. Veness³⁰, S. Veneziano^{132a}, A. Ventura^{72a,72b}, D. Ventura⁸⁴, M. Venturi⁴⁸, N. Venturi¹⁵⁸, V. Vercesi^{119a}, M. Verducci¹³⁸, W. Verkerke¹⁰⁵, J.C. Vermeulen¹⁰⁵, A. Vest⁴⁴, M.C. Vetterli^{142,d}, I. Vichou¹⁶⁵, T. Vickey^{145b,ah}, O.E. Vickey Boeriu^{145b}, G.H.A. Viehhauser¹¹⁸, S. Viel¹⁶⁸, M. Villa^{20a,20b}, M. Villaplana Perez¹⁶⁷, E. Vilucchi⁴⁷, M.G. Vincker²⁹, E. Vinek³⁰, V.B. Vinogradov⁶⁴, M. Virchaux^{136,*}, J. Virzi¹⁵, O. Vitells¹⁷², M. Viti⁴², I. Vivarelli⁴⁸, F. Vives Vaque³, S. Vlachos¹⁰, D. Vladioiu⁹⁸, M. Vlasak¹²⁷, A. Vogel²¹, P. Vokac¹²⁷, G. Volpi⁴⁷, M. Volpi⁸⁶, G. Volpini^{89a}, H. von der Schmitt⁹⁹, H. von Radziewski⁴⁸, E. von Toerne²¹, V. Vorobel¹²⁶, V. Vorwerk¹², M. Vos¹⁶⁷, R. Voss³⁰, T.T. Voss¹⁷⁵, J.H. Vossebeld⁷³, N. Vranjes¹³⁶, M. Vranjes Milosavljevic¹⁰⁵, V. Vrba¹²⁵, M. Vreeswijk¹⁰⁵, T. Vu Anh⁴⁸, R. Vuillermet³⁰, I. Vukotic³¹, W. Wagner¹⁷⁵, P. Wagner¹²⁰, H. Wahlen¹⁷⁵, S. Wahrmund⁴⁴, J. Wakabayashi¹⁰¹, S. Walch⁸⁷, J. Walder⁷¹, R. Walker⁹⁸, W. Walkowiak¹⁴¹, R. Wall¹⁷⁶, P. Waller⁷³, B. Walsh¹⁷⁶, C. Wang⁴⁵, H. Wang¹⁷³, H. Wang^{33b,ai}, J. Wang¹⁵¹, J. Wang⁵⁵, R. Wang¹⁰³, S.M. Wang¹⁵¹, T. Wang²¹, A. Warburton⁸⁵, C.P. Ward²⁸, D.R. Wardrope⁷⁷, M. Warsinsky⁴⁸, A. Washbrook⁴⁶, C. Wasicki⁴², I. Watanabe⁶⁶, P.M. Watkins¹⁸, A.T. Watson¹⁸, I.J. Watson¹⁵⁰, M.F. Watson¹⁸, G. Watts¹³⁸, S. Watts⁸², A.T. Waugh¹⁵⁰, B.M. Waugh⁷⁷, M.S. Weber¹⁷, P. Weber⁵⁴, J.S. Webster³¹, A.R. Weidberg¹¹⁸, P. Weigell⁹⁹, J. Weingarten⁵⁴, C. Weiser⁴⁸, P.S. Wells³⁰, T. Wenaus²⁵, D. Wendland¹⁶, Z. Weng^{151,t}, T. Wengler³⁰, S. Wenig³⁰, N. Wermes²¹, M. Werner⁴⁸, P. Werner³⁰, M. Werth¹⁶³, M. Wessels^{58a}, J. Wetter¹⁶¹, C. Weydert⁵⁵, K. Whalen²⁹, A. White⁸, M.J. White⁸⁶, S. White^{122a,122b}, S.R. Whitehead¹¹⁸, D. Whiteson¹⁶³, D. Whittington⁶⁰, F. Wicek¹¹⁵, D. Wicke¹⁷⁵, F.J. Wickens¹²⁹, W. Wiedenmann¹⁷³, M. Wielers¹²⁹, P. Wienemann²¹, C. Wiglesworth⁷⁵, L.A.M. Wiik-Fuchs²¹, P.A. Wijeratne⁷⁷, A. Wildauer⁹⁹, M.A. Wildt^{42,q}, I. Wilhelm¹²⁶, H.G. Wilkens³⁰, J.Z. Will⁹⁸, E. Williams³⁵, H.H. Williams¹²⁰, W. Willis³⁵, S. Willocq⁸⁴, J.A. Wilson¹⁸, M.G. Wilson¹⁴³, A. Wilson⁸⁷, I. Wingerter-Seetz⁵, S. Winkelmann⁴⁸, F. Winklmeier³⁰, M. Wittgen¹⁴³, S.J. Wollstadt⁸¹, M.W. Wolter³⁹, H. Wolters^{124a,g}, W.C. Wong⁴¹, G. Wooden⁸⁷, B.K. Wosiek³⁹, J. Wotschack³⁰, M.J. Woudstra⁸², K.W. Wozniak³⁹, K. Wraight⁵³, M. Wright⁵³, B. Wrona⁷³, S.L. Wu¹⁷³, X. Wu⁴⁹, Y. Wu^{33b,aj}, E. Wulf³⁵, B.M. Wynne⁴⁶, S. Xella³⁶, M. Xiao¹³⁶, S. Xie⁴⁸, C. Xu^{33b,x}, D. Xu¹³⁹, B. Yabsley¹⁵⁰, S. Yacoob^{145a,ak}, M. Yamada⁶⁵, H. Yamaguchi¹⁵⁵, A. Yamamoto⁶⁵, K. Yamamoto⁶³, S. Yamamoto¹⁵⁵, T. Yamamura¹⁵⁵, T. Yamanaka¹⁵⁵, T. Yamazaki¹⁵⁵, Y. Yamazaki⁶⁶, Z. Yan²², H. Yang⁸⁷, U.K. Yang⁸², Y. Yang¹⁰⁹, Z. Yang^{146a,146b}, S. Yanush⁹¹, L. Yao^{33a}, Y. Yao¹⁵, Y. Yasu⁶⁵, G.V. Ybeles Smit¹³⁰, J. Ye⁴⁰, S. Ye²⁵, M. Yilmaz^{4c}, R. Yoosoofmiya¹²³, K. Yorita¹⁷¹, R. Yoshida⁶, K. Yoshihara¹⁵⁵, C. Young¹⁴³, C.J. Young¹¹⁸, S. Youssef²², D. Yu²⁵, J. Yu⁸, J. Yu¹¹², L. Yuan⁶⁶, A. Yurkewicz¹⁰⁶, B. Zabinski³⁹, R. Zaidan⁶², A.M. Zaitsev¹²⁸, Z. Zajacova³⁰, L. Zanello^{132a,132b}, D. Zanzi⁹⁹, A. Zaytsev²⁵, C. Zeitnitz¹⁷⁵, M. Zeman¹²⁵, A. Zemla³⁹, C. Zender²¹, O. Zenin¹²⁸, T. Ženis^{144a}, Z. Zinonos^{122a,122b}, S. Zenz¹⁵, D. Zerwas¹¹⁵, G. Zevi della Porta⁵⁷, D. Zhang^{33b,ai}, H. Zhang⁸⁸, J. Zhang⁶, X. Zhang^{33d}, Z. Zhang¹¹⁵, L. Zhao¹⁰⁸, Z. Zhao^{33b}, A. Zhemchugov⁶⁴, J. Zhong¹¹⁸, B. Zhou⁸⁷, N. Zhou¹⁶³, Y. Zhou¹⁵¹, C.G. Zhu^{33d}, H. Zhu⁴², J. Zhu⁸⁷,

Y. Zhu^{33b}, X. Zhuang⁹⁸, V. Zhuravlov⁹⁹, A. Zibell⁹⁸,
D. Zieminska⁶⁰, N.I. Zimin⁶⁴, R. Zimmermann²¹,
S. Zimmermann²¹, S. Zimmermann⁴⁸, M. Ziolkowski¹⁴¹,
R. Zitoun⁵, L. Živković³⁵, V.V. Zmouchko^{128,*},
G. Zobernig¹⁷³, A. Zoccoli^{20a,20b}, M. zur Nedden¹⁶,
V. Zutshi¹⁰⁶, L. Zwalinski³⁰.

¹ School of Chemistry and Physics, University of
Adelaide, Adelaide, Australia

² Physics Department, SUNY Albany, Albany NY,
United States of America

³ Department of Physics, University of Alberta,
Edmonton AB, Canada

⁴ (a) Department of Physics, Ankara University, Ankara;

(b) Department of Physics, Dumlupinar University,
Kutahya; (c) Department of Physics, Gazi University,
Ankara; (d) Division of Physics, TOBB University of
Economics and Technology, Ankara; (e) Turkish Atomic
Energy Authority, Ankara, Turkey

⁵ LAPP, CNRS/IN2P3 and Université de Savoie,
Annecy-le-Vieux, France

⁶ High Energy Physics Division, Argonne National
Laboratory, Argonne IL, United States of America

⁷ Department of Physics, University of Arizona, Tucson
AZ, United States of America

⁸ Department of Physics, The University of Texas at
Arlington, Arlington TX, United States of America

⁹ Physics Department, University of Athens, Athens,
Greece

¹⁰ Physics Department, National Technical University of
Athens, Zografou, Greece

¹¹ Institute of Physics, Azerbaijan Academy of Sciences,
Baku, Azerbaijan

¹² Institut de Física d'Altes Energies and Departament
de Física de la Universitat Autònoma de Barcelona and
ICREA, Barcelona, Spain

¹³ (a) Institute of Physics, University of Belgrade,
Belgrade; (b) Vinca Institute of Nuclear Sciences,
University of Belgrade, Belgrade, Serbia

¹⁴ Department for Physics and Technology, University of
Bergen, Bergen, Norway

¹⁵ Physics Division, Lawrence Berkeley National
Laboratory and University of California, Berkeley CA,
United States of America

¹⁶ Department of Physics, Humboldt University, Berlin,
Germany

¹⁷ Albert Einstein Center for Fundamental Physics and
Laboratory for High Energy Physics, University of Bern,
Bern, Switzerland

¹⁸ School of Physics and Astronomy, University of
Birmingham, Birmingham, United Kingdom

¹⁹ (a) Department of Physics, Bogazici University,
Istanbul; (b) Division of Physics, Dogus University,
Istanbul; (c) Department of Physics Engineering,
Gaziantep University, Gaziantep; (d) Department of
Physics, Istanbul Technical University, Istanbul, Turkey

²⁰ (a) INFN Sezione di Bologna; (b) Dipartimento di

Fisica, Università di Bologna, Bologna, Italy

²¹ Physikalisches Institut, University of Bonn, Bonn,
Germany

²² Department of Physics, Boston University, Boston
MA, United States of America

²³ Department of Physics, Brandeis University, Waltham
MA, United States of America

²⁴ (a) Universidade Federal do Rio De Janeiro

COPPE/EE/IF, Rio de Janeiro; (b) Federal University of
Juiz de Fora (UFJF), Juiz de Fora; (c) Federal University
of Sao Joao del Rei (UFSJ), Sao Joao del Rei; (d)
Instituto de Fisica, Universidade de Sao Paulo, Sao
Paulo, Brazil

²⁵ Physics Department, Brookhaven National
Laboratory, Upton NY, United States of America

²⁶ (a) National Institute of Physics and Nuclear
Engineering, Bucharest; (b) University Politehnica
Bucharest, Bucharest; (c) West University in Timisoara,
Timisoara, Romania

²⁷ Departamento de Física, Universidad de Buenos Aires,
Buenos Aires, Argentina

²⁸ Cavendish Laboratory, University of Cambridge,
Cambridge, United Kingdom

²⁹ Department of Physics, Carleton University, Ottawa
ON, Canada

³⁰ CERN, Geneva, Switzerland

³¹ Enrico Fermi Institute, University of Chicago, Chicago
IL, United States of America

³² (a) Departamento de Física, Pontificia Universidad
Católica de Chile, Santiago; (b) Departamento de Física,
Universidad Técnica Federico Santa María, Valparaíso,
Chile

³³ (a) Institute of High Energy Physics, Chinese Academy
of Sciences, Beijing; (b) Department of Modern Physics,
University of Science and Technology of China, Anhui; (c)
Department of Physics, Nanjing University, Jiangsu; (d)
School of Physics, Shandong University, Shandong, China

³⁴ Laboratoire de Physique Corpusculaire, Clermont
Université and Université Blaise Pascal and
CNRS/IN2P3, Clermont-Ferrand, France

³⁵ Nevis Laboratory, Columbia University, Irvington NY,
United States of America

³⁶ Niels Bohr Institute, University of Copenhagen,
Kobenhavn, Denmark

³⁷ (a) INFN Gruppo Collegato di Cosenza; (b)
Dipartimento di Fisica, Università della Calabria,
Arcavata di Rende, Italy

³⁸ AGH University of Science and Technology, Faculty of
Physics and Applied Computer Science, Krakow, Poland

³⁹ The Henryk Niewodniczanski Institute of Nuclear
Physics, Polish Academy of Sciences, Krakow, Poland

⁴⁰ Physics Department, Southern Methodist University,
Dallas TX, United States of America

⁴¹ Physics Department, University of Texas at Dallas,
Richardson TX, United States of America

⁴² DESY, Hamburg and Zeuthen, Germany

⁴³ Institut für Experimentelle Physik IV, Technische

- Universität Dortmund, Dortmund, Germany
- ⁴⁴ Institut für Kern- und Teilchenphysik, Technical University Dresden, Dresden, Germany
- ⁴⁵ Department of Physics, Duke University, Durham NC, United States of America
- ⁴⁶ SUPA - School of Physics and Astronomy, University of Edinburgh, Edinburgh, United Kingdom
- ⁴⁷ INFN Laboratori Nazionali di Frascati, Frascati, Italy
- ⁴⁸ Fakultät für Mathematik und Physik, Albert-Ludwigs-Universität, Freiburg, Germany
- ⁴⁹ Section de Physique, Université de Genève, Geneva, Switzerland
- ⁵⁰ ^(a) INFN Sezione di Genova; ^(b) Dipartimento di Fisica, Università di Genova, Genova, Italy
- ⁵¹ ^(a) E. Andronikashvili Institute of Physics, Iv. Javakishvili Tbilisi State University, Tbilisi; ^(b) High Energy Physics Institute, Tbilisi State University, Tbilisi, Georgia
- ⁵² II Physikalisches Institut, Justus-Liebig-Universität Giessen, Giessen, Germany
- ⁵³ SUPA - School of Physics and Astronomy, University of Glasgow, Glasgow, United Kingdom
- ⁵⁴ II Physikalisches Institut, Georg-August-Universität, Göttingen, Germany
- ⁵⁵ Laboratoire de Physique Subatomique et de Cosmologie, Université Joseph Fourier and CNRS/IN2P3 and Institut National Polytechnique de Grenoble, Grenoble, France
- ⁵⁶ Department of Physics, Hampton University, Hampton VA, United States of America
- ⁵⁷ Laboratory for Particle Physics and Cosmology, Harvard University, Cambridge MA, United States of America
- ⁵⁸ ^(a) Kirchhoff-Institut für Physik, Ruprecht-Karls-Universität Heidelberg, Heidelberg; ^(b) Physikalisches Institut, Ruprecht-Karls-Universität Heidelberg, Heidelberg; ^(c) ZITI Institut für technische Informatik, Ruprecht-Karls-Universität Heidelberg, Mannheim, Germany
- ⁵⁹ Faculty of Applied Information Science, Hiroshima Institute of Technology, Hiroshima, Japan
- ⁶⁰ Department of Physics, Indiana University, Bloomington IN, United States of America
- ⁶¹ Institut für Astro- und Teilchenphysik, Leopold-Franzens-Universität, Innsbruck, Austria
- ⁶² University of Iowa, Iowa City IA, United States of America
- ⁶³ Department of Physics and Astronomy, Iowa State University, Ames IA, United States of America
- ⁶⁴ Joint Institute for Nuclear Research, JINR Dubna, Dubna, Russia
- ⁶⁵ KEK, High Energy Accelerator Research Organization, Tsukuba, Japan
- ⁶⁶ Graduate School of Science, Kobe University, Kobe, Japan
- ⁶⁷ Faculty of Science, Kyoto University, Kyoto, Japan
- ⁶⁸ Kyoto University of Education, Kyoto, Japan
- ⁶⁹ Department of Physics, Kyushu University, Fukuoka, Japan
- ⁷⁰ Instituto de Física La Plata, Universidad Nacional de La Plata and CONICET, La Plata, Argentina
- ⁷¹ Physics Department, Lancaster University, Lancaster, United Kingdom
- ⁷² ^(a) INFN Sezione di Lecce; ^(b) Dipartimento di Matematica e Fisica, Università del Salento, Lecce, Italy
- ⁷³ Oliver Lodge Laboratory, University of Liverpool, Liverpool, United Kingdom
- ⁷⁴ Department of Physics, Jožef Stefan Institute and University of Ljubljana, Ljubljana, Slovenia
- ⁷⁵ School of Physics and Astronomy, Queen Mary University of London, London, United Kingdom
- ⁷⁶ Department of Physics, Royal Holloway University of London, Surrey, United Kingdom
- ⁷⁷ Department of Physics and Astronomy, University College London, London, United Kingdom
- ⁷⁸ Laboratoire de Physique Nucléaire et de Hautes Energies, UPMC and Université Paris-Diderot and CNRS/IN2P3, Paris, France
- ⁷⁹ Fysiska institutionen, Lunds universitet, Lund, Sweden
- ⁸⁰ Departamento de Física Teórica C-15, Universidad Autónoma de Madrid, Madrid, Spain
- ⁸¹ Institut für Physik, Universität Mainz, Mainz, Germany
- ⁸² School of Physics and Astronomy, University of Manchester, Manchester, United Kingdom
- ⁸³ CPPM, Aix-Marseille Université and CNRS/IN2P3, Marseille, France
- ⁸⁴ Department of Physics, University of Massachusetts, Amherst MA, United States of America
- ⁸⁵ Department of Physics, McGill University, Montreal QC, Canada
- ⁸⁶ School of Physics, University of Melbourne, Victoria, Australia
- ⁸⁷ Department of Physics, The University of Michigan, Ann Arbor MI, United States of America
- ⁸⁸ Department of Physics and Astronomy, Michigan State University, East Lansing MI, United States of America
- ⁸⁹ ^(a) INFN Sezione di Milano; ^(b) Dipartimento di Fisica, Università di Milano, Milano, Italy
- ⁹⁰ B.I. Stepanov Institute of Physics, National Academy of Sciences of Belarus, Minsk, Republic of Belarus
- ⁹¹ National Scientific and Educational Centre for Particle and High Energy Physics, Minsk, Republic of Belarus
- ⁹² Department of Physics, Massachusetts Institute of Technology, Cambridge MA, United States of America
- ⁹³ Group of Particle Physics, University of Montreal, Montreal QC, Canada
- ⁹⁴ P.N. Lebedev Institute of Physics, Academy of Sciences, Moscow, Russia
- ⁹⁵ Institute for Theoretical and Experimental Physics (ITEP), Moscow, Russia
- ⁹⁶ Moscow Engineering and Physics Institute (MEPhI), Moscow, Russia
- ⁹⁷ Skobeltsyn Institute of Nuclear Physics, Lomonosov

Moscow State University, Moscow, Russia

⁹⁸ Fakultät für Physik, Ludwig-Maximilians-Universität München, München, Germany

⁹⁹ Max-Planck-Institut für Physik (Werner-Heisenberg-Institut), München, Germany

¹⁰⁰ Nagasaki Institute of Applied Science, Nagasaki, Japan

¹⁰¹ Graduate School of Science and Kobayashi-Maskawa Institute, Nagoya University, Nagoya, Japan

¹⁰² (a) INFN Sezione di Napoli; (b) Dipartimento di Scienze Fisiche, Università di Napoli, Napoli, Italy

¹⁰³ Department of Physics and Astronomy, University of New Mexico, Albuquerque NM, United States of America

¹⁰⁴ Institute for Mathematics, Astrophysics and Particle Physics, Radboud University Nijmegen/Nikhef, Nijmegen, Netherlands

¹⁰⁵ Nikhef National Institute for Subatomic Physics and University of Amsterdam, Amsterdam, Netherlands

¹⁰⁶ Department of Physics, Northern Illinois University, DeKalb IL, United States of America

¹⁰⁷ Budker Institute of Nuclear Physics, SB RAS, Novosibirsk, Russia

¹⁰⁸ Department of Physics, New York University, New York NY, United States of America

¹⁰⁹ Ohio State University, Columbus OH, United States of America

¹¹⁰ Faculty of Science, Okayama University, Okayama, Japan

¹¹¹ Homer L. Dodge Department of Physics and Astronomy, University of Oklahoma, Norman OK, United States of America

¹¹² Department of Physics, Oklahoma State University, Stillwater OK, United States of America

¹¹³ Palacký University, RCPTM, Olomouc, Czech Republic

¹¹⁴ Center for High Energy Physics, University of Oregon, Eugene OR, United States of America

¹¹⁵ LAL, Université Paris-Sud and CNRS/IN2P3, Orsay, France

¹¹⁶ Graduate School of Science, Osaka University, Osaka, Japan

¹¹⁷ Department of Physics, University of Oslo, Oslo, Norway

¹¹⁸ Department of Physics, Oxford University, Oxford, United Kingdom

¹¹⁹ (a) INFN Sezione di Pavia; (b) Dipartimento di Fisica, Università di Pavia, Pavia, Italy

¹²⁰ Department of Physics, University of Pennsylvania, Philadelphia PA, United States of America

¹²¹ Petersburg Nuclear Physics Institute, Gatchina, Russia

¹²² (a) INFN Sezione di Pisa; (b) Dipartimento di Fisica E. Fermi, Università di Pisa, Pisa, Italy

¹²³ Department of Physics and Astronomy, University of Pittsburgh, Pittsburgh PA, United States of America

¹²⁴ (a) Laboratório de Instrumentação e Física Experimental de Partículas - LIP, Lisboa, Portugal; (b) Departamento de Física Teórica y del Cosmos and CAFPE, Universidad de Granada, Granada, Spain

¹²⁵ Institute of Physics, Academy of Sciences of the Czech Republic, Praha, Czech Republic

¹²⁶ Faculty of Mathematics and Physics, Charles University in Prague, Praha, Czech Republic

¹²⁷ Czech Technical University in Prague, Praha, Czech Republic

¹²⁸ State Research Center Institute for High Energy Physics, Protvino, Russia

¹²⁹ Particle Physics Department, Rutherford Appleton Laboratory, Didcot, United Kingdom

¹³⁰ Physics Department, University of Regina, Regina SK, Canada

¹³¹ Ritsumeikan University, Kusatsu, Shiga, Japan

¹³² (a) INFN Sezione di Roma I; (b) Dipartimento di Fisica, Università La Sapienza, Roma, Italy

¹³³ (a) INFN Sezione di Roma Tor Vergata; (b) Dipartimento di Fisica, Università di Roma Tor Vergata, Roma, Italy

¹³⁴ (a) INFN Sezione di Roma Tre; (b) Dipartimento di Fisica, Università Roma Tre, Roma, Italy

¹³⁵ (a) Faculté des Sciences Ain Chock, Réseau Universitaire de Physique des Hautes Energies - Université Hassan II, Casablanca; (b) Centre National de l'Energie des Sciences Techniques Nucleaires, Rabat; (c) Faculté des Sciences Semlalia, Université Cadi Ayyad, LPHEA-Marrakech; (d) Faculté des Sciences, Université Mohamed Premier and LPTPM, Oujda; (e) Faculté des sciences, Université Mohammed V-Agdal, Rabat, Morocco

¹³⁶ DSM/IRFU (Institut de Recherches sur les Lois Fondamentales de l'Univers), CEA Saclay (Commissariat a l'Energie Atomique), Gif-sur-Yvette, France

¹³⁷ Santa Cruz Institute for Particle Physics, University of California Santa Cruz, Santa Cruz CA, United States of America

¹³⁸ Department of Physics, University of Washington, Seattle WA, United States of America

¹³⁹ Department of Physics and Astronomy, University of Sheffield, Sheffield, United Kingdom

¹⁴⁰ Department of Physics, Shinshu University, Nagano, Japan

¹⁴¹ Fachbereich Physik, Universität Siegen, Siegen, Germany

¹⁴² Department of Physics, Simon Fraser University, Burnaby BC, Canada

¹⁴³ SLAC National Accelerator Laboratory, Stanford CA, United States of America

¹⁴⁴ (a) Faculty of Mathematics, Physics & Informatics, Comenius University, Bratislava; (b) Department of Subnuclear Physics, Institute of Experimental Physics of the Slovak Academy of Sciences, Kosice, Slovak Republic

¹⁴⁵ (a) Department of Physics, University of Johannesburg, Johannesburg; (b) School of Physics, University of the Witwatersrand, Johannesburg, South Africa

- ¹⁴⁶ (a) Department of Physics, Stockholm University; (b) The Oskar Klein Centre, Stockholm, Sweden
- ¹⁴⁷ Physics Department, Royal Institute of Technology, Stockholm, Sweden
- ¹⁴⁸ Departments of Physics & Astronomy and Chemistry, Stony Brook University, Stony Brook NY, United States of America
- ¹⁴⁹ Department of Physics and Astronomy, University of Sussex, Brighton, United Kingdom
- ¹⁵⁰ School of Physics, University of Sydney, Sydney, Australia
- ¹⁵¹ Institute of Physics, Academia Sinica, Taipei, Taiwan
- ¹⁵² Department of Physics, Technion: Israel Institute of Technology, Haifa, Israel
- ¹⁵³ Raymond and Beverly Sackler School of Physics and Astronomy, Tel Aviv University, Tel Aviv, Israel
- ¹⁵⁴ Department of Physics, Aristotle University of Thessaloniki, Thessaloniki, Greece
- ¹⁵⁵ International Center for Elementary Particle Physics and Department of Physics, The University of Tokyo, Tokyo, Japan
- ¹⁵⁶ Graduate School of Science and Technology, Tokyo Metropolitan University, Tokyo, Japan
- ¹⁵⁷ Department of Physics, Tokyo Institute of Technology, Tokyo, Japan
- ¹⁵⁸ Department of Physics, University of Toronto, Toronto ON, Canada
- ¹⁵⁹ (a) TRIUMF, Vancouver BC; (b) Department of Physics and Astronomy, York University, Toronto ON, Canada
- ¹⁶⁰ Faculty of Pure and Applied Sciences, University of Tsukuba, Tsukuba, Japan
- ¹⁶¹ Department of Physics and Astronomy, Tufts University, Medford MA, United States of America
- ¹⁶² Centro de Investigaciones, Universidad Antonio Narino, Bogota, Colombia
- ¹⁶³ Department of Physics and Astronomy, University of California Irvine, Irvine CA, United States of America
- ¹⁶⁴ (a) INFN Gruppo Collegato di Udine; (b) ICTP, Trieste; (c) Dipartimento di Chimica, Fisica e Ambiente, Università di Udine, Udine, Italy
- ¹⁶⁵ Department of Physics, University of Illinois, Urbana IL, United States of America
- ¹⁶⁶ Department of Physics and Astronomy, University of Uppsala, Uppsala, Sweden
- ¹⁶⁷ Instituto de Física Corpuscular (IFIC) and Departamento de Física Atómica, Molecular y Nuclear and Departamento de Ingeniería Electrónica and Instituto de Microelectrónica de Barcelona (IMB-CNM), University of Valencia and CSIC, Valencia, Spain
- ¹⁶⁸ Department of Physics, University of British Columbia, Vancouver BC, Canada
- ¹⁶⁹ Department of Physics and Astronomy, University of Victoria, Victoria BC, Canada
- ¹⁷⁰ Department of Physics, University of Warwick, Coventry, United Kingdom
- ¹⁷¹ Waseda University, Tokyo, Japan
- ¹⁷² Department of Particle Physics, The Weizmann Institute of Science, Rehovot, Israel
- ¹⁷³ Department of Physics, University of Wisconsin, Madison WI, United States of America
- ¹⁷⁴ Fakultät für Physik und Astronomie, Julius-Maximilians-Universität, Würzburg, Germany
- ¹⁷⁵ Fachbereich C Physik, Bergische Universität Wuppertal, Wuppertal, Germany
- ¹⁷⁶ Department of Physics, Yale University, New Haven CT, United States of America
- ¹⁷⁷ Yerevan Physics Institute, Yerevan, Armenia
- ¹⁷⁸ Centre de Calcul de l'Institut National de Physique Nucléaire et de Physique des Particules (IN2P3), Villeurbanne, France
- ^a Also at Laboratório de Instrumentação e Física Experimental de Partículas - LIP, Lisboa, Portugal
- ^b Also at Faculdade de Ciências and CFNUL, Universidade de Lisboa, Lisboa, Portugal
- ^c Also at Particle Physics Department, Rutherford Appleton Laboratory, Didcot, United Kingdom
- ^d Also at TRIUMF, Vancouver BC, Canada
- ^e Also at Department of Physics, California State University, Fresno CA, United States of America
- ^f Also at Novosibirsk State University, Novosibirsk, Russia
- ^g Also at Department of Physics, University of Coimbra, Coimbra, Portugal
- ^h Also at Department of Physics, UASLP, San Luis Potosi, Mexico
- ⁱ Also at Università di Napoli Parthenope, Napoli, Italy
- ^j Also at Institute of Particle Physics (IPP), Canada
- ^k Also at Department of Physics, Middle East Technical University, Ankara, Turkey
- ^l Also at Louisiana Tech University, Ruston LA, United States of America
- ^m Also at Dep Física and CEFITEC of Faculdade de Ciências e Tecnologia, Universidade Nova de Lisboa, Caparica, Portugal
- ⁿ Also at Department of Physics and Astronomy, University College London, London, United Kingdom
- ^o Also at Department of Physics, University of Cape Town, Cape Town, South Africa
- ^p Also at Institute of Physics, Azerbaijan Academy of Sciences, Baku, Azerbaijan
- ^q Also at Institut für Experimentalphysik, Universität Hamburg, Hamburg, Germany
- ^r Also at Manhattan College, New York NY, United States of America
- ^s Also at CPPM, Aix-Marseille Université and CNRS/IN2P3, Marseille, France
- ^t Also at School of Physics and Engineering, Sun Yat-sen University, Guanzhou, China
- ^u Also at Academia Sinica Grid Computing, Institute of Physics, Academia Sinica, Taipei, Taiwan
- ^v Also at School of Physics, Shandong University, Shandong, China
- ^w Also at Dipartimento di Fisica, Università La

Sapienza, Roma, Italy

^x Also at DSM/IRFU (Institut de Recherches sur les Lois Fondamentales de l'Univers), CEA Saclay (Commissariat a l'Energie Atomique), Gif-sur-Yvette, France

^y Also at Section de Physique, Université de Genève, Geneva, Switzerland

^z Also at Departamento de Fisica, Universidade de Minho, Braga, Portugal

^{aa} Also at Department of Physics and Astronomy, University of South Carolina, Columbia SC, United States of America

^{ab} Also at Institute for Particle and Nuclear Physics, Wigner Research Centre for Physics, Budapest, Hungary

^{ac} Also at California Institute of Technology, Pasadena CA, United States of America

^{ad} Also at Institute of Physics, Jagiellonian University, Krakow, Poland

^{ae} Also at LAL, Université Paris-Sud and CNRS/IN2P3, Orsay, France

^{af} Also at Nevis Laboratory, Columbia University, Irvington NY, United States of America

^{ag} Also at Department of Physics and Astronomy, University of Sheffield, Sheffield, United Kingdom

^{ah} Also at Department of Physics, Oxford University, Oxford, United Kingdom

^{ai} Also at Institute of Physics, Academia Sinica, Taipei, Taiwan

^{aj} Also at Department of Physics, The University of Michigan, Ann Arbor MI, United States of America

^{ak} Also at Discipline of Physics, University of KwaZulu-Natal, Durban, South Africa

* Deceased